



# *Kinetic ODEs Modeling Vehicular Traffic in Time and Space*

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\* Joint with **Luisa Fermo** (University of Cagliari, Italy)



## *Keywords and Motivations*

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Continuous flow



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Granularity



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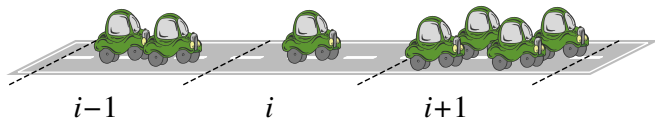


Stochastic games

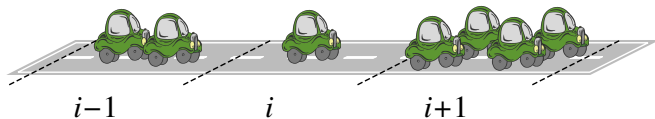


## The model

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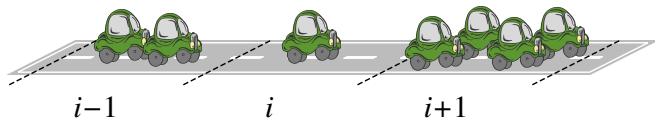


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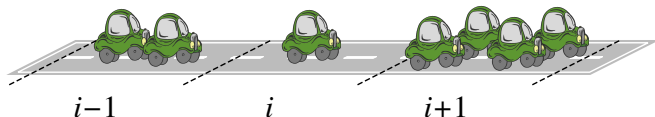
- ▶ Space cells:  $I_1, \dots, I_i, \dots, I_n, \cup_{i=1}^n I_i = [0, L]$

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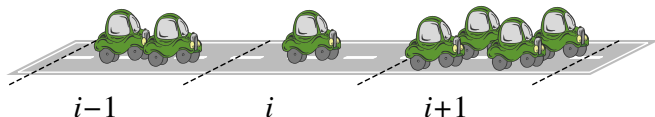
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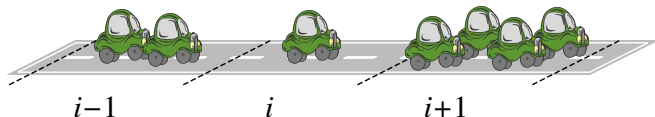


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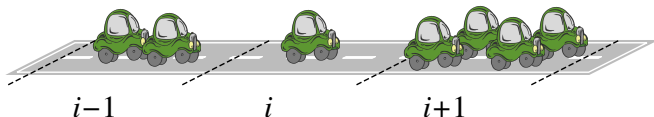


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$$\frac{df_{ij}}{dt} + v_j (\Phi_{i,i+1} f_{ij} - \Phi_{i-1,i} f_{i-1,j}) =$$

$$\Phi_{i,i+1} = \begin{cases} \frac{1 - \rho_{i+1}}{\rho_i} & \text{if } \rho_i + \rho_{i+1} > 1 \\ 1 & \text{if } \rho_i + \rho_{i+1} \leq 1, \end{cases}$$

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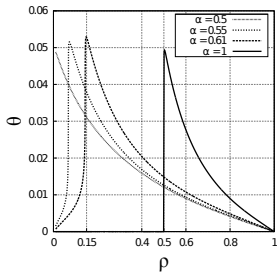
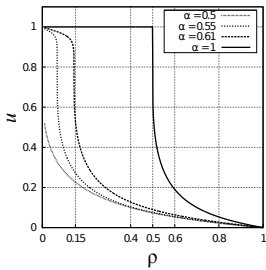
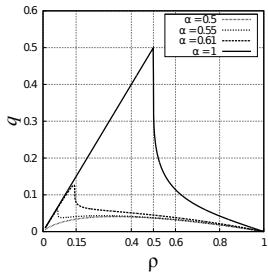


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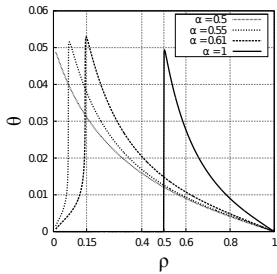
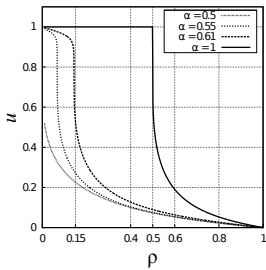
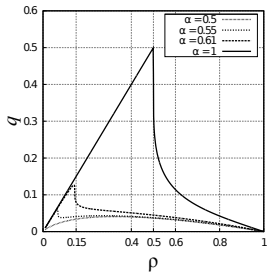
$$\frac{df_{ij}}{dt} + v_j (\Phi_{i,i+1} f_{ij} - \Phi_{i-1,i} f_{i-1,j}) = \sum_{h,k=1}^n \eta_{hk}(i) \mathcal{A}_{hk}^j(i) f_{ih} f_{ik} - f_{ij} \sum_{k=1}^n \eta_{jk}(i) f_{ik}$$

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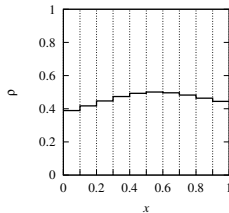
## Case studies



