From low rank tensors for grids of multivariate functions to joint distributions of statistical models: selecting the relevant norm.

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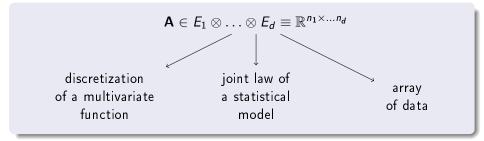
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Preliminaries

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CP and TT decomposition

CP decomposition

$$\mathbf{A} = \sum_{\alpha=1}^{r} \mathbf{x}_{\alpha} \otimes \mathbf{y}_{\alpha} \otimes \mathbf{z}_{\alpha} \quad \in \mathbb{R}^{n \times n \times n}$$
$$r_{cp}(\mathbf{A}) = \inf \left\{ r \in \mathbb{N} \mid \exists \mathbf{A} = \sum_{\alpha=1}^{r} \dots \right\}$$
$$3nr \text{ terms}$$

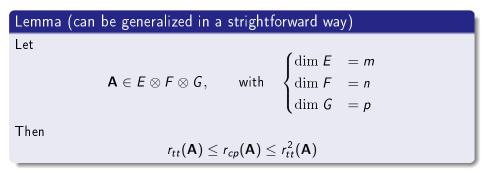
TT decomposition

$$\begin{split} \mathbf{A}[i, j, k] &= \mathbf{u}[i]. G[j]. \mathbf{v}[k] \\ r_{\mathrm{tt}} : \mathbf{u}_i \in \mathbb{R}^{1 \times r}, \quad G_j \in \mathbb{R}^{r \times r}, \quad \mathbf{v}_k \in \mathbb{R}^{r \times 1} \\ nr^2 + 2nr \text{ terms} \end{split}$$

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- Development on a basis and reorganisation for *r_c*
- Development with diagonal G matrix

for
$$r_{cp} \leq r_{tt}^2$$

for $r_{tt} \leq r_{cp}$

Example

For example, if r = 2

$$\begin{split} \mathbf{A} &= \mathbf{x}_1 \otimes \mathbf{y}_1 \otimes \mathbf{z}_1 + \mathbf{x}_2 \otimes \mathbf{y}_2 \otimes \mathbf{z}_2 \\ \text{with} \qquad \mathbf{x}_1 &= \left(x_i^{(1)} \right)_i, \quad \mathbf{y}_1 = \left(y_j^{(1)} \right)_j, \dots \end{split}$$

Then

$$\begin{aligned} x_i^{(1)} y_j^{(1)} z_k^{(1)} + x_i^{(2)} y_j^{(2)} z_k^{(2)} &= \left(x_i^{(1)} \ x_i^{(2)} \right) \begin{pmatrix} y_j^{(1)} z_k^{(1)} \\ y_j^{(2)} z_k^{(2)} \end{pmatrix} \\ &= \left(x_i^{(1)} \ x_i^{(2)} \right) \begin{pmatrix} y_j^{(1)} \ 0 \\ 0 \ y_j^{(2)} \end{pmatrix} \begin{pmatrix} z_k^{(1)} \\ z_k^{(2)} \end{pmatrix} \\ &= \mathbf{u}_i . G_j . \mathbf{v}_k \end{aligned}$$

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TT rank is a tensor property (whatever the basis), and

$$u_{i}.G_{j}.v_{k} = u_{i}.(PP^{-1}).G_{j}.(QQ^{-1}).v_{k}$$

= $(u_{i}.P)(P^{-1}.G_{j}.Q)(Q^{-1}.v_{k})$
= $u'_{i}G'_{j}v'_{k}$

Simultaneously diagonalizable matrices

• $(G_j)_{1 \le j \le n}$ is a set of $r \times r$ diagonalizable matrices

Then, it is equivalent that

- $\forall (i,j), \quad G_i G_j = G_j G_i$
- There exists a basis P such that each G_j is diagonal in this basis

Let $\mathbf{A} \in \mathbb{R}^{m \times n \times p}$ with $a_{ijk} = u_i.G_j.v_k$,

Lemma

- $r_{\rm tt} \leq r_{\rm cp} \leq r_{\rm tt}^2$
- $r_{cp} = r_{tt}$ iff $(G_j)_j$ simultaneously diagonalisable

Take home message: very simple

If a tensor has low CP rank, then it has low TT rank.

