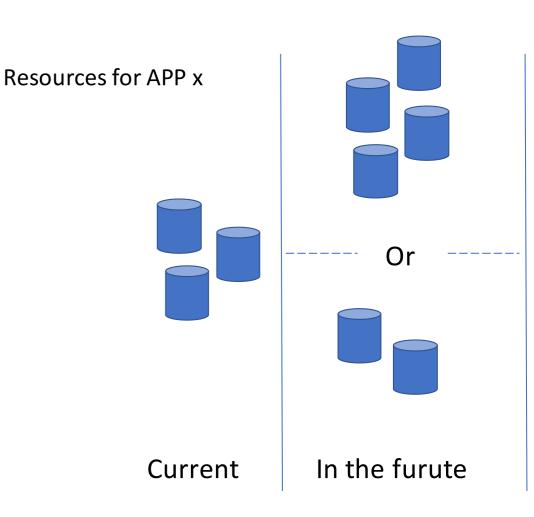
Modeling the Stream Rate of Vehicular Networks for Predictable Auto-Scaling of Edge-Cloud Systems

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Introduction

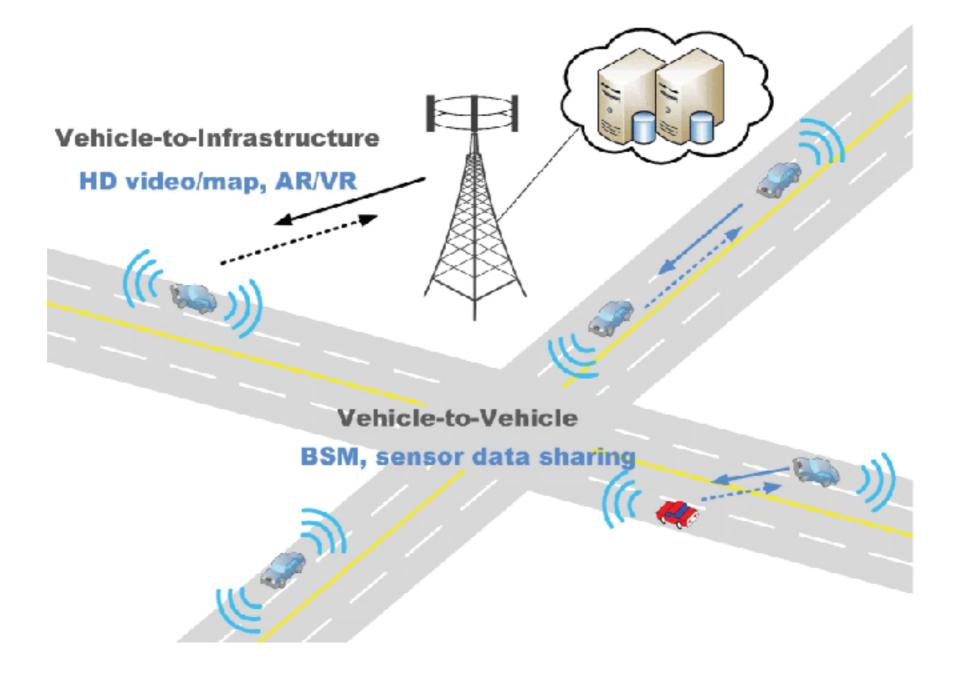
- Context: Vehicular Networks connected to the Cloud
- Objective: take advantage of the Edge and Cloud processing capabilities efficiently
- Use-case: auto-scaling for Edge-Cloud architectures



Goals

- Modeling the stream arrivals rate
 - Use of Edge Services to predict the load of information to be processed
 - Making a more realistic prediction using Coxian distributions
 - Mathematical model for arrival of information
- Designing an Auto-Scaling module to reserve resources in the Cloud
 - Reduction the amount of information processed in the Cloud

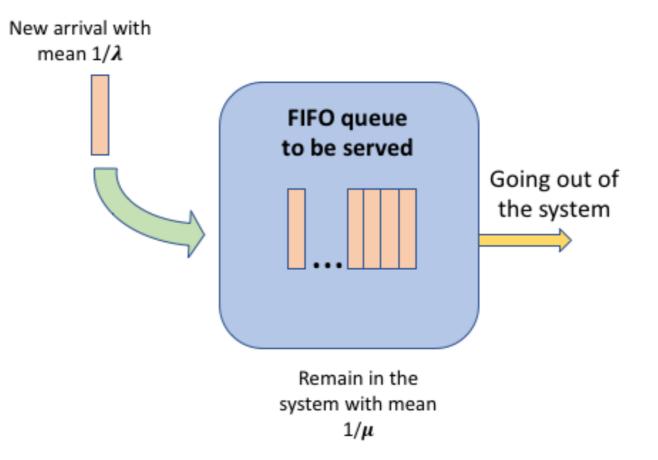
Vehicular Networks



* Taken from Le Liang, Toward Intelligent Vehicular Networks: A Machine Learning Framework

Prediction of the arrivals

- Classical arriving/service time model for networks based on queue theory
- Usage of exponential distribution to model times of service



Prediction of the arrivals

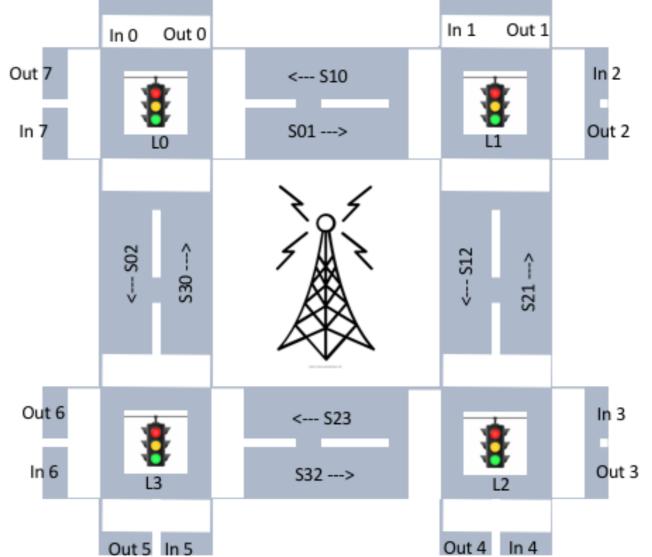
 Another approach is to see like a black box where vehicles enters and travel inside a coverage area



Inside the coverage area, different situations could occur

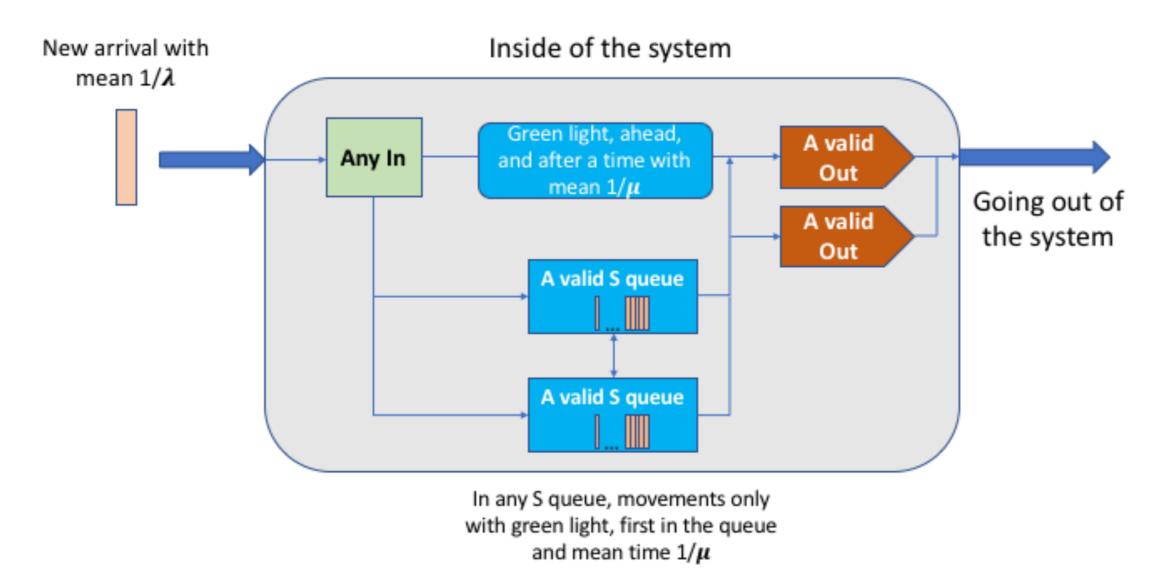
Prediction of the arrivals

- Predicting model based on traffic lights
- Coverage area where vehicles move inside it by a random time



Prediction of the arrival

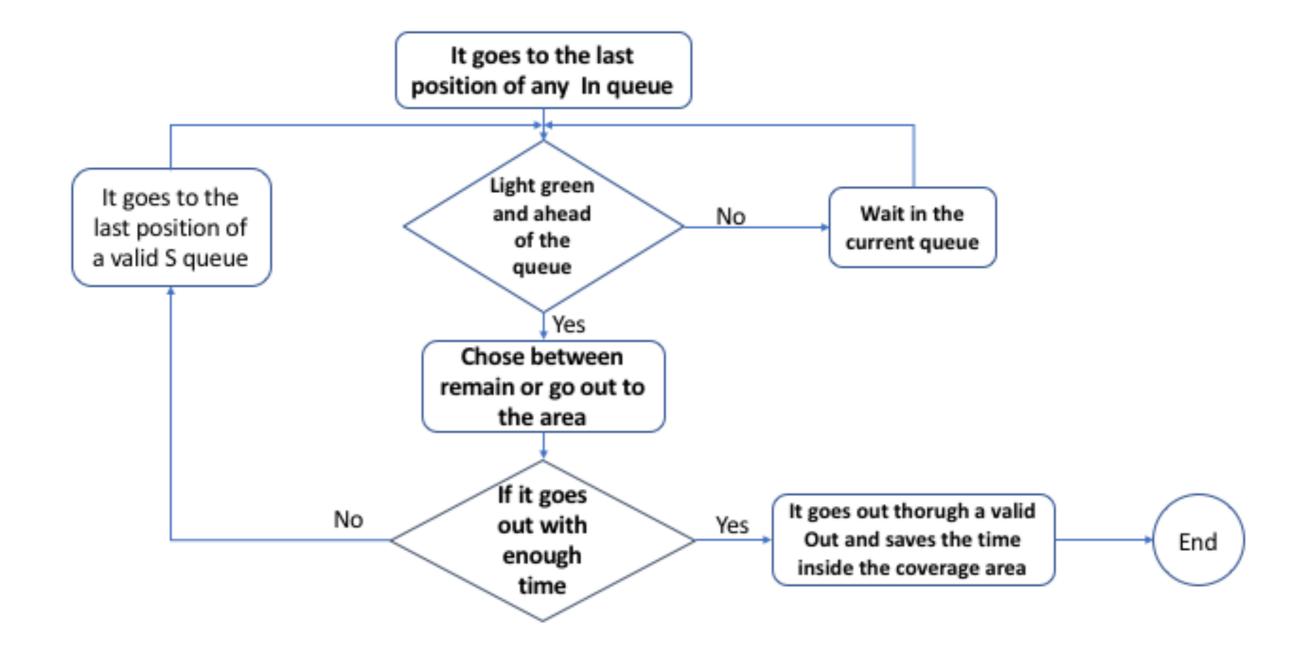
 Although multiple random variables with exponentials distribution are considered, the time inside the coverage area is not a exponential distribution



