

Welcome to the Workshop on Mathematical Foundations of Traffic



**Alexandre Bayen, Rinaldo Colombo,
Paola Goatin, Benedetto Piccoli**

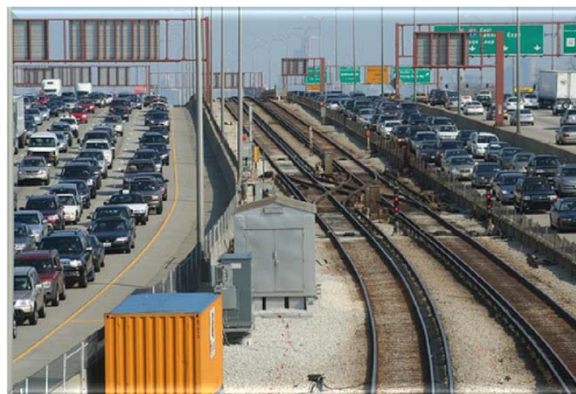
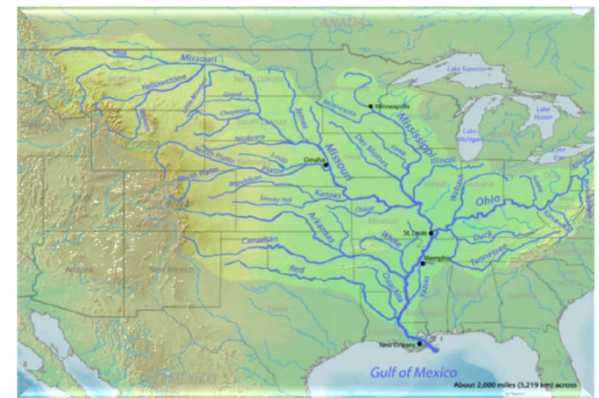
INRIA, Sophia Antipolis, March 2013



Large scale infrastructure systems

Physical systems integrate dynamical processes in which spatial variations play an integral role in their evolution. Multiple challenges

- Large scale data analytics on streaming data
- Control of non fully automated systems (human in the loop)

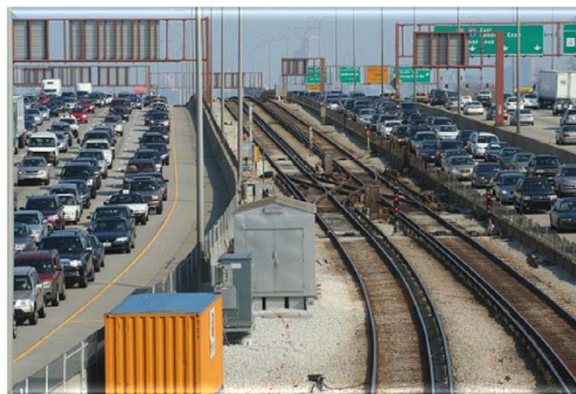




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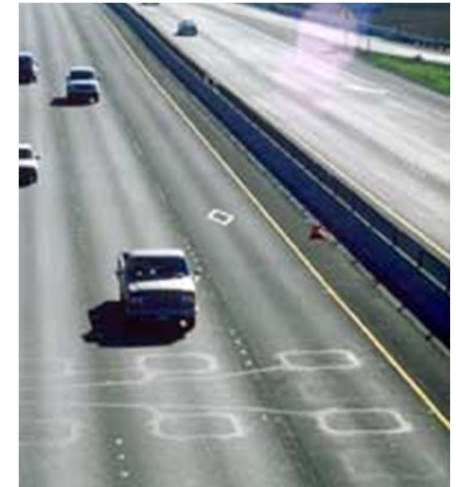




“Classical” source of traffic information

Dedicated traffic monitoring infrastructure:

- Self inductive loops
- Wireless pavement sensors
- FasTrak, EZ-pass transponders
- Cameras
- Radars
- License plate readers



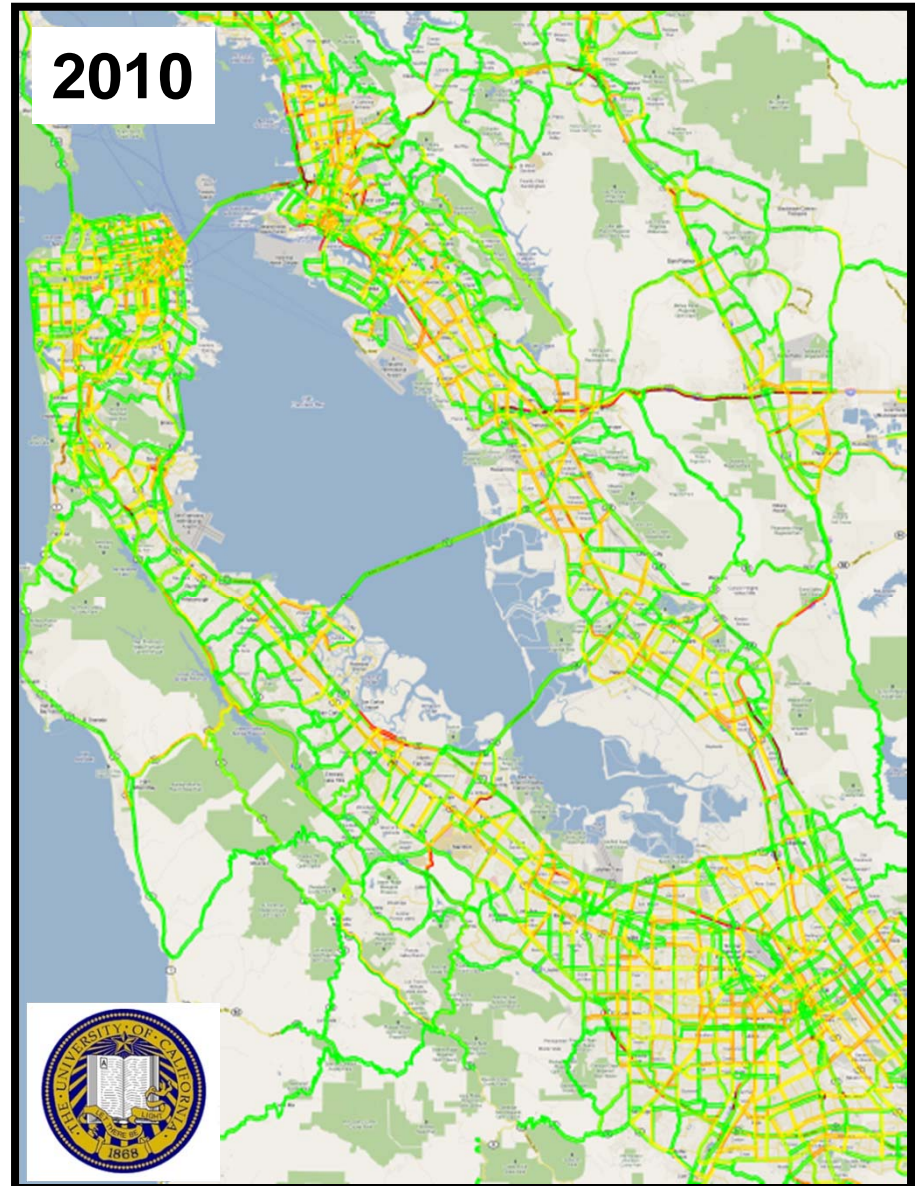
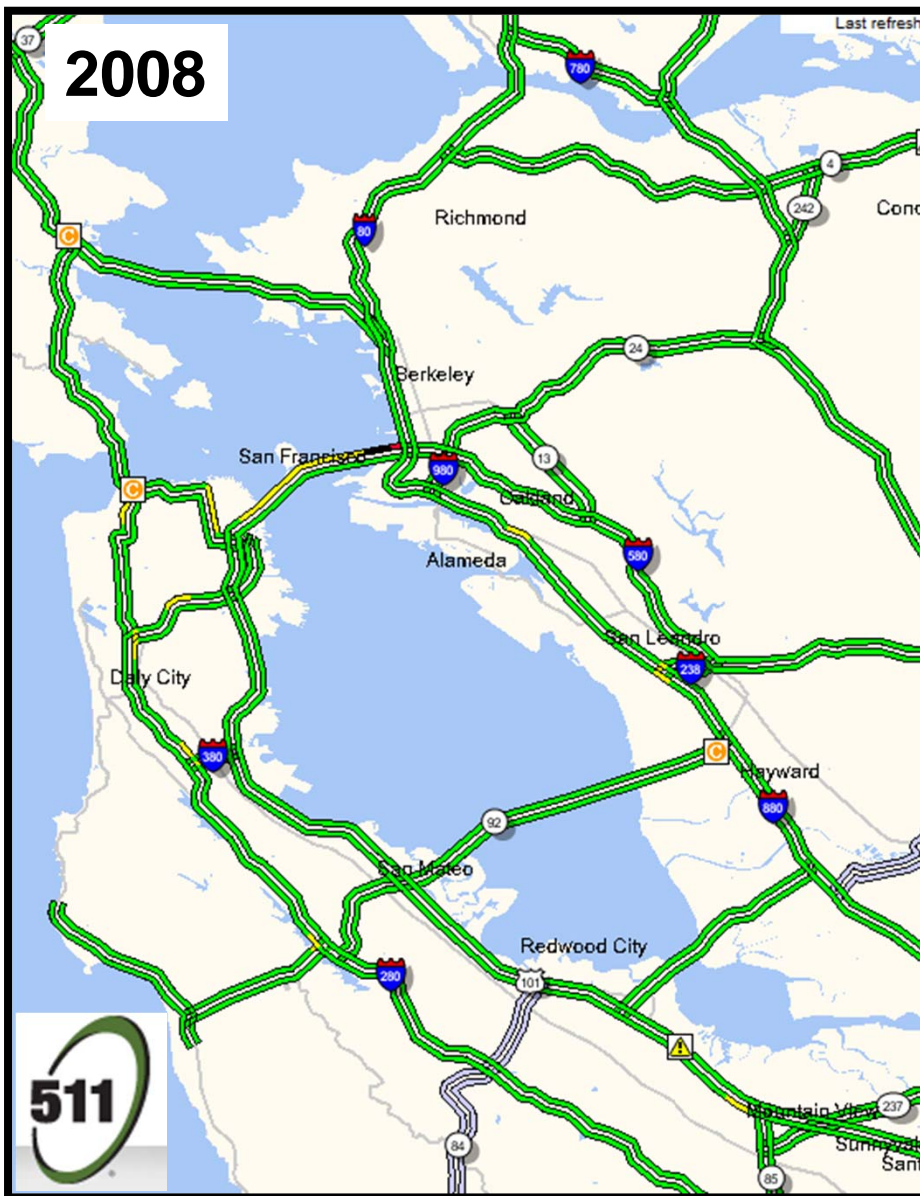
Issues of today’s dedicated infrastructure

- Installation costs
- Maintenance costs
- Reliability
- Coverage





First historical indirect beneficiary: transportation





Example: 0.5% of Mobile Millennium data (one day)



One day of Yellow Cab data: 2010-03-29 04:00:02.0

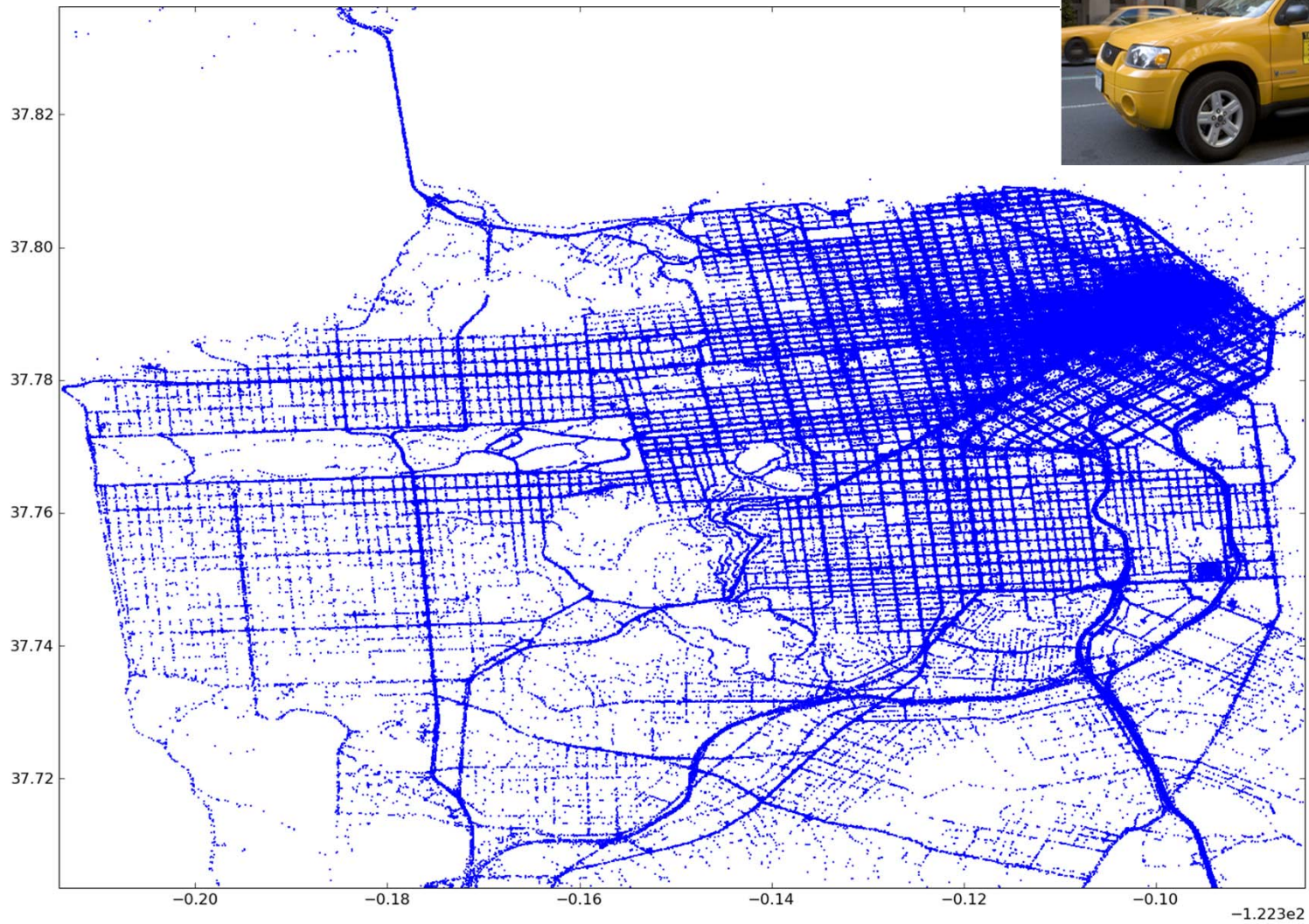
Mobile Millennium



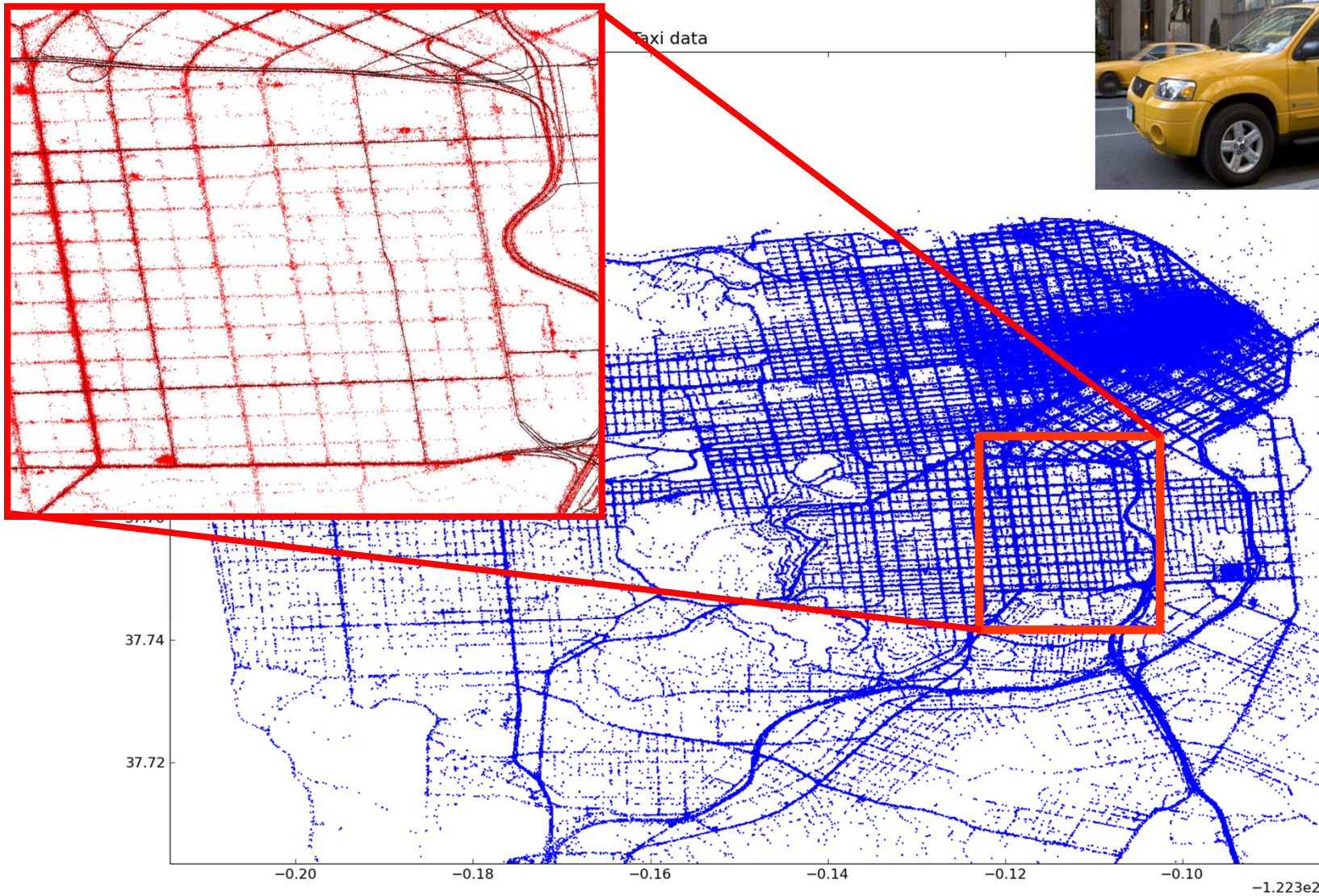
CALIFORNIA
PATH

<http://traffic.berkeley.edu>

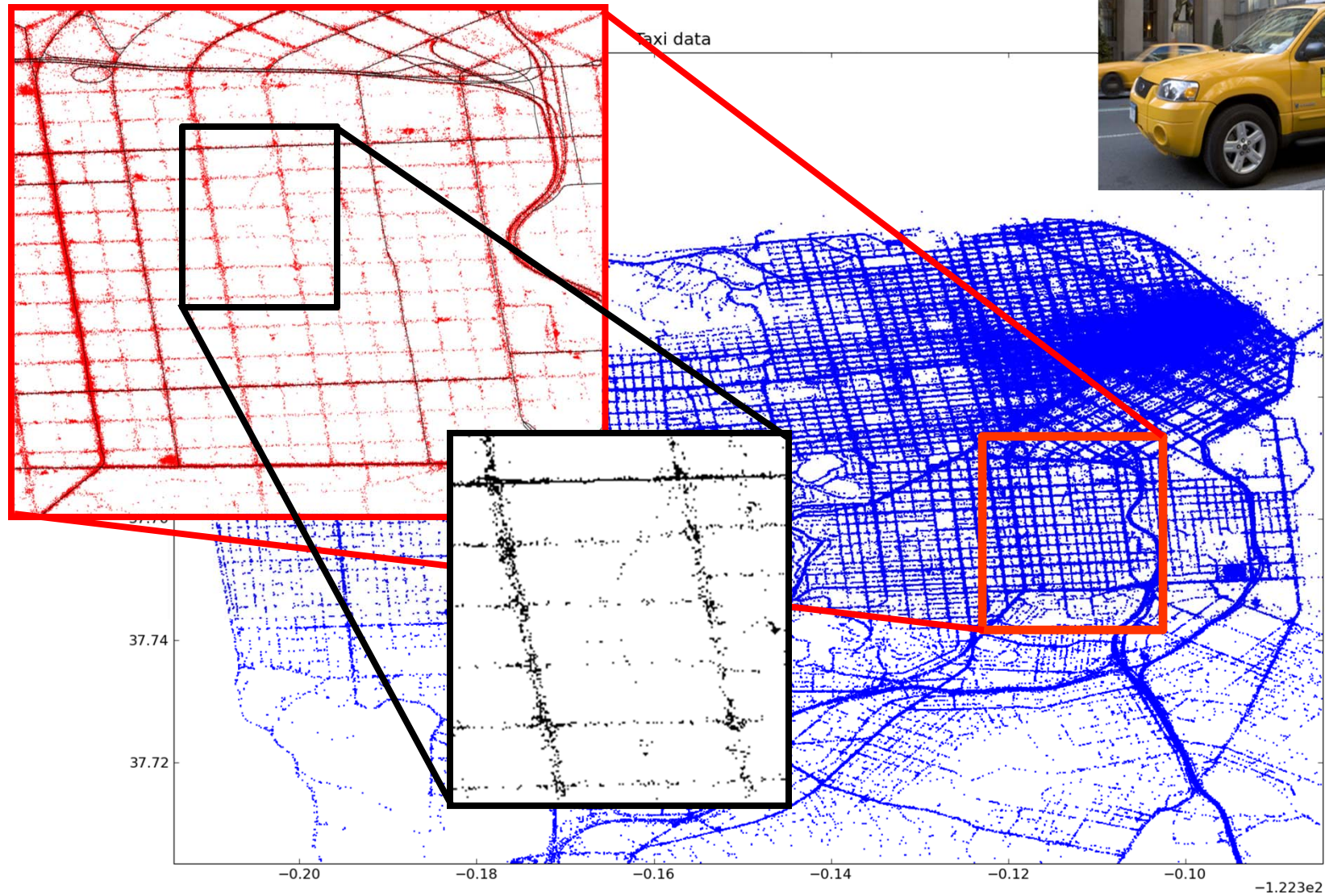
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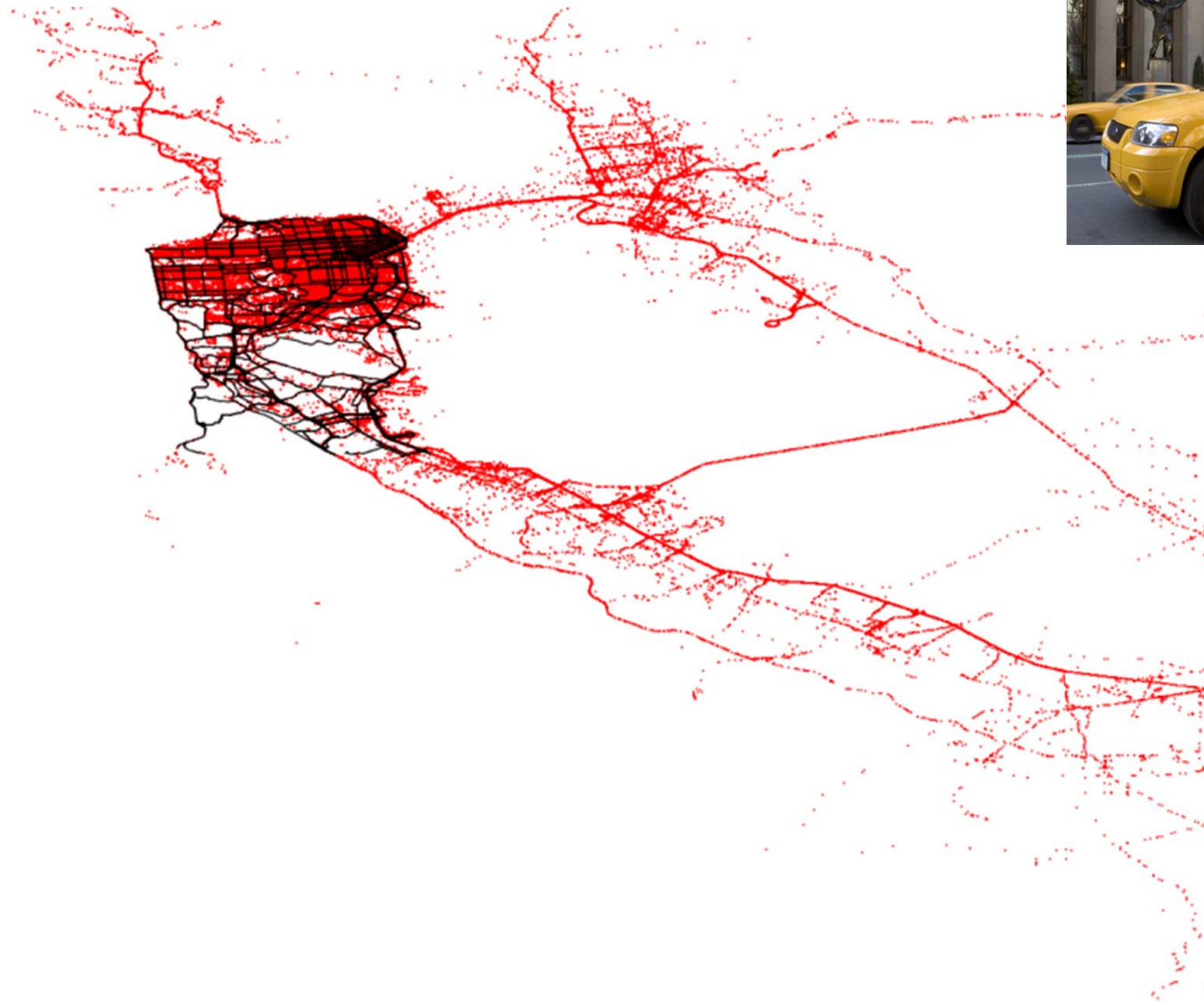
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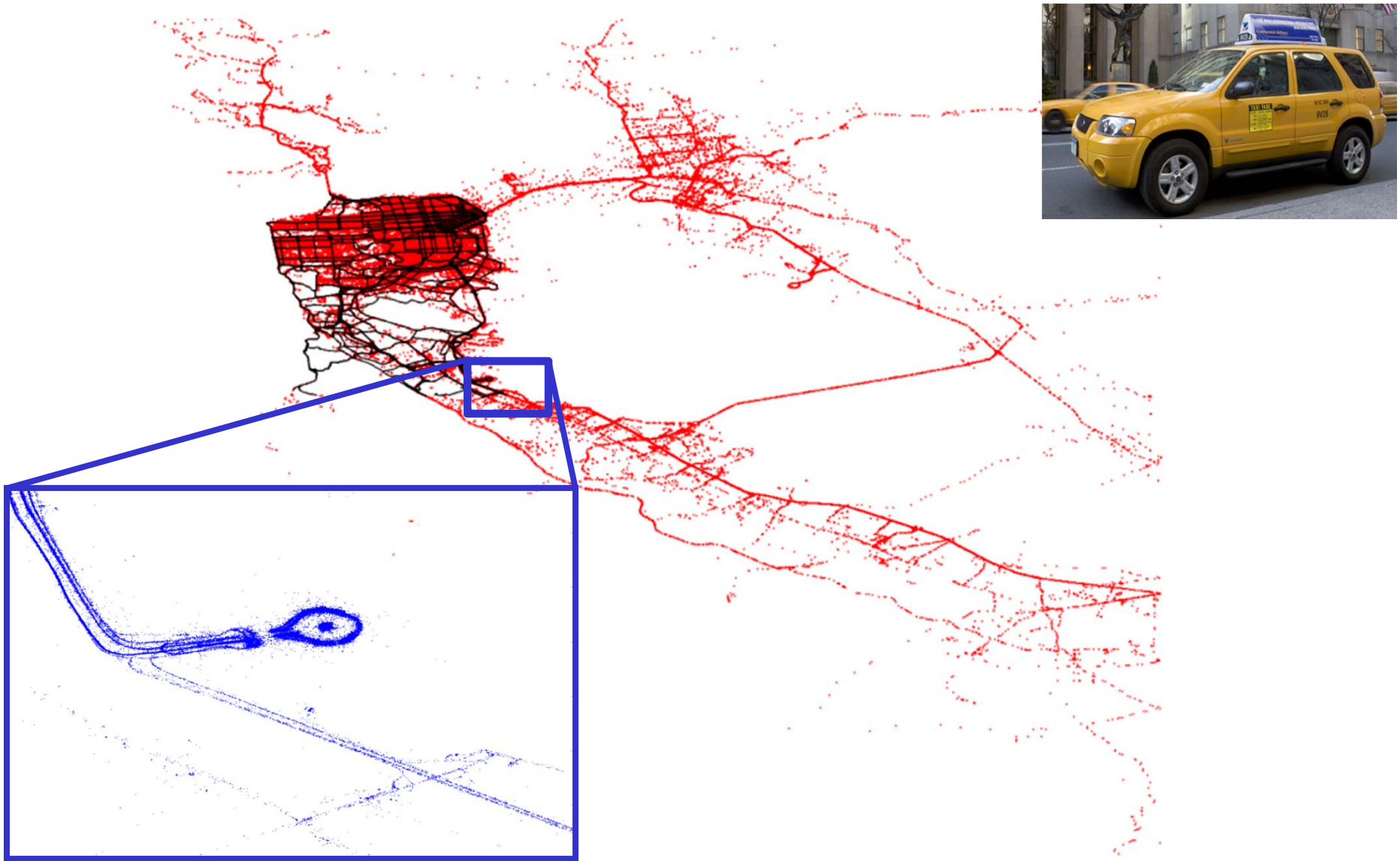


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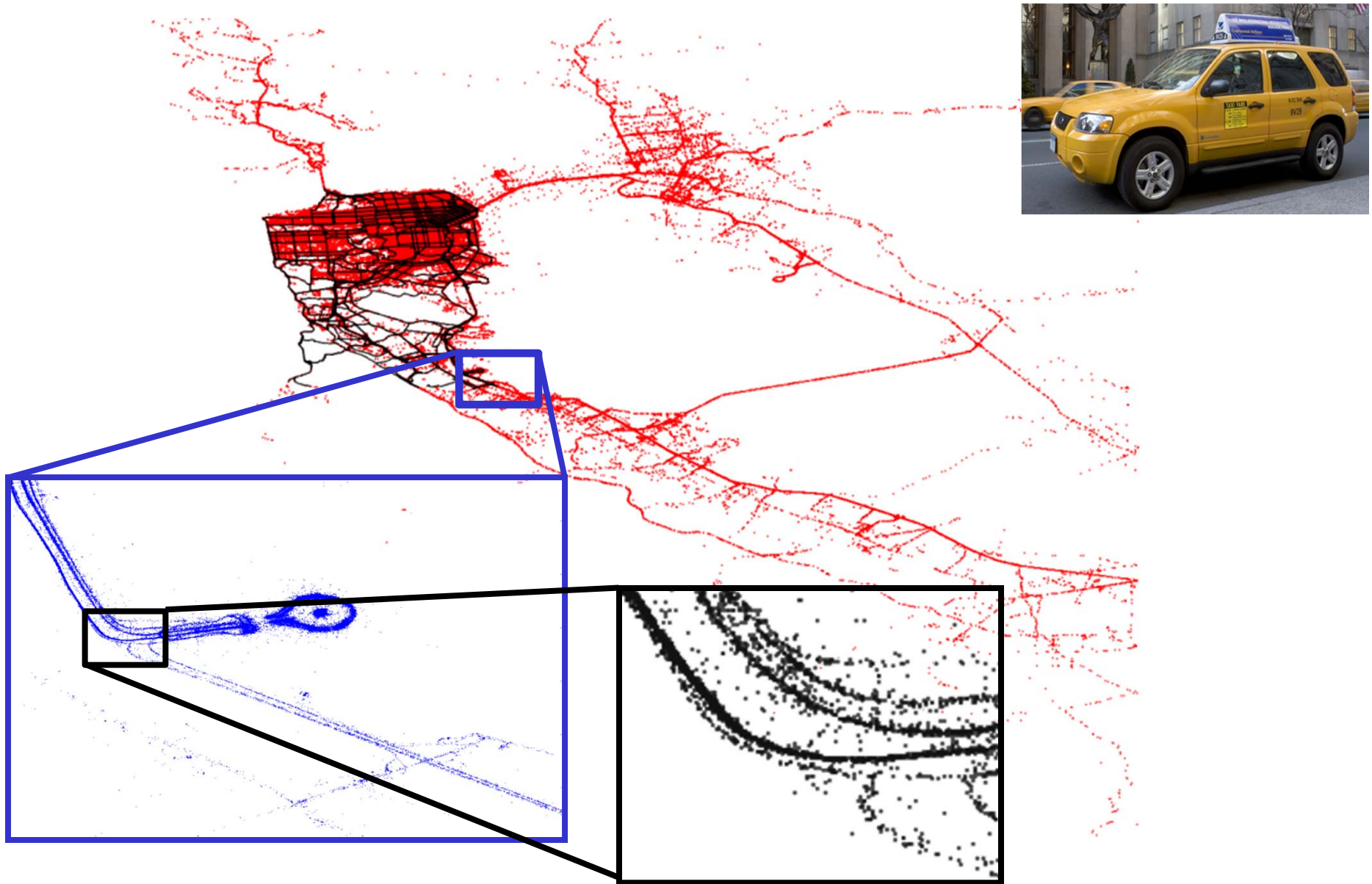




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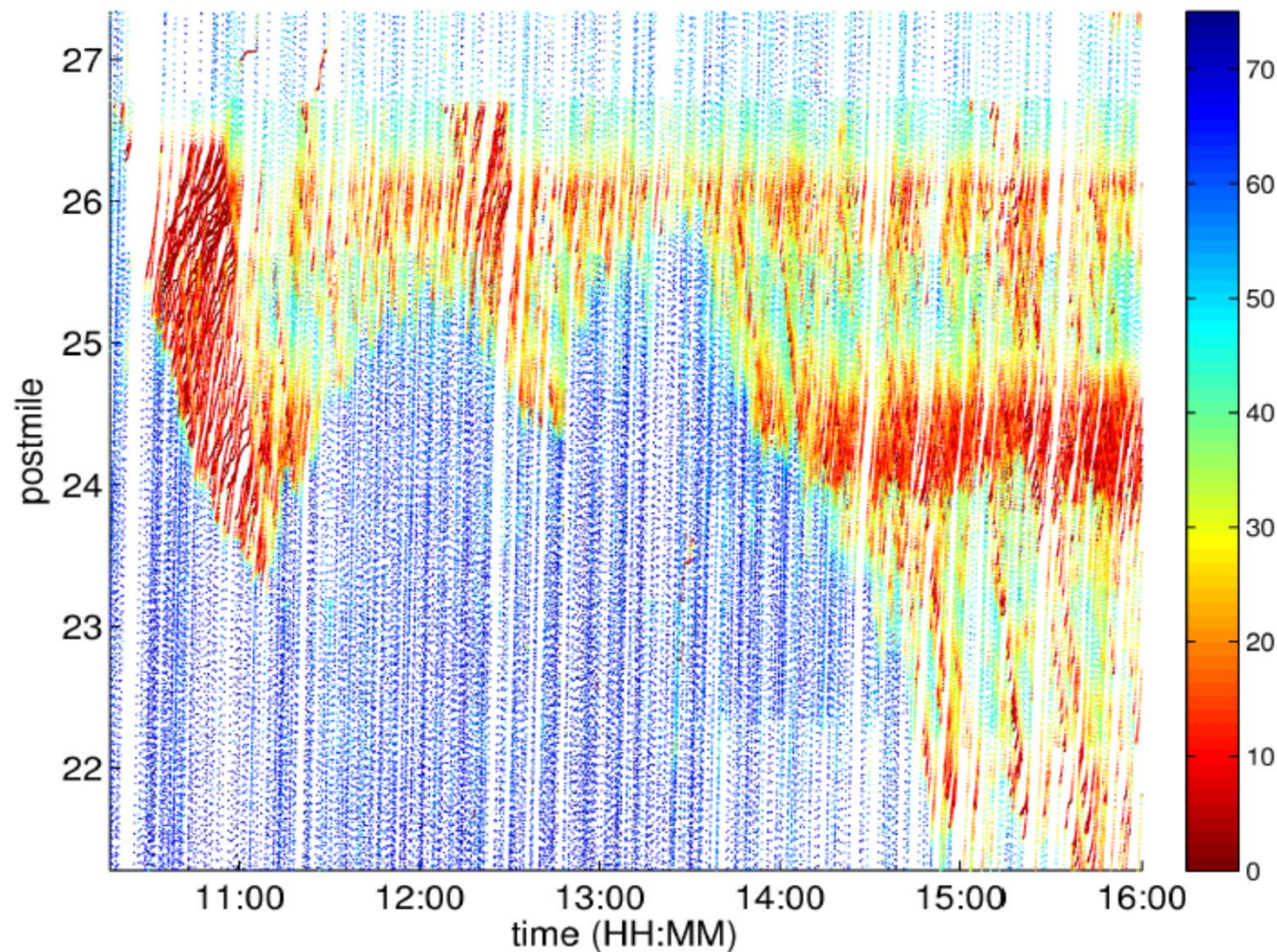




What it means to have GPS data at 2% penetration

Paradise for data assimilation starts at 2% penetration rate

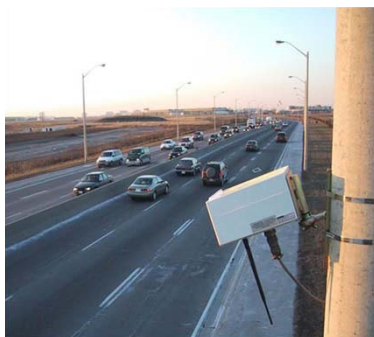
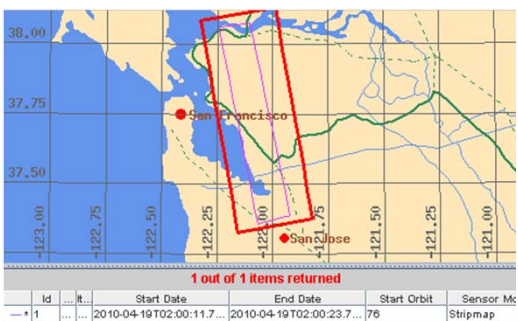
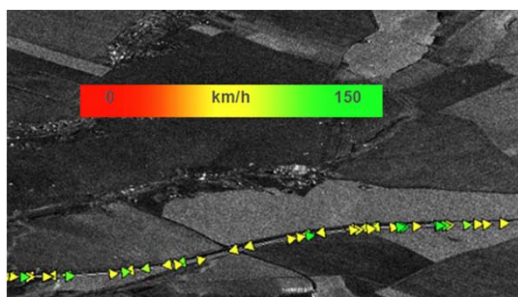
- However, it is rare to have such penetration uniformly (spatio temporally): thus algorithms need to work on decimated data





Data fusion at very large scale

The future lies in integration, mining and analytics of BIG DATA



From the sky or space

From the ground

From the vehicles

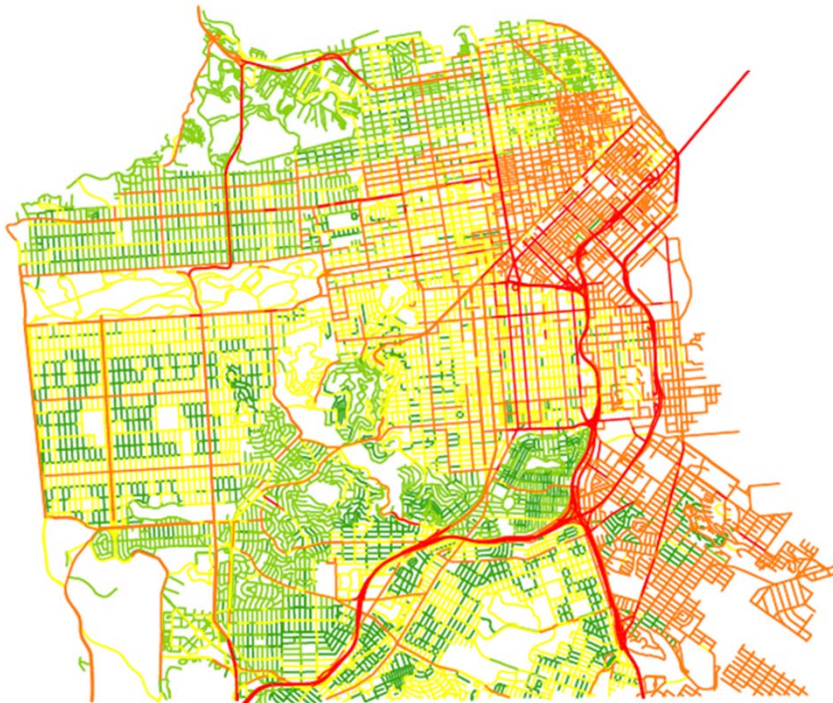


Traffic tomorrow: beyond traffic

e-Wellness project (E. Seto)

- Noise levels inferred from traffic: moving beyond the “average number of vehicles / year” paradigm: hour by hour noise levels.

Today: noise map (static)



Tomorrow: hourly noise map



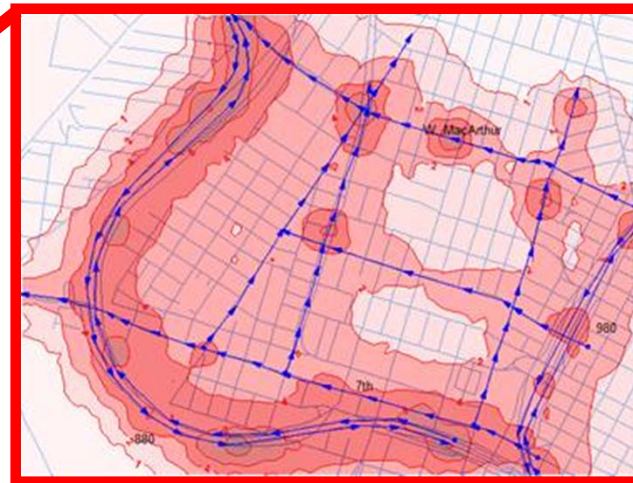
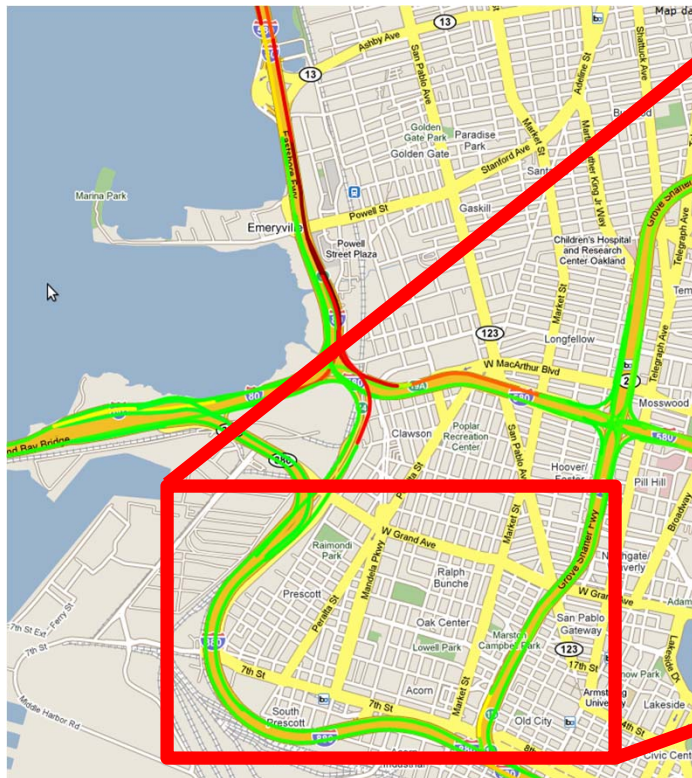


Traffic tomorrow: beyond traffic

e-Wellness project (E. Seto)

- Noise levels inferred from traffic: moving beyond the “average number of vehicles / year” paradigm: hour by hour noise levels.
- Emission levels inferred from traffic, using emission and atmospheric dispersion models. Next gen: sensor based.

Today: pollution map



Tomorrow: sensor based data



Courtesy NASA/DHS



Leveraging Hybrid Traffic Data

The public agencies will use novel types of data

- Unprocessed data (“dust”, “raw”) probe data
- Data can be used to enhance traffic information and management
- Procurement procedures unknown until 2010 in California
- Pricing schemes unknown until 2010 in California

california center for innovative transportation
UNIVERSITY OF CALIFORNIA, BERKELEY



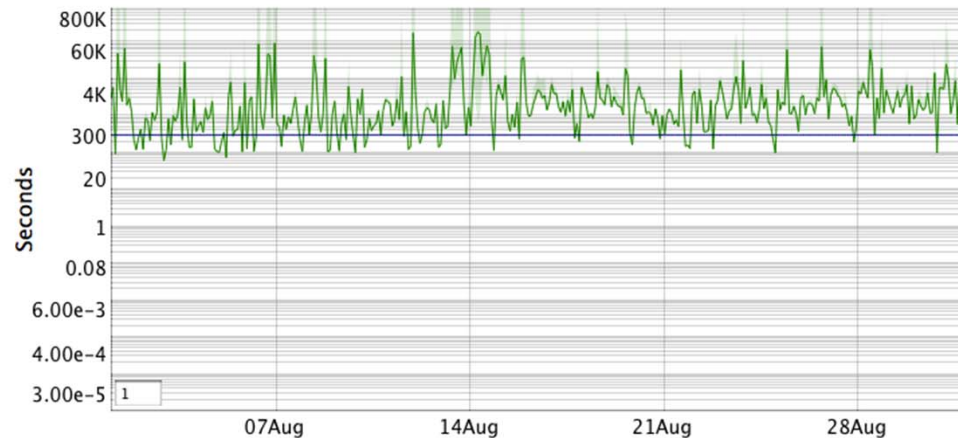
REQUEST FOR PROPOSALS:
UNAGGREGATED DATA PROCUREMENT

TRAFFIC DATA FOR I-15 & I-880 CORRIDORS



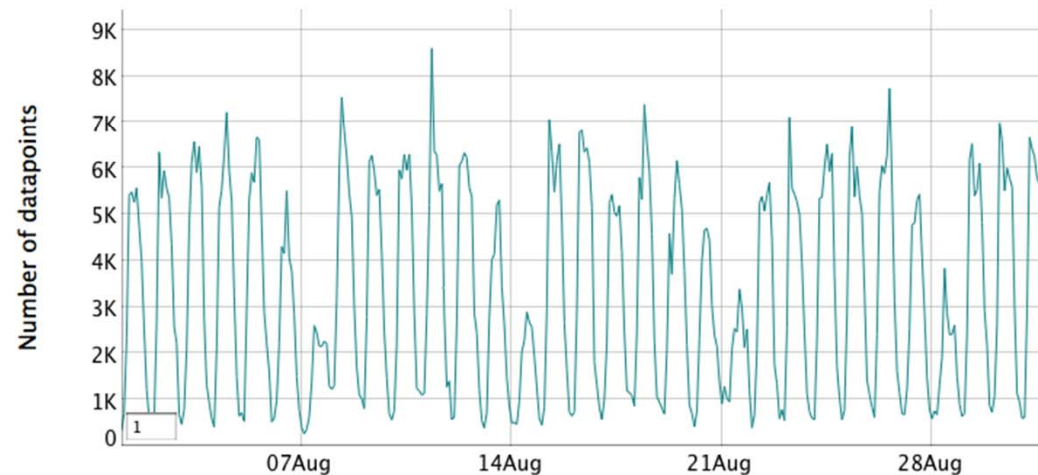
Hybrid Traffic Data – Data Quality Metrics

Transmission delay

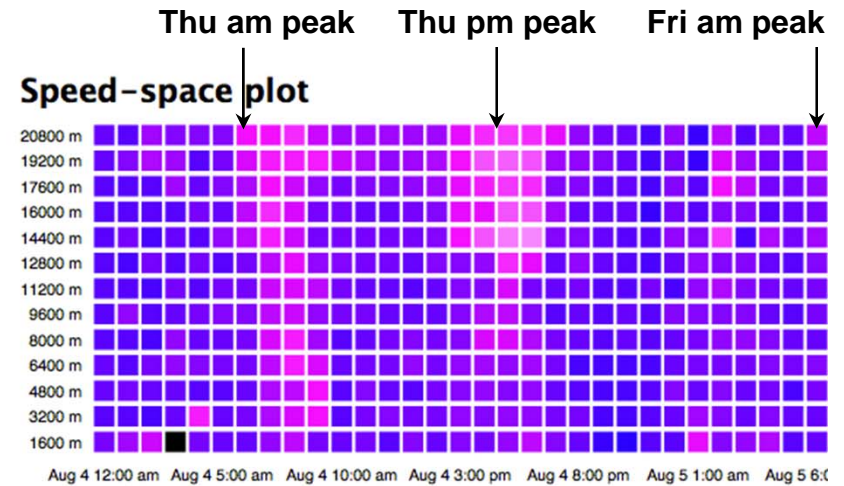


The amount of time that elapses between the device recording its location and the corresponding record being inserted into the database, in seconds. Line is the average; shaded area represents a standard deviation on either side of the average. Data aggregated every two hours.

Time coverage



The total number of data points at the time specified on the x-axis. Data aggregated every two hours.



Legend:
 0 20 40 60 80 ND

Provide public agencies with quality metrics, including:

- Latency
- Coverage
- Accuracy of tracks
- Volumes
- Etc.



Leveraging social networks



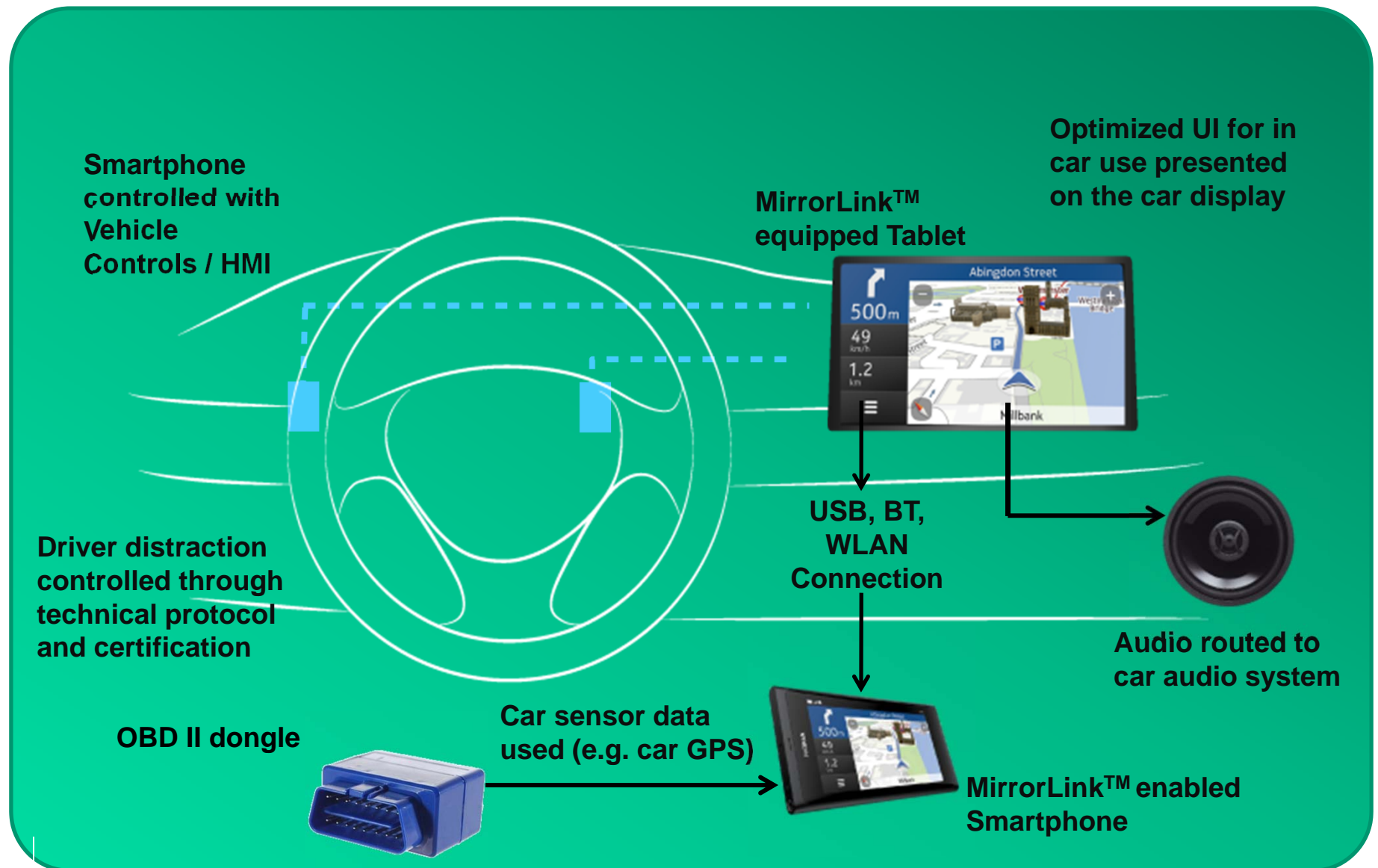
The Connected Corridor Consortium will rely on social networks