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A tensor as discretisation of a multivariate function

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Multivariate function (here d=2 for simplicity)

Let

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}$$

Three implementations

$$f \longrightarrow f \in \mathcal{H}$$

 $f \longrightarrow f(x, y) = x^2 + 2xy + y^2$
 $f(x_i, y_i) = M[i, j]$

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Cartesian Mesh

1D mesh

$$\mathbf{x} \in \mathbb{R}^{n}, \quad \forall i, \quad x_{i} \in \mathbb{R}$$
$$\mathbf{x} = (x_{1}, \dots, x_{n}) \quad \text{with} \quad x_{1} < \dots < x_{n}$$
$$\mathscr{D}(f, \mathbf{x}) = (f(x_{1}), \dots, f(x_{n}))$$
$$\mathcal{H} \times \mathcal{M} \xrightarrow{\mathscr{D}} \mathbb{R}^{n}$$

2D Cartesian Mesh

- Let us consider 2 meshes \mathbf{x}, \mathbf{y} in \mathbb{R} of respective sizes m, n.
- Then $x \otimes_m y$ in \mathbb{R}^2 can be defined as

$$\mathbf{x} \otimes_{\mathbf{m}} \mathbf{y} = \begin{pmatrix} (x_1, y_1) & (x_1, y_2) & \dots & (x_1, y_n) \\ (x_2, y_1) & (x_2, y_2) & \dots & (x_2, y_n) \\ \vdots & \vdots & & \vdots \\ (x_m, y_1) & (x_m, y_2) & \dots & (x_m, y_n) \end{pmatrix}$$

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Product of functions: two variables

•
$$(fg)(x) = f(x)g(x)$$

• $(f \otimes g)(x, y) = f(x)g(y)$

Discretisation of product of functions

•
$$\mathscr{D}(fg, \mathbf{x}) = \mathscr{D}(f, \mathbf{x}) \odot \mathscr{D}(g, \mathbf{x})$$

• $\mathscr{D}(f \otimes g, \mathbf{x} \otimes_{\mathsf{m}} \mathbf{y}) = \mathscr{D}(f, \mathbf{x}) \otimes \mathscr{D}(g, \mathbf{y})$

Consequence

If $u = f \otimes g$ [u(x, y) = f(x)g(y), separation of variables], the matrix $\mathscr{D}(u, \mathbf{x} \otimes_m \mathbf{y})$ of discretization of u on mesh $\mathbf{x} \otimes_m \mathbf{y}$ has rank one too.

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Generalization is straightforward ...

$$\begin{split} \mathscr{D}\left(\prod_{\mu}f_{\mu}\,,\,\mathbf{x}
ight) &= igodot \mathscr{D}(f_{\mu},\mathbf{x}) \ \mathscr{D}\left(\bigotimes_{\mu}f_{\mu}\,,\,\otimes_{\mu}^{(m)}\mathbf{x}_{\mu}
ight) &= \bigotimes_{\mu}\mathscr{D}(f_{\mu},\mathbf{x}_{\mu}) \end{split}$$

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An elementary lemma (can be extended to d > 2)

Let

$$\begin{array}{ccc} \mathcal{H} \otimes \mathcal{H} & \xrightarrow{\mathscr{D}} & \mathbb{R}^{m \times n} \\ \psi & \longrightarrow & \mathscr{D}(\psi, \mathbf{x} \otimes_{\mathsf{m}} \mathbf{y}) \end{array}$$

Let (rank r CP-decomposition)

$$\psi = \sum_{lpha=1}^{r} \mathbf{u}_{lpha} \otimes \mathbf{v}_{lpha} \qquad ext{with} \quad \mathbf{u}_{lpha}, \mathbf{v}_{lpha} \in \mathcal{H}$$

Then

$$\forall m, n, \quad r_{\sf cp}\left(\mathscr{D}(\psi, \, {\sf x} