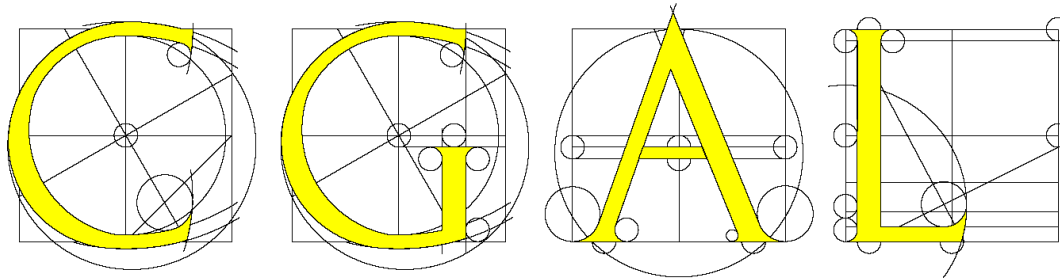


# 2D Triangulations in



Pierre Alliez  
Mariette Yvinec

<http://www.cgal.org>

# Outline

- **Specifications**
  - Definition
  - Triangulations in CGAL
  - Features
- **Representation**
  - As a set of faces
  - Representation based on vertices and cells
- **Software design**
  - Traits class
  - Triangulation data structure
- **Algorithms**
  - Point location
- **Examples**
- **Applications**



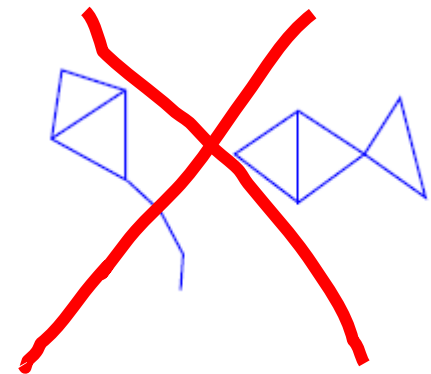
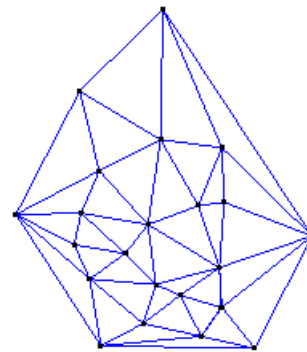
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- **Exercises**



# Definitions

- A **2D triangulation** is a set  $T$  of triangular facets such that:
  - two facets are either disjoint or share a lower dimensional face (edge or vertex).
  - the set of facets in  $T$  is connected for the adjacency relation.
  - the domain  $U_T$  which is the union of facets in  $T$  has no singularity.





# Definitions

- A simplicial complex is a set  $T$  of simplices such that
  - any face of a simplex in  $T$  is a simplex in  $T$
  - two simplices in  $T$  either are disjoint or share a common subface.
- The dimension  $d$  of a simplicial complex is the maximal dimension of its simplices.
- A simplicial complex  $T$  is pure if any simplex of  $T$  is included in a simplex of  $T$  with maximal dimension.



# Definitions

- Two simplexes in  $T$  with maximal dimension  $d$  are said to be adjacent if they share a  $(d-1)$  dimensional subface. A simplicial complex is connected if the adjacency relation defines a connected graph over the set of simplices of  $T$  with maximal dimension.
- The union  $U_T$  of all simplices in  $T$  is called the domain of  $T$ .
- A point  $p$  in the domain of  $T$  is said to be singular if its surrounding in  $U_T$  is neither a topological ball nor a topological disc.



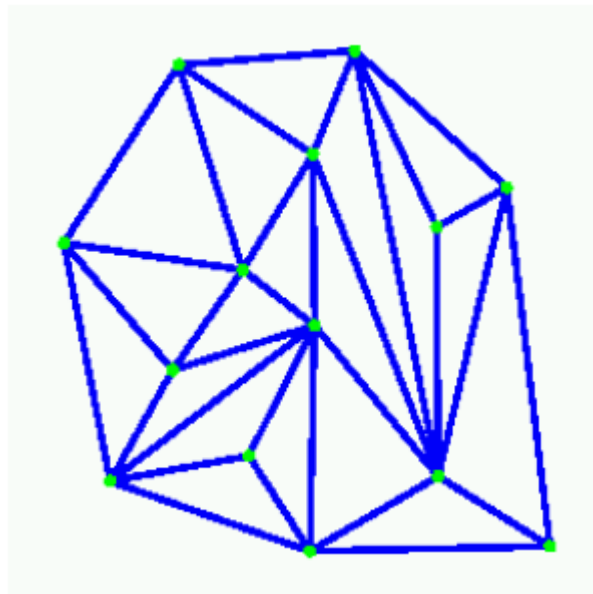
# 2D Triangulations in CGAL

- Basic
- Delaunay
- Regular
- Constrained
- Constrained Delaunay



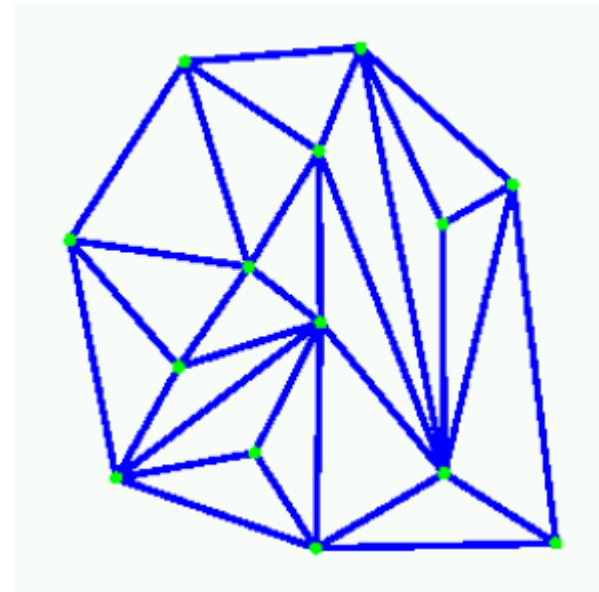
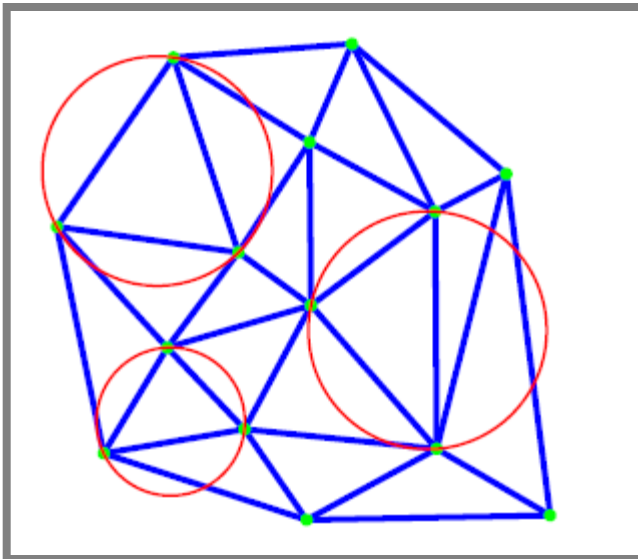
# Basic Triangulation