- Partnerships with major players in the ecosystem (e.g. Waze)
- Use of novel types of data (contextual, text based)
- Use of incentivization (not only through information)
- Behavioral response analysis





The future of connected cars (in the next 5 yrs)





MirrorLink™: the Next Big Opportunity

The MirrorLink™ standard was introduced in 2010

- MirrorLink™ transforms the smartphone into a car app platform
- Managed by the Car Connectivity Consortium (69 members)
- All major car manufacturers
- All major Android and Windows phone manufacturers

Car OEMs	
Mobile OEMs	
Tier-1 Suppliers	
Test Labs	

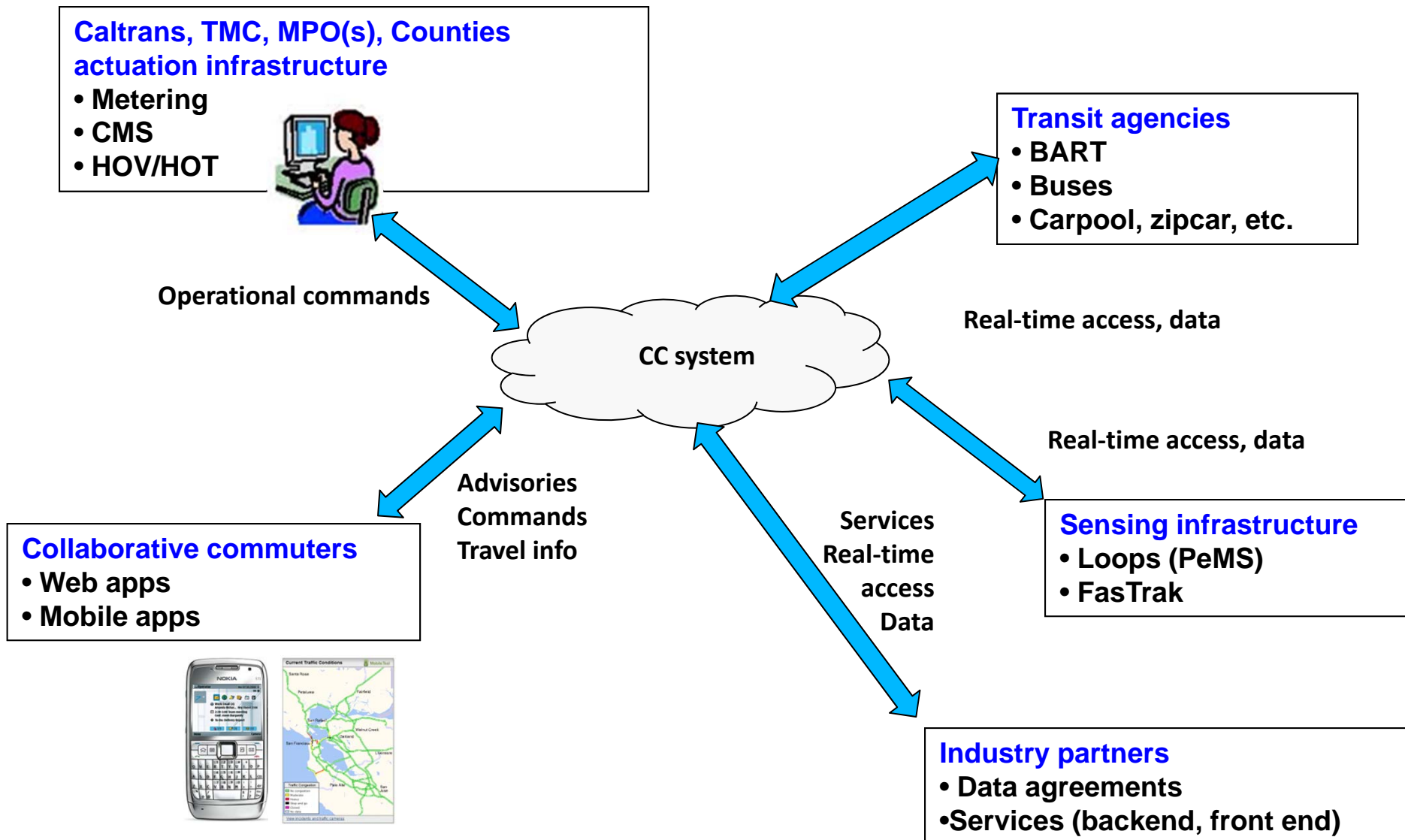


The next big thing in California: ICM



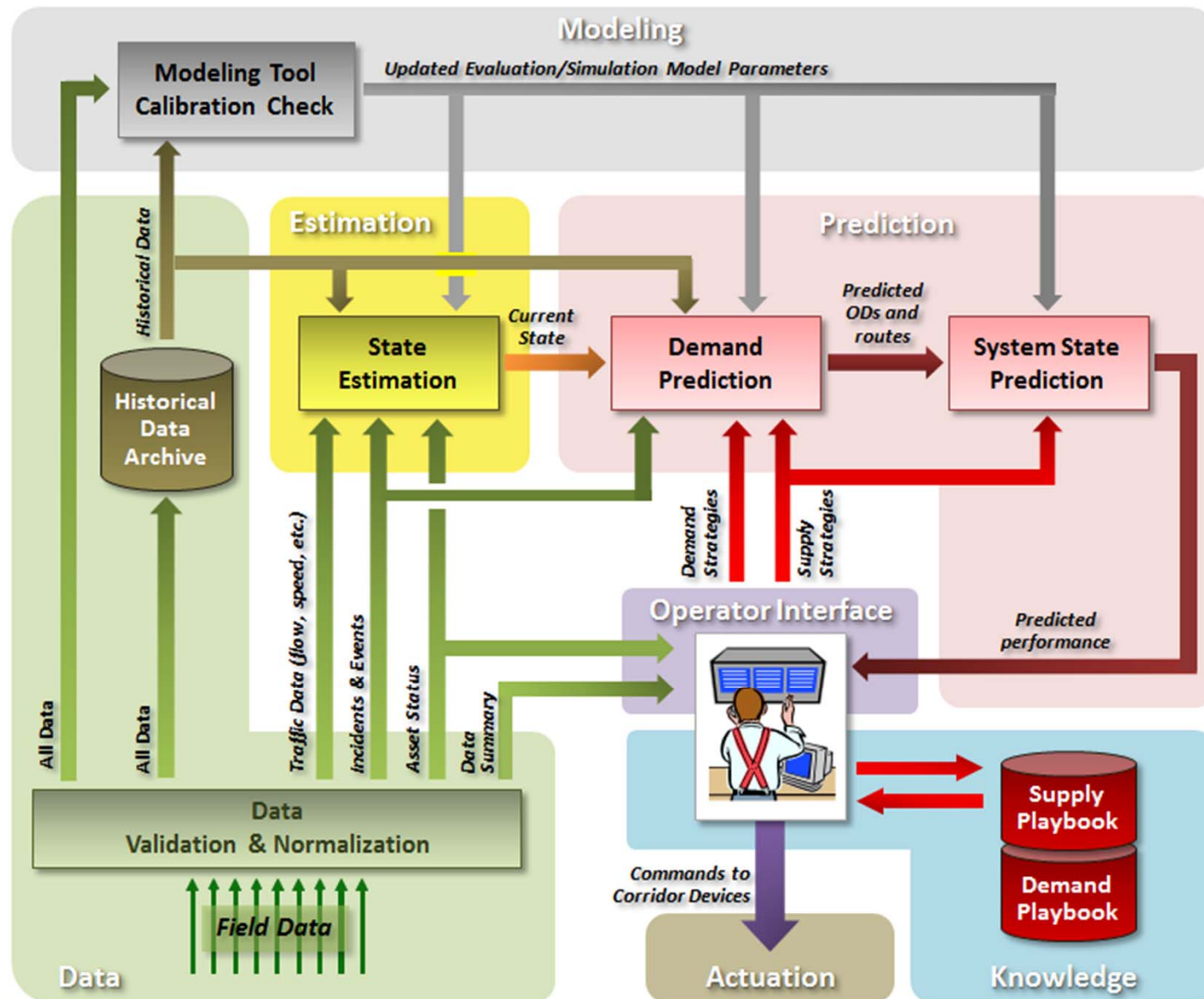


Institutional architecture for connected corridors



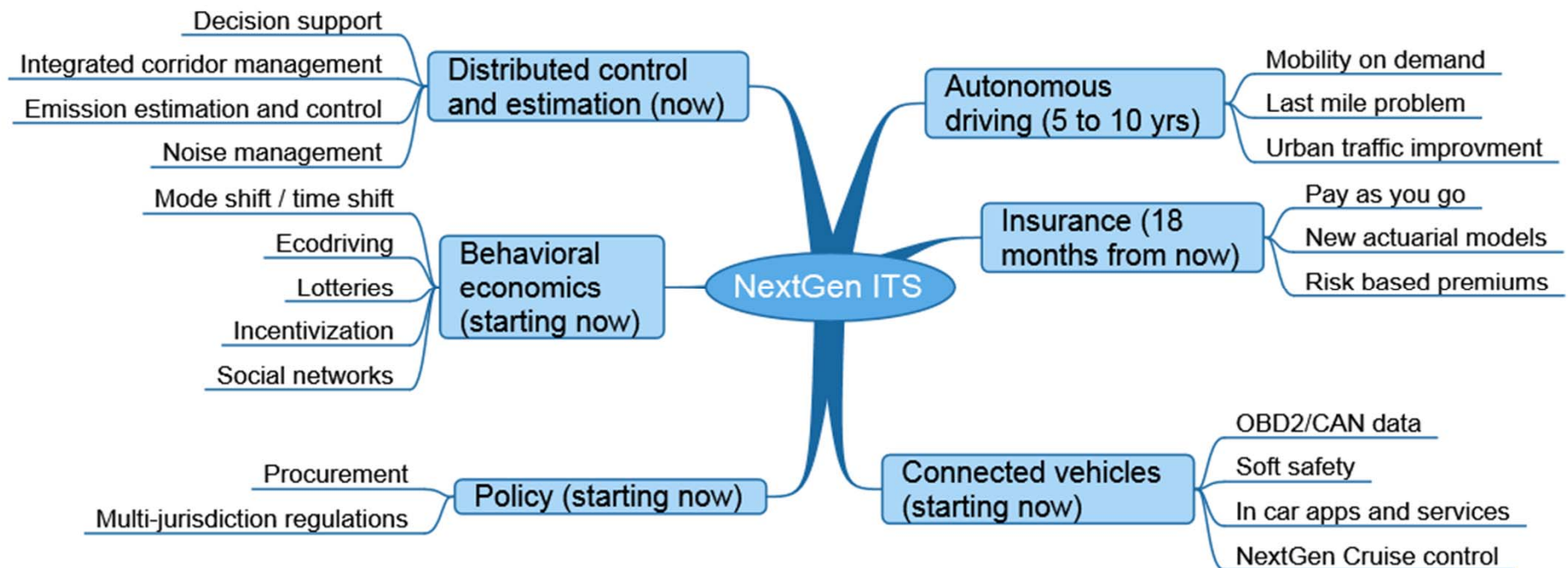


Building a decision support system



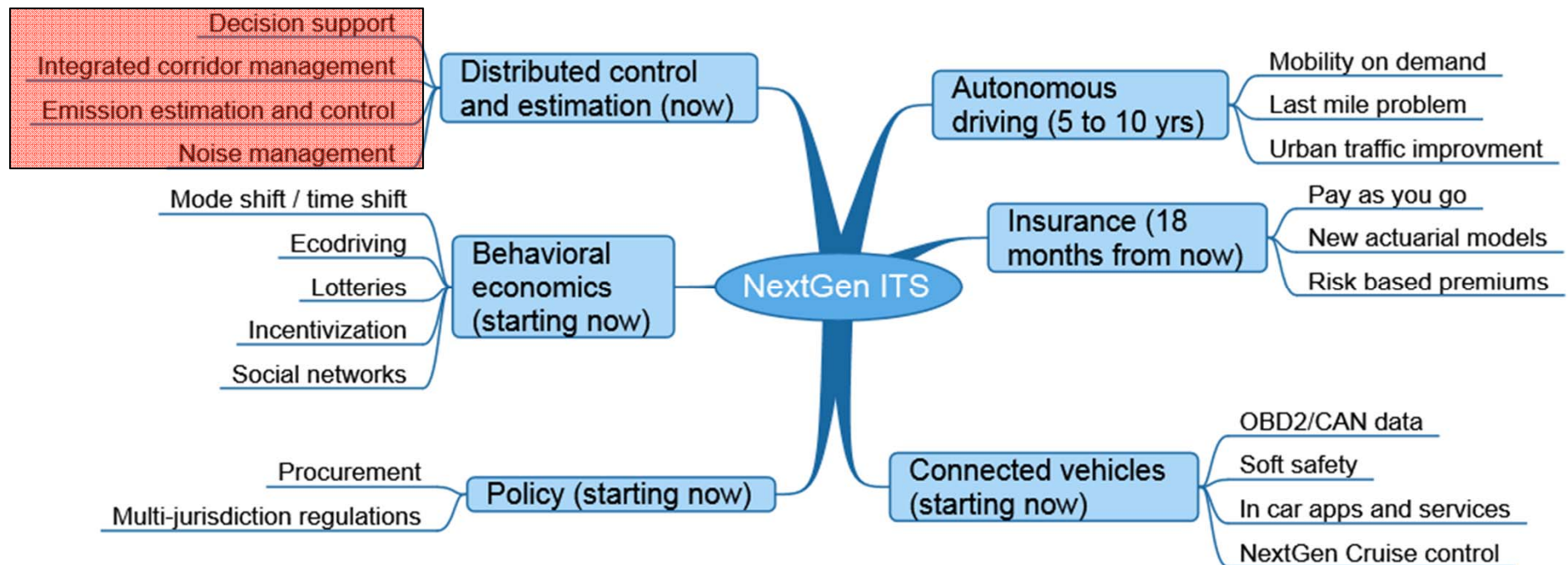


Next challenges of ITS





Next challenges of ITS





Themes covered in the workshop

Topics covered by the workshop

- **Bottlenecks (Gasser, Leclercq)**
- **Hamilton Jacobi (Claudel, Monneau, Costesque)**
- **Self organization (Christiani)**
- **PDE-ODE models, queuing (Della Monache, Arita, Tosin)**
- **Micro-macro (Rossi)**