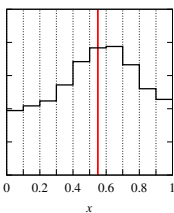
# Case studies



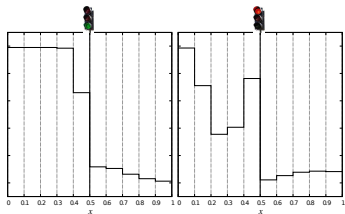
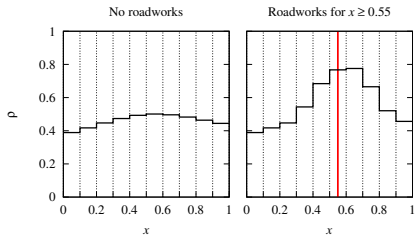
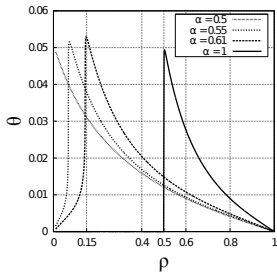
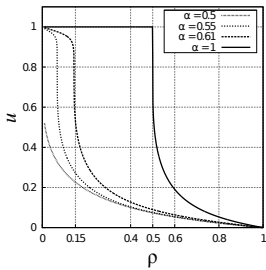
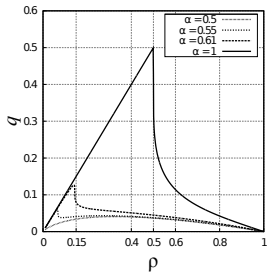
No roadworks



Roadworks for  $x \geq 0.55$



# Case studies





## Theory: initial/boundary-value problem

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$$\left\{ \begin{array}{l} \frac{df_{ij}}{dt} + v_j (\Phi_{i,i+1}[\rho] f_{ij} - \Phi_{i-1,i}[\rho] f_{i-1,j}) = \eta(i)[\rho] \left( \sum_{h,k=1}^n \mathcal{A}_{hk}^j(i)[\rho] f_{ih} f_{ik} - f_{ij} \rho_i \right) \\ f_{ij}(0) = f_{ij}^0 \in [0, 1] \quad \forall i, j \\ f_{0j}(t) = \bar{f}_j(t) \in [0, 1] \quad \forall j, \forall t \\ \Phi_{0,1} = \bar{\Phi}(t) \in [0, 1] \quad \forall t \end{array} \right.$$



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Under suitable **regularity assumptions** on  $\Phi_{i,i+1}$ ,  $\eta(i)$ ,  $\mathcal{A}_{hk}^j(i)$ :





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- ▶ **Uniqueness and continuous dependence** on the data:

$$\|\mathbf{f} - \mathbf{g}\|_{\infty} \leq C \left[ \|\mathbf{f}^0 - \mathbf{g}^0\|_1 + \int_0^{T_{\max}} (|\bar{\Phi}^f(t) - \bar{\Phi}^g(t)| + \|\bar{\mathbf{f}}(t) - \bar{\mathbf{g}}(t)\|_1) dt \right]$$



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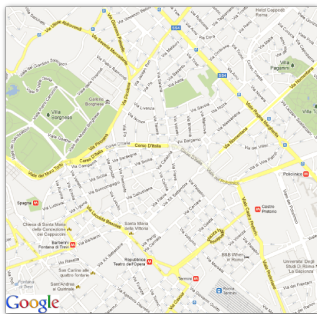
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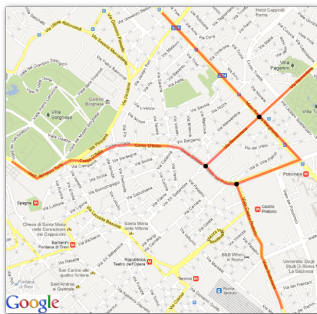
$$\|\mathbf{f} - \mathbf{g}\|_{\infty} \leq \mathcal{C} \left[ \|\mathbf{f}^0 - \mathbf{g}^0\|_1 + \int_0^{T_{\max}} (|\bar{\Phi}^f(t) - \bar{\Phi}^g(t)| + \|\bar{\mathbf{f}}(t) - \bar{\mathbf{g}}(t)\|_1) dt \right]$$

- ▶ **Boundedness** of the solution:

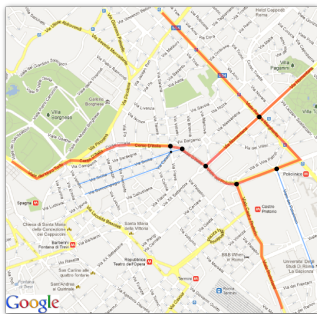
$$0 \leq f_{ij}(t) \leq 1, \quad \forall i, j, \forall t$$



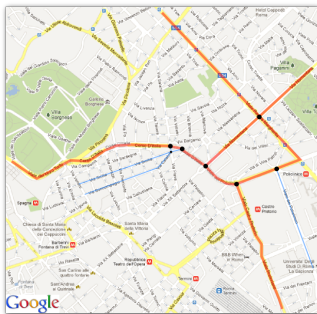
## ► Road networks



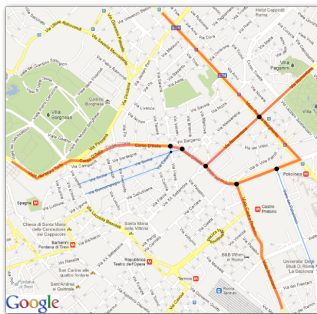
- ▶ Road networks
- ▶ **Main** and **minor** roads with different refinements



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- ▶ Junctions handled just as easily as cell interfaces



- ▶ Road networks
- ▶ Main and minor roads with different refinements
- ▶ Junctions handled just as easily as cell interfaces
- ▶ (Hopefully) easy to extend the theory of IBV problems to the whole network





## References

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