- Lazy incremental construction, no control over the shape of triangles



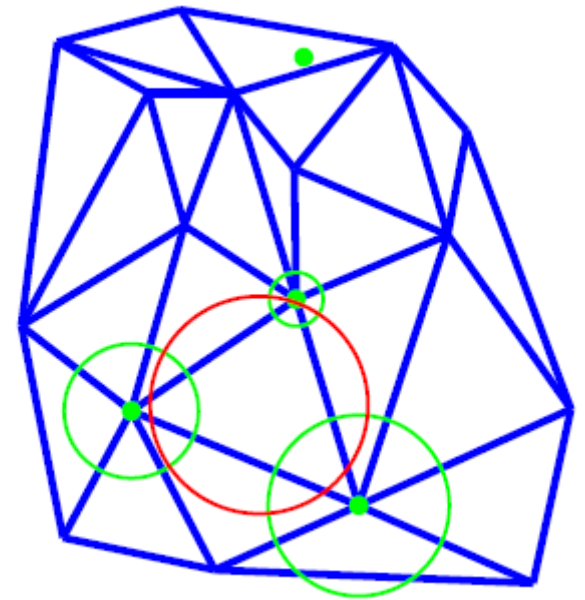
# Delaunay Triangulation

- Empty circle property



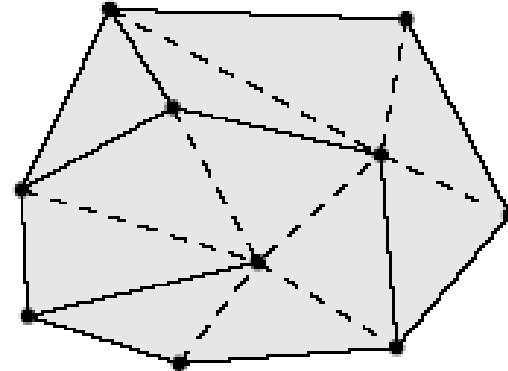
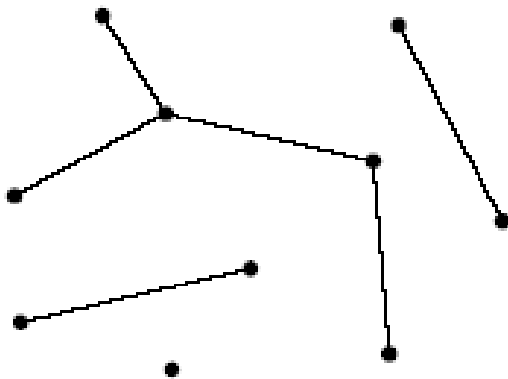
# Regular Triangulation

- **Generalization of Delaunay triangulation.**
- Defined for a set of **weighted points**. Each weighted point can be considered as a sphere whose square radius is equal to the weight. The regular triangulation is the dual of the power diagram.



# Constrained Triangulation

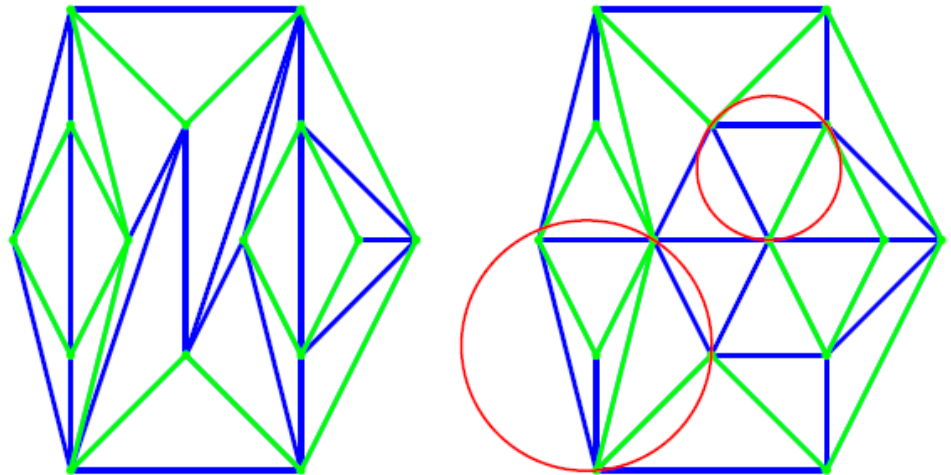
- Allows to enforce edges.





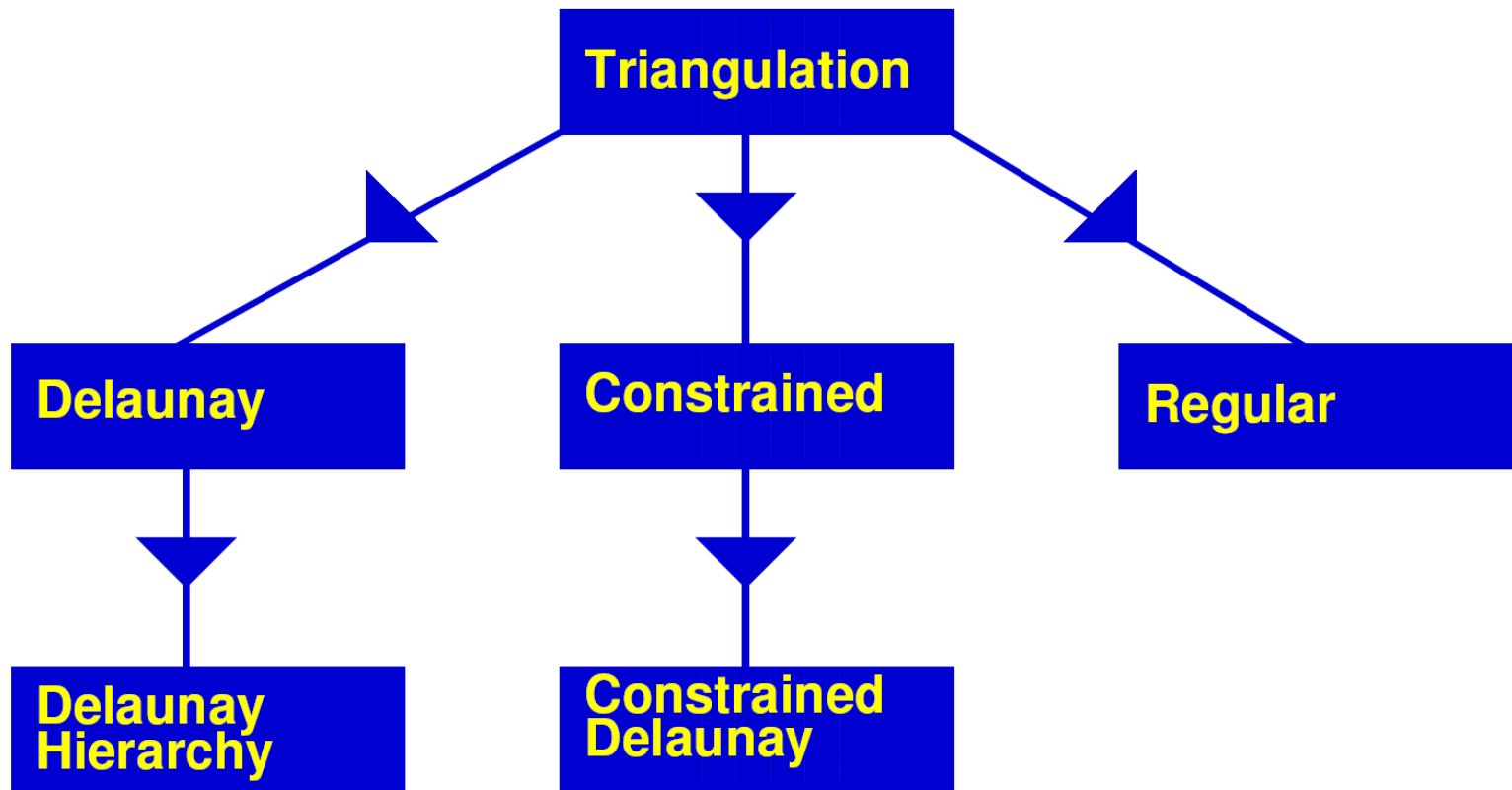
# Constrained Delaunay Triangulation

- Constrained triangulation which is as much **Delaunay as possible**. Each triangle satisfies the constrained empty circle property : its circumscribing circle encloses no vertex visible from the interior of the triangle, where enforced edges are considered as visibility obstacles.





# Derivation Tree (2D)



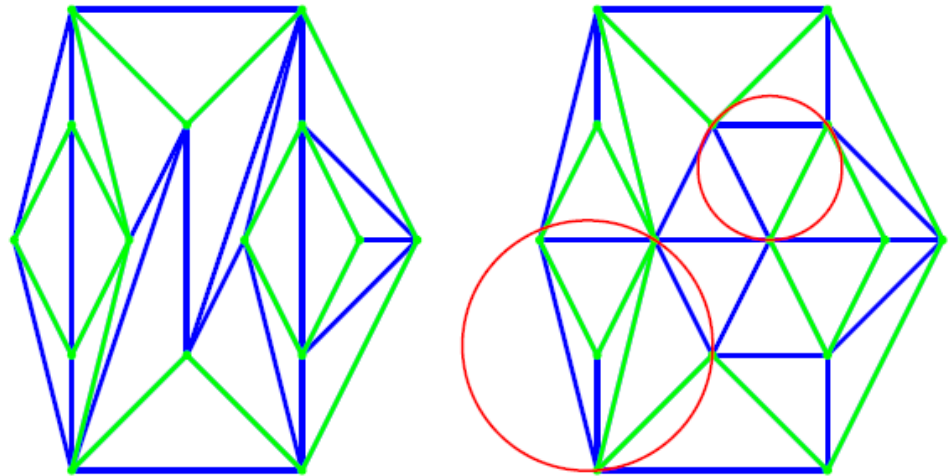
# General Features

- **Traversal:**
  - going from a face to its neighbors
  - iterators to visit all faces of a triangulation
  - circulators to visit all faces around a vertex or all faces intersected by a line.
- **Point location query**
- **Insertion, removal, flips:**
  - Features adapted to each type of triangulations (e.g., the insertions
  - and deletions in a Delaunay triangulation maintain the empty circle property).



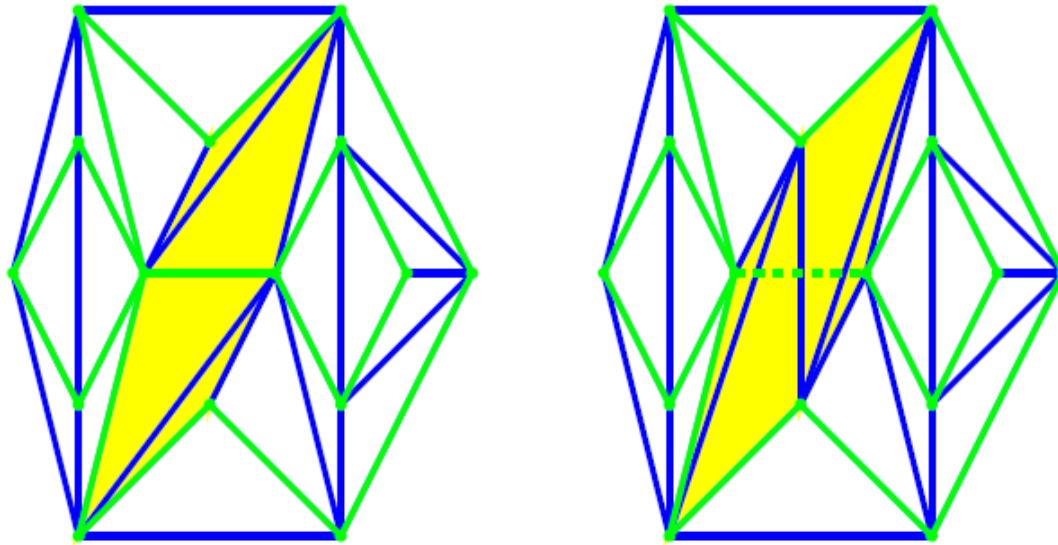
# Additional Features

- For some triangulations



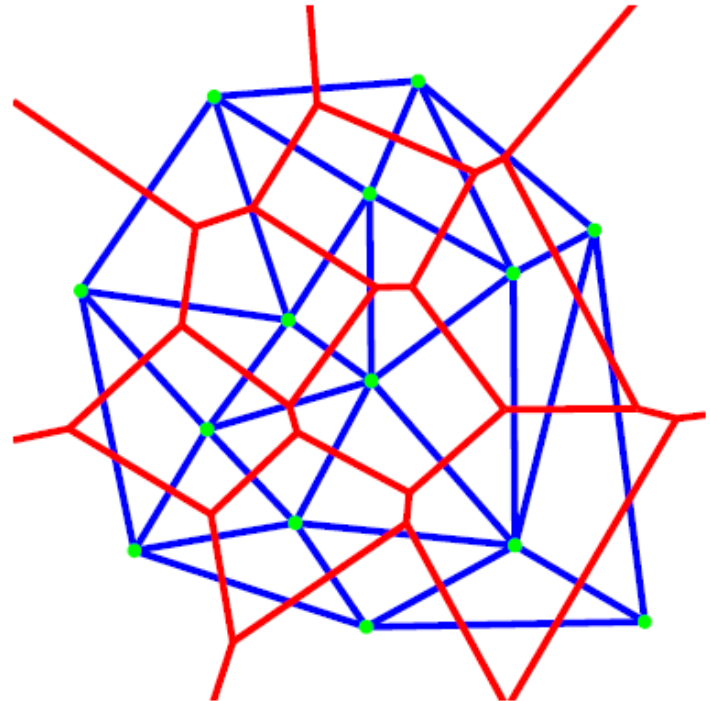
# Additional Features

- Example for **constrained** and **Delaunay constrained** triangulations:
  - Insertion and removal of constraints



# Additional Features

- For Delaunay triangulation
  - Nearest neighbor queries
  - Voronoi diagram



# Traversal (1)

- **Iterators**
  - All faces iterator
  - All vertices iterator
  - All edges iterator