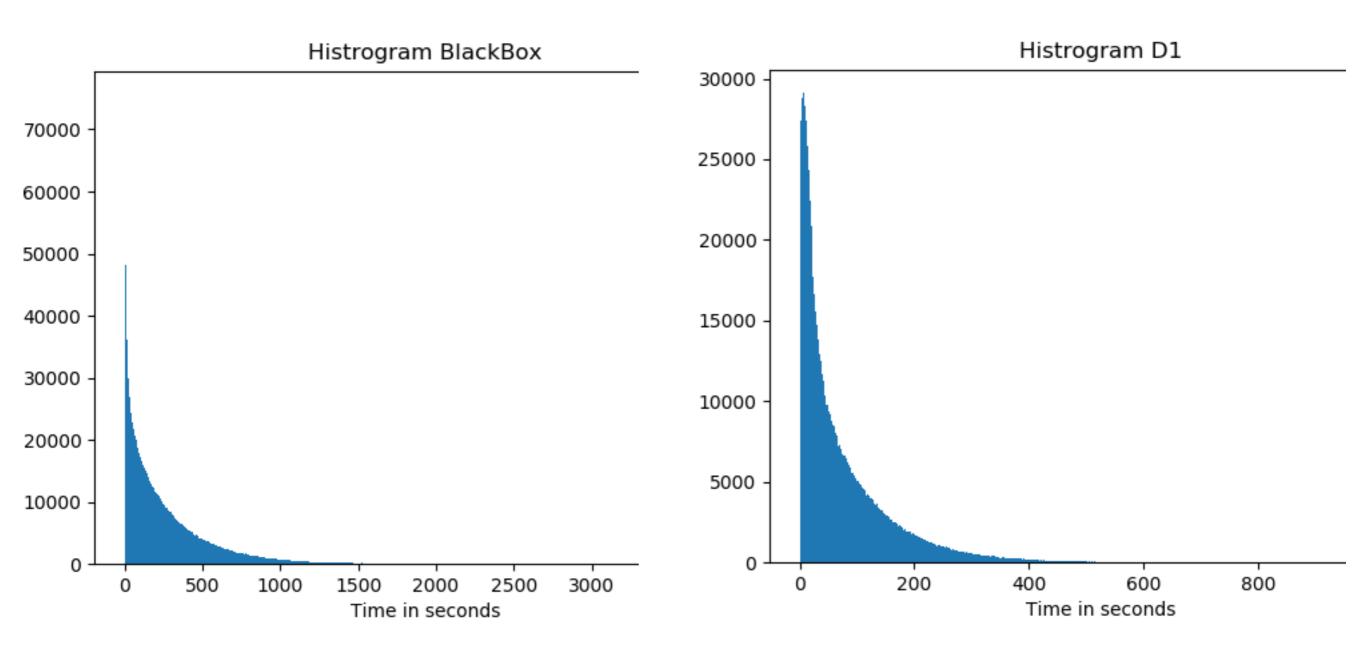
Assumptions

- Vehicles move inside the coverage area only over the rails
- Each rail is seen as a queue
- There are two kind of queues :
 - In: Those are entrances to the coverage area
 - S: Those are the rails which connect to different traffic lights
- Arrivals are following an exponential distribution with mean $1/\lambda$
- Semaphores change between red and green light following a random exponential distribution with mean $1/\gamma$
- Vehicles only move to other place in case of green light and after a random time exponentially distributed with mean $1/\mu$

Movement of the vehicles more similar to real life



Distribution of times inside the coverage area



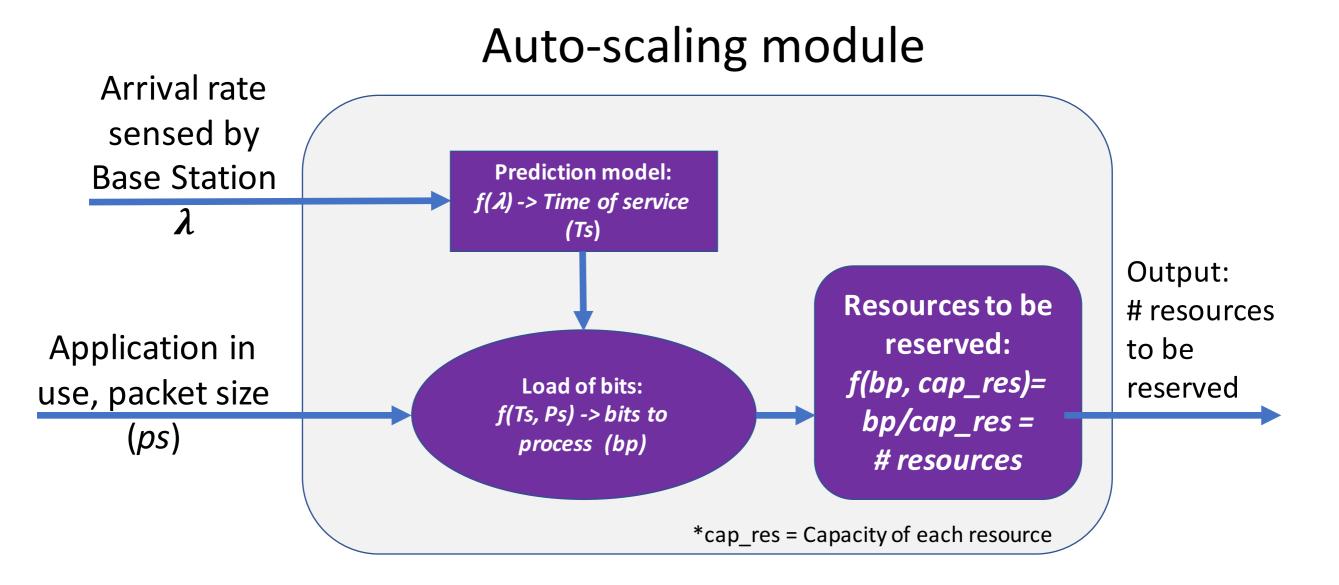
Why prediction is important

- If the time of permanence in the system is know, it could be possible to know the load of information that needs to be processed
- In order to have a mathematical model of the times inside the system, Coxian distribution is though to be used
- The challenge is find the set of parameters of Coxian distribution that suit the behavior of vehicles
- The model of prediction, is a key point for the Autoscaling module