- **Phase transition models, two phases (Blandin, Marcellini)**
- **Fundamental diagram (Zhang)**
- **Riemann solvers, junctions (Garavello, Cividini)**
- **Simulation (Briani)**
- **Second order models (Lebacque)**
- **Traffic monitoring (Work)**
- **Forecast and control (Canudas de Vit)**
- **Control (Canudas de Vit, Geroliminis, Hoogendoorn)**
- **Ramp metering (Gibbens)**
- **Traffic light control (Goettlich)**
- **Pedestrians (Borsche)**



Workshop schedule

March 2013	Wednesday 20	Thursday 21	Friday 22
8:30-9:00	Registration		
9:00-9:15	Keynote Opening Bayen	Goettlich	Zhang
9:15-9:45			
9:45-10:30	Lebacque	Work	Ledercq
10:30-11:00	coffee break		
11:00-11:45	Gasser	Canudas de Witt	Blandin
11:45-12:30	Gibbens	Geroliminis	Tosin Marcellini
12:30-14:30	lunch		
14:30-15:15	Monneau	Hoogendoorn	round table
15:15-16:00	Costeseque Cividini	Briani Rossi	
16:00-16:30	coffee break		
16:30-17:15	Claudiel	Garavello	
17:15-18:00	Borsche Cristiani	Delle Monache Arita	



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Successive workshops – Maiori, Italy, 2010



Workshop on Mathematical Foundations of Traffic



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- UCLA, USA, 2011



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