# Traversal (2)

- **Circulators**

- **Face circulator**

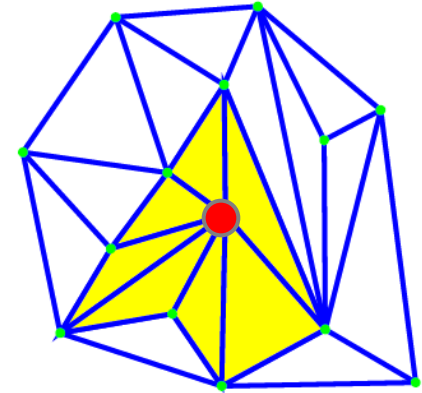
- faces incident to a vertex

- **Edge circulator**

- edges incident to a vertex

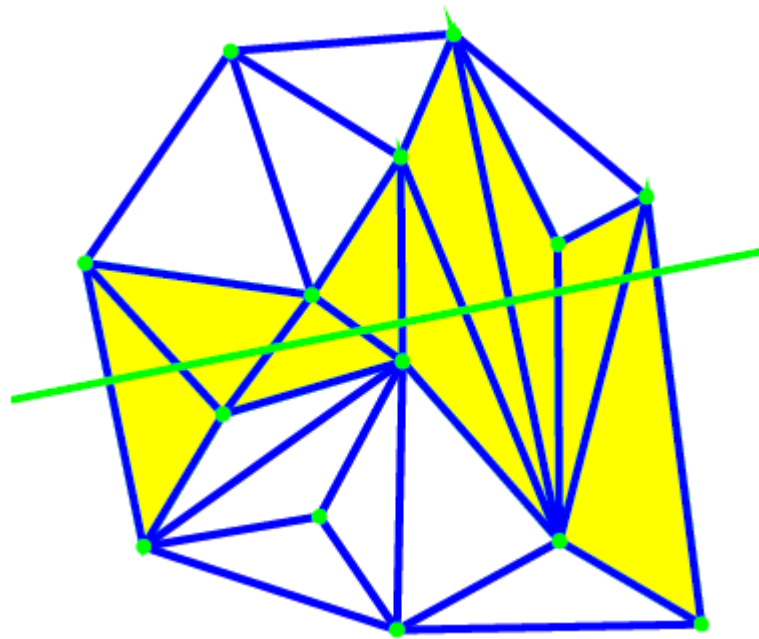
- **Vertex circulator**

- vertices incident to a vertex



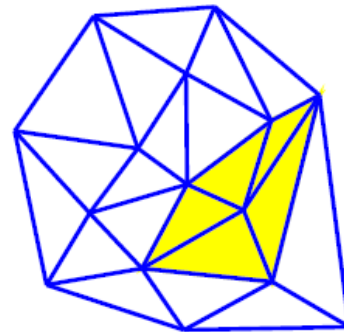
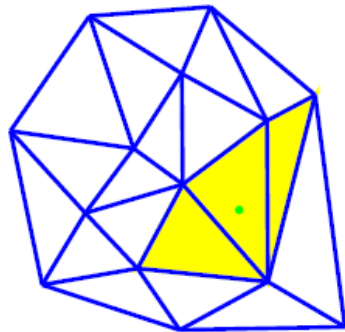
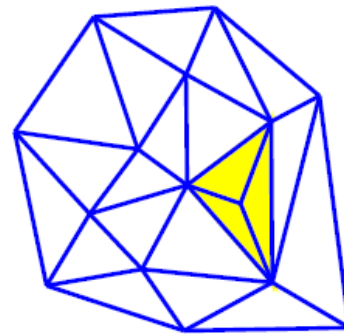
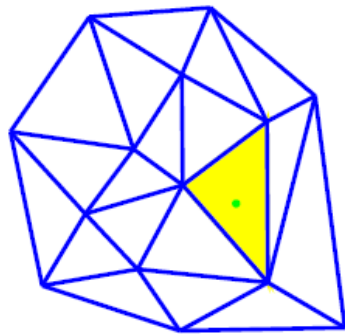
# Traversal (3)

- Line face circulator

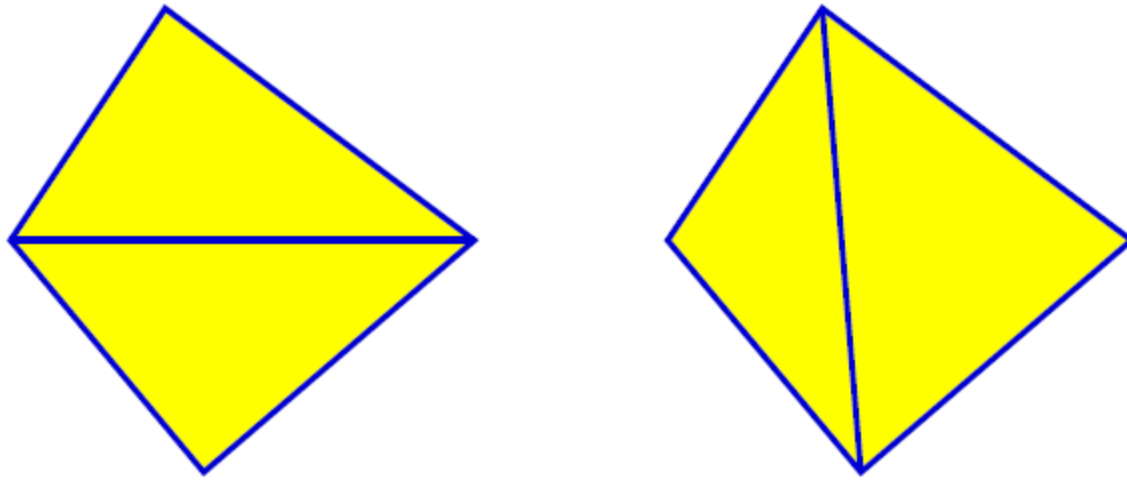




# Point Location & Insertion



# Edge Flip



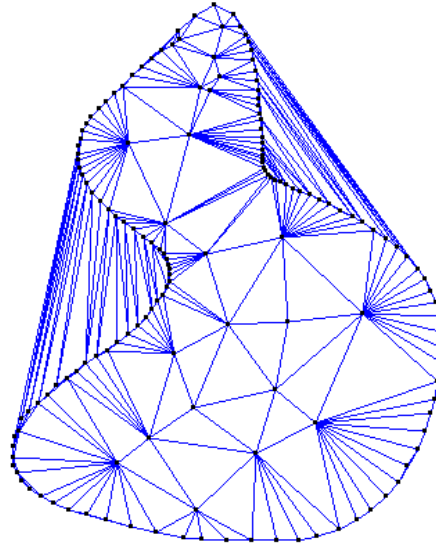
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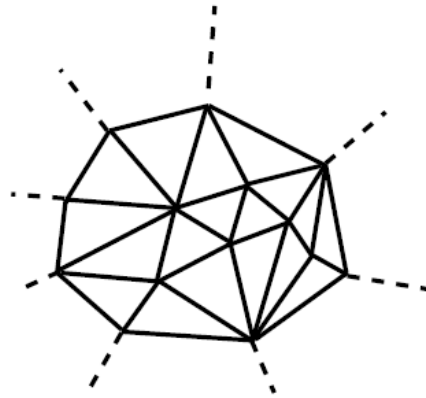
# Triangulations as a Set of Faces

- All triangulations in CGAL tile the **convex hull of their vertices**. Triangulated polygonal regions can be obtained through constrained triangulations.



# Triangulations as a Set of Faces

- All triangulations in CGAL tile the **convex hull of their vertices**. Triangulated polygonal regions can be obtained through constrained triangulations.
- An **imaginary vertex (so-called infinite vertex)** is added).



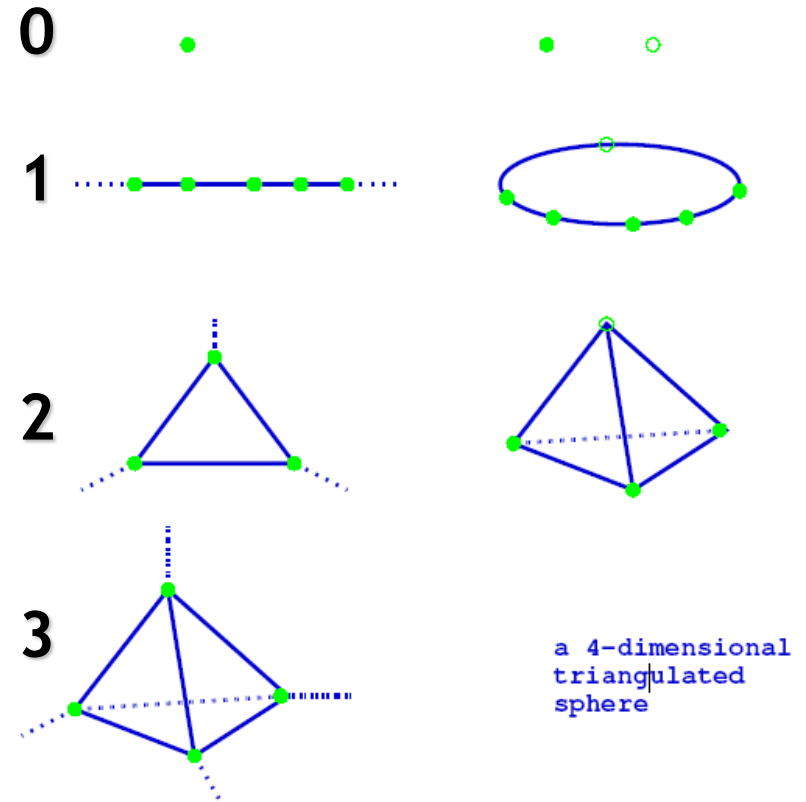
# Triangulations as a Set of Faces

- All triangulations in CGAL tile the convex hull of their vertices. Triangulated polygonal regions can be obtained through constrained triangulations.
- An imaginary vertex (so-called infinite vertex is added).
  - Any face is a triangle.
  - Any edge is incident to two exactly 2 faces.
  - The set of faces is equivalent to a 2D topological sphere.



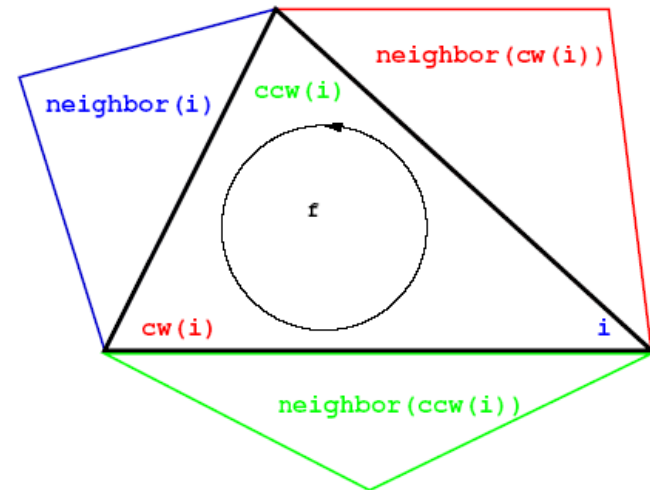
# Triangulations as a Set of Faces

In any dimension,  
the set of faces is  
combinatorially  
equivalent to a  
**triangulated  
sphere**.



# Representation

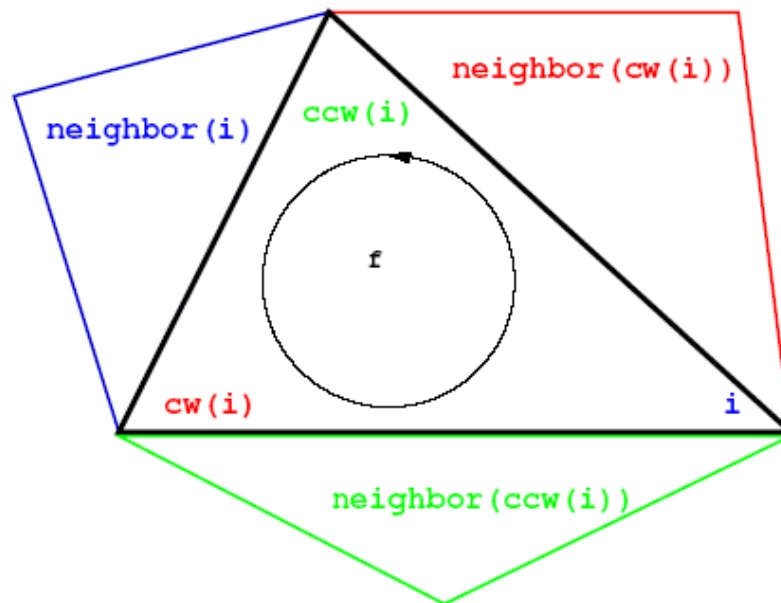
- The internal representation is based on **faces** and **vertices**.
- Edges are implicitly represented
- **Vertex**
  - `Face* v_face`
- **Face**
  - `Vertex* vertex[3]`
  - `Face* neighbor[3]`





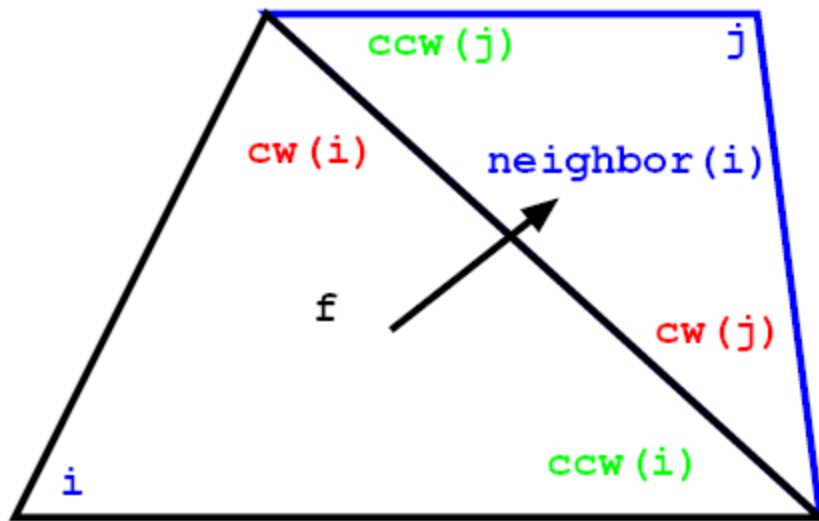
# Representation

- functions  $cw(i)$  &  $ccw(i)$



# Representation

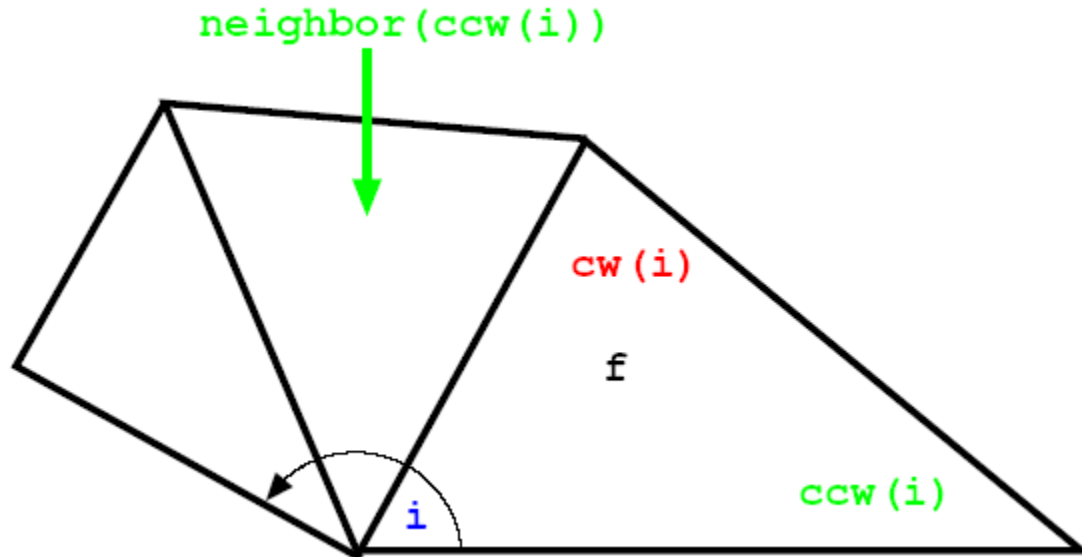
- From one Face to Another



```
n = f->neighbor(i)  
j = n->index(f)
```