System architecture

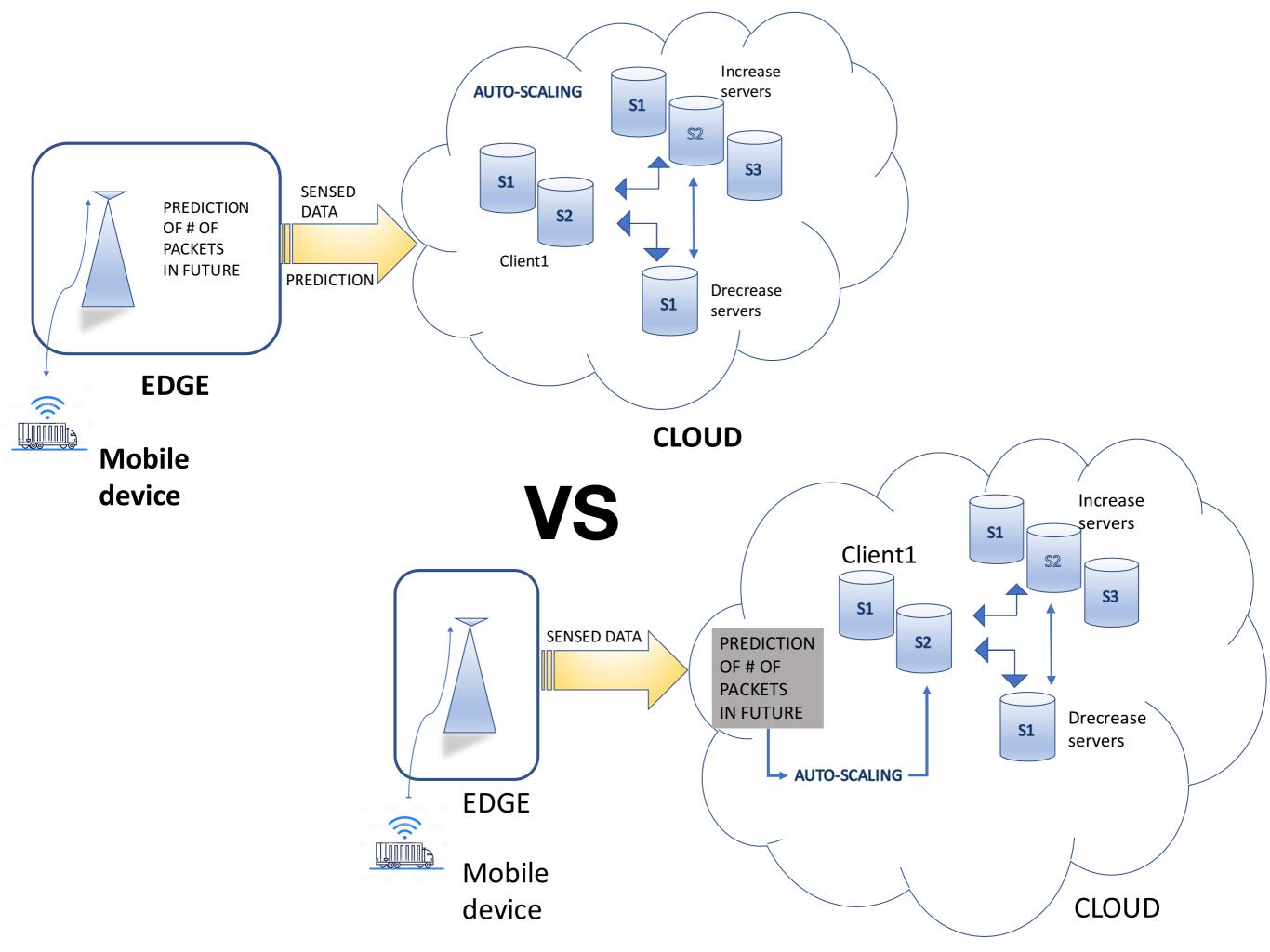
- Vehicle to infrastructure network model
- Edge processing capabilities
- Edge
 Prediction
 Cloud
 Scaling

Auto-scaling module



Use of Edge-Cloud architecture

- Two approaches:
 - Prediction made in the Edge, process as much as possible in the Edge and reduce services required from Cloud
 - Prediction made in the Cloud, reserve services in the Cloud



Benefits of Edge-Cloud Auto-scaling

- Knowing the arrival rate to the system, the prediction model estimate the time that vehicles are inside of the system
- Based on the size of packages and the rate of them, (kbps), the load of information is computed
- The work load for a period of time is computed
- Cloud resources are reserved based on the work load

Next steps

- Use of a real Edge-Cloud architecture to be deployed over the Grid5000
- Compare performance of prediction
- Install the prediction module in the Edge and in the Cloud in two separate experiments.
- Compare the accuracy of predictions in Edge against in Cloud

Expected results

- The model is more realistic to real world
- The model could be easily extended to other use-cases
- The prediction made in the Edge is more efficient than in the Cloud
- Latency could be reduced