

M1/M2 Research Internship – Stage M1/M2 2022-2023 :

Experimental Investigation of a Stochastic Self-Organizing Overlay

1 Supervision

Advisers	François Taiani, <code>francois.taiani@irisa.fr</code> , 02 99 84 75 04 George Giakkoupis, <code>george.giakkoupis@inria.fr</code> Davide Frey, <code>davide.frey@inria.fr</code>
Lab	Centre Inria Rennes, IRISA (UMR 6074)
Team	WIDE (The World Is DistributEd) Équipes-Projet Inria / Département D1 IRISA

2 Context

Self-organizing overlays are a class of epidemic distributed protocols that allow a set of distributed nodes to construct “emergent” topologies in a robust, efficient, and highly scalable manner. Initially proposed 15 years ago [10, 13], they have since been applied to an extensive range of problems, from peer-to-peer recommendation [2, 5, 6, 9, 12], to distributed topology construction [3, 4], and KNN graph computation [7].

Self-organizing overlays (SOOs) assume a distance¹ function $d(-, -)$ on participants (1), and seek to construct for each participant $u \in \Pi$, a neighborhood $N(u)$ (or *view*) of its k closest peers (2).

$$d: \Pi \times \Pi \rightarrow \mathbb{R} \\ (u, v) \quad d(u, v). \quad (1)$$

$$N(u) \in \operatorname{argmin}_{S \subseteq \Pi \setminus \{u\}: |S|=k} \sum_{v \in S} d(u, v), \quad (2)$$

Starting from a random configuration, SOOs usually combine two stochastic processes to achieve this goal, that execute in periodic rounds:

- Relying on a Random Peer Sampling Service (RPS) [11], each node periodically probes some random peers and improve its current view accordingly.
- In parallel, each node periodically requests the view of one of its neighbors, chosen at random, and uses these new participants (these ‘friends-of-friends’) to improve its view.

Experimentally, SOOs have been shown to converge particularly rapidly in many situations, in a number of rounds that is proportional to the logarithm of the size of the system $O(\log(|\Pi|))$ (see for instance Figure 1), but no proof of this result has been proposed yet.

3 Objective

The supervisors and a previous intern, Lucie Guillou, have recently developed a formal analysis of the convergence of an SOO algorithm based on partitions of the search space. The SOO algorithm works in a one-dimensional space of 2^ℓ identifiers and repeatedly partitions this space using limited peer-to-peer exchanges to construct local views of k neighbors. The formal analysis provides a proof that this algorithm converges to top- k neighborhoods with high probability in $\log(n)$ rounds.

This internship aims to perform an in-depth experimental analysis of a generalization of this algorithm to higher dimensions on real and synthetic datasets.

We would first like to consider the procedures described by Dong, Indyk, Razenshteyn, and Wagner in [1] to transform a high-dimensional dataset into a one-dimensional one before applying our decentralized

¹In some niche cases, d might not even be a distance.

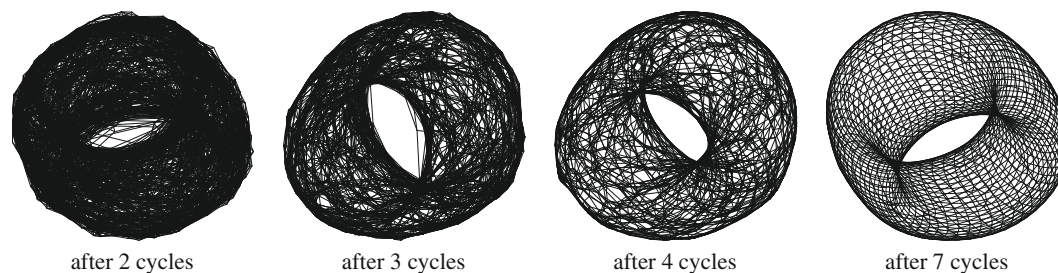


Figure 1: Convergence of a Self-Organizing Overlay with the T-Man algorithm executing on 2500 nodes, taken from [10]

SOO algorithm and measuring key performance metrics. We plan to apply such procedures to the datasets described in [8], and compare the obtained results to that of centralized solutions to approximate k-neighbor search problems.

In a second stage, we plan to perform a sensitivity analysis using synthetic datasets in order to assess to which extent key properties of the datasets (such as the distribution of pair-wise distances against that of the average pair-wise distance) influence the results of our algorithm.

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