# Representation

- Around a vertex



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# Software Design

- Many CGAL classes are parameterized by one or more **template parameters**:
  - Polygon\_2<Traits, Container>
  - Polyhedron\_3<Traits, HDS>
  - Planar\_map\_2<Dcel, Traits>
  - Arrangement\_2<Dcel, Traits, Base node>
  - Min\_circle\_2<Traits>
  - Point\_set\_2<Traits>
  - Range\_tree\_k<Traits>



# Triangulation Classes

`Triangulation_2`<Traits, TDS>

`Triangulation_3`<Traits, TDS>

- **Traits**

- Geometric traits

- **TDS**

- Triangulation Data Structure



# Geometric Traits

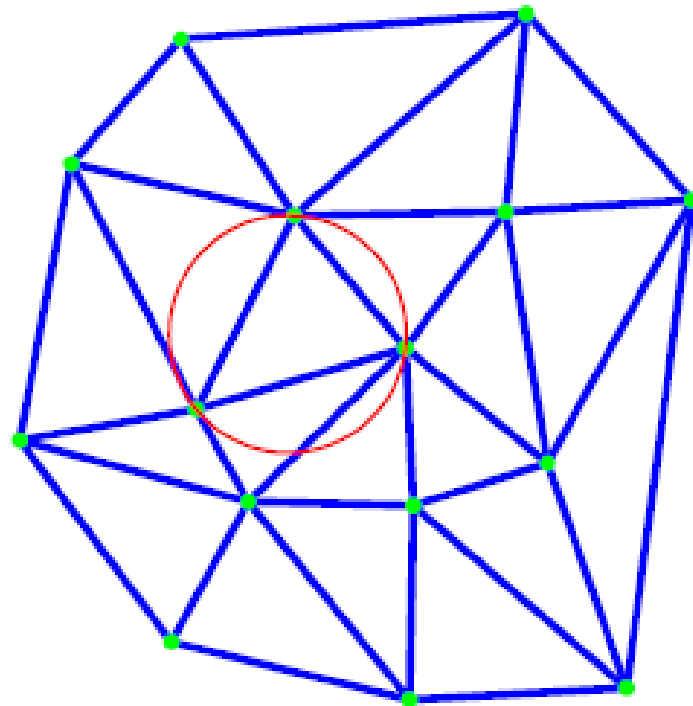
- Geometric **traits classes** provide :
  - Basic geometric objects
  - Predicates and Constructors
- Requirements for traits are documented
  - basic library data structures and algorithms can be used with user-defined objects
- Default traits classes are provided



# Traits Class for Delaunay Triangulation

- Requirements:

- Point
- Segment
- Triangle
- Line
- Ray
  
- orientation test
- in circle test
- circumcenter
- bisector





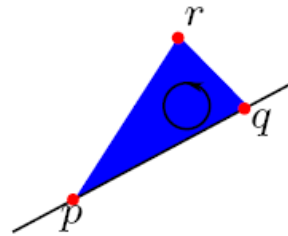
# Traits Class for Delaunay Triangulation

- Default traits class:
  - `Triangulation_euclidean_traits_2<Kernel>`
- Delaunay triangulation of 2D points:
  - `typedef Cartesian<double> Kernel;`
  - `typedef Triangulation_euclidean_traits_2<Kernel> Traits;`
  - `typedef Delaunay_triangulation_2<Traits> Triangulation;`

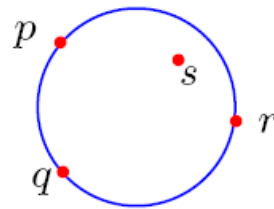


# Predicates for Delaunay Triangulation

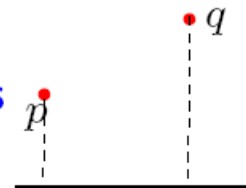
- Orientation test



- Incircle test



- Comparison of coordinates



# Traits Class for Terrains

## Needs

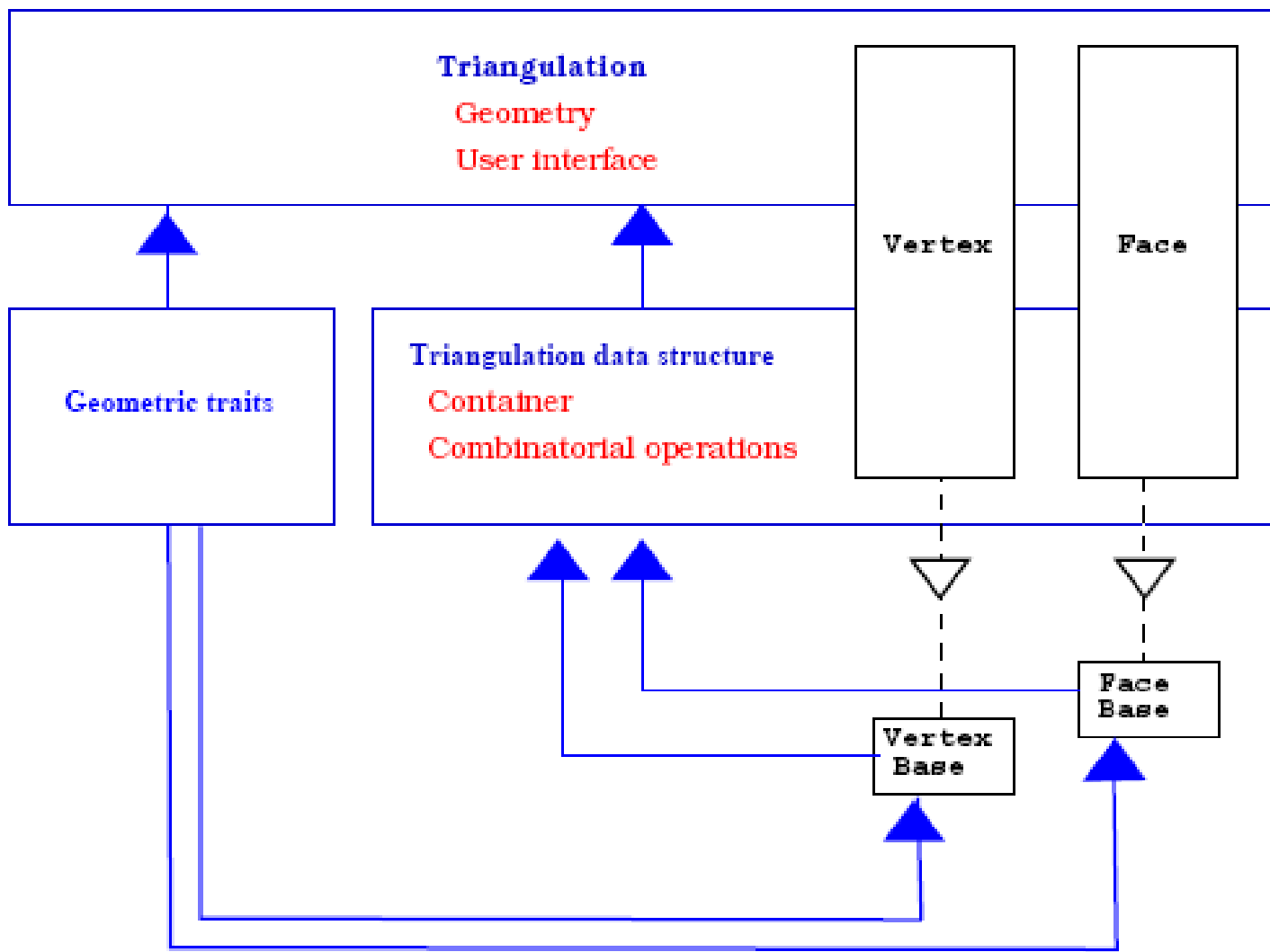
- 3D points
- orientation
- in circle
- on x and y coordinates

Triangulation\_euclidean\_traits\_xy\_3<kernel>

## Definition:

```
typedef Cartesian<double> kernel;  
typedef Triangulation euclidean traits xy 3<kernel> Traits;  
typedef Delaunay triangulation 2<Traits> Triangulation;
```

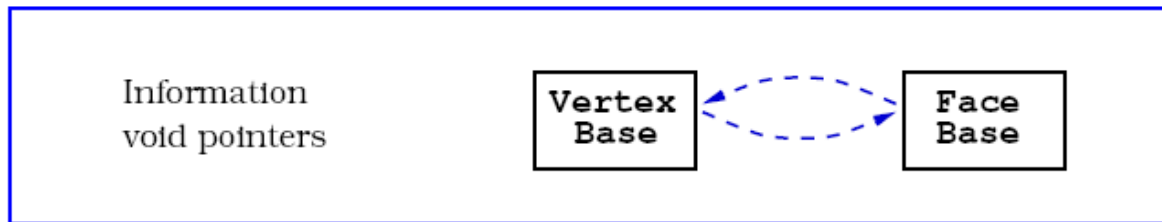




 derivation  
 template parameter



# Triangulation Design



## Vertex base

Vertex base :: Point

Vertex base( Point p, void\* f)

Point point();

void\* face();

void\* set point();

void\* set face();

## Face base

Face base(void\* v0, void\* v1, void\* v2,  
void\* n0, void\* n1, void\* n2)

void\* vertex(int i);

void\* neighbor(int i);

void\* set vertex(int i, void\* v);

void\* set neighbor(int i, void\* f);

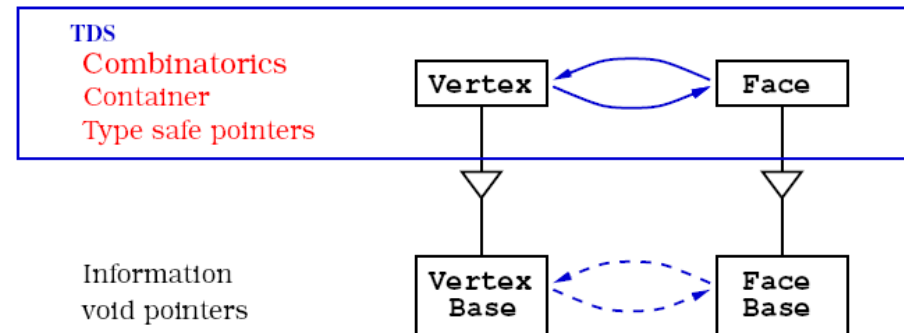


# Triangulation Data Structure

## Tds<Vb,Fb>

Types:

- Tds<Vb,Fb>::Vertex inherits from Vb
- Tds<Vb,Fb>::Face inherits from Fb
- Tds<Vb,Fb>::Face iterator
- Tds<Vb,Fb>::Edge iterator
- Tds<Vb,Fb>::Vertex iterator
- Tds<Vb,Fb>::Face circulator
- Tds<Vb,Fb>::Edge circulator
- Tds<Vb,Fb>::Vertex circulator

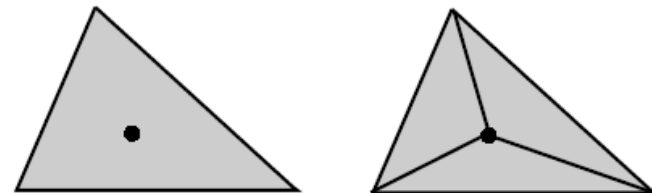
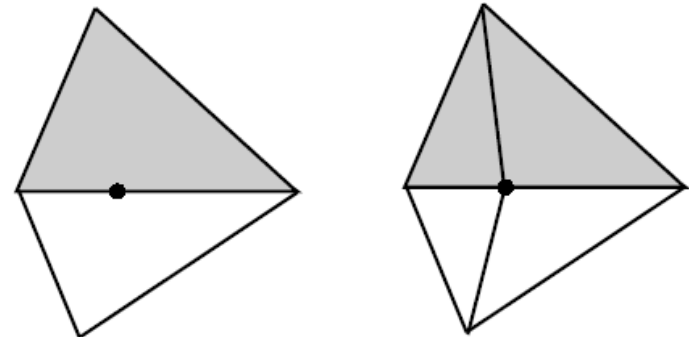


# Combinatorial Operations

void `insert_in_face` (Vertex\* v, Face\* f)

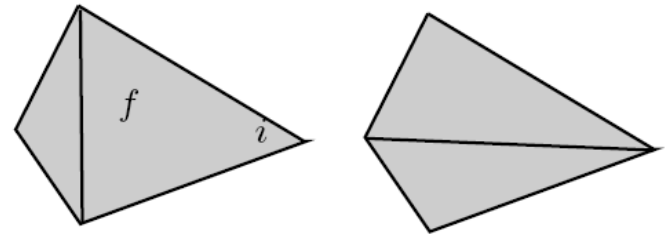
void `insert_in_edge` (Vertex\* v, Face\* f, int i)

void `remove_degre_3` (Vertex\* v);



# Combinatorial Operations

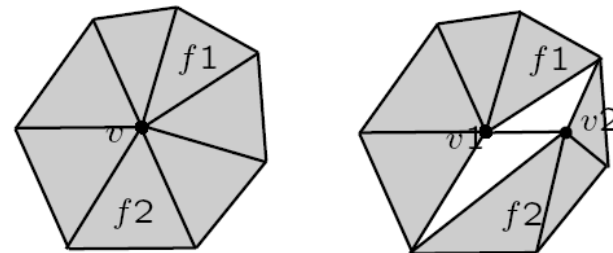
void **flip** (Face\* f, int i);



(on-going work)

void **split vertex** (Vertex\*, Face\* f1, Face\* f2)

void **join vertices** (Vertex\* v1, vertex\* v2)





# The Triangulation Class

```
CGAL::Triangulation 2<Gt, Tds >  
typedef Gt geometric_traits;  
typedef Tds Triangulation_data_structure;  
typedef Triangulation_2<Gt, Tds > Triangulation;
```

## Types

```
Gt::Point_2  
Gt::Segment_2  
Gt::Triangle_2  
Triangulation::Vertex inherits from Tds::Vertex  
Triangulation::Face inherits from Tds::Face  
Triangulation::Vertex_handle  
Triangulation::Face_handle
```

```
typedef pair<Face handle, int>  
Edge ;  
Triangulation::Face_iterator  
Triangulation::Edge_iterator  
Triangulation::Vertex_iterator  
Triangulation::Line_face_circulat  
or  
Triangulation::Face_circulator  
Triangulation::Edge_circulator  
Triangulation::Vertex_circulator
```



# High Level Functions

```
enum Locate_type { VERTEX=0, EDGE, FACE,  
                  OUTSIDE_CONVEX_HULL,  
                  OUTSIDE_AFFINE_HULL}  
  
Face_handle locate( Point query,  
                  Locate_type& lt,  
                  int& li,  
                  Face_handle h =Face_handle() );
```

```
Vertex_handle insert(Point p)
```

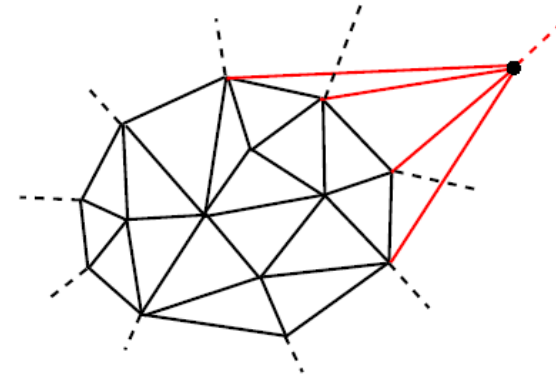
```
void remove(Vertex_handle v)
```



# Insertion

Vertex handle `insert` (Point `p`)

```
{  
    Locate type lt; int li;  
    Face handle loc = locate(p, lt, li);  
    switch(lt){  
    case VERTEX : return f->vertex(li);  
    case EDGE : return insert_in_edge( p, loc,li);  
    case FACE : return insert_in_face(v,loc);  
    case OUTSIDE CH : return insert_outside ch(p,loc);  
    case OUTSIDE AH : return insert_outside ah(p);  
    }
```



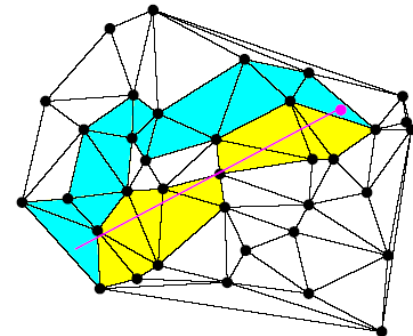
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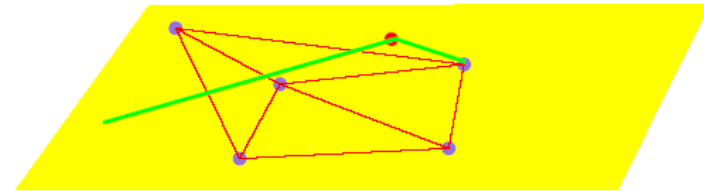
# Algorithms for Triangulation

- All CGAL triangulations are built through **incremental on-line** insertion of vertices.
- The main algorithmic issue is therefore to deal with **point location**.
- **CGAL** offers different algorithms :
  - linewalk ●
  - Zigzag walk ●
  - jump and walk strategy
  - the Delaunay hierarchy

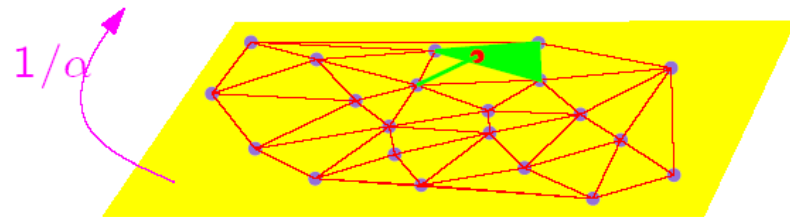
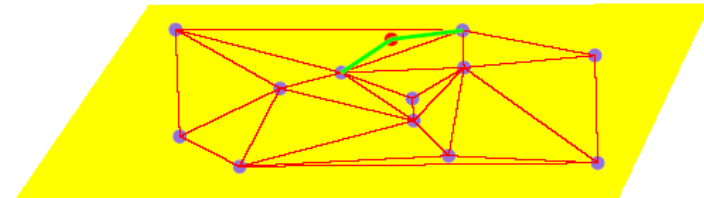


# Efficient Localization

- Delaunay Hierarchy



Location structure



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```
#include <CGAL/Cartesian.h>
#include <CGAL/Triangulation_2.h>

using namespace CGAL;
using namespace std;

typedef Cartesian<double> Kernel;
typedef Triangulation_2<Kernel> Triangulation;
typedef Triangulation::Vertex_circulator Vertex_circulator;
typedef Kernel::Point_2 Point;

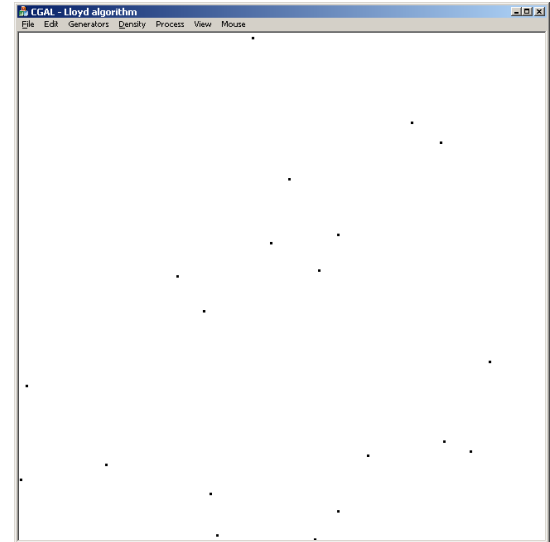
    Triangulation t;
    Point p;
    while(cin >> p) t.insert(p);
    Vertex_circulator vc = t.incident_vertices(t.infinite_vertex());
    Vertex_circulator done(vc);
    do
        cout << vc->point();
    while(++vc != done);
}
```





# Drawing Generators...

```
template <class kernel, class TDS>
class DT2 : public CGAL::Delaunay_triangulation_2<kernel,TDS>
{
    public:
    void gl_draw_generators()
    {
        ::glBegin(GL_POINTS);
        Point_iterator it;
        for(it = points_begin();
            it != points_end();
            it++)
        {
            const Point& p = *it;
            ::glVertex2d(p.x(),p.y());
        }
        ::glEnd();
    }
};
```

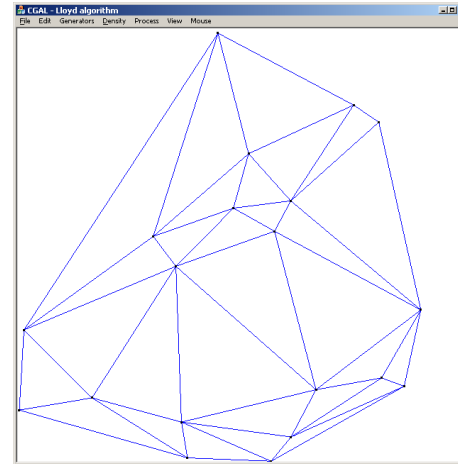


<http://www.cgal.org>



# Drawing Delaunay Edges...

```
void gl_draw_delaunay_edges()
{
    ::glBegin(GL_LINES);
    Edge_iterator it;
    for(it = edges_begin();
        it != edges_end();
        it++)
    {
        // edge = std::pair<Face_handle,int>
        Edge& edge = *it;
        const Point& p1 = edge.first->vertex(ccw(edge.second))->point();
        const Point& p2 = edge.first->vertex(cw(edge.second))->point();
        ::glVertex2f(p1.x(), p1.y());
        ::glVertex2f(p2.x(), p2.y());
    }
    ::glEnd();
}
```



# Drawing Voronoi Edges

```
void gl_draw_voronoi_edges() {  
    ::glBegin(GL_LINES);  
    Edge_iterator hEdge;  
    for(hEdge = edges_begin(); hEdge != edges_end(); hEdge++)  
    {  
        CGAL::Object object = dual(hEdge);  
        Segment segment;  
        Ray ray;  
        Point source, target;  
        if(CGAL::assign(segment,object))  
        {  
            source = segment.source();  
            target = segment.target();  
        }  
        else if(CGAL::assign(ray,object))  
        {  
            source = ray.source();  
            target = ray.point(1);  
        }  
        ::glVertex2f(source.x(),source.y());  
        ::glVertex2f(target.x(),target.y());  
    }  
    ::glEnd(); }  
}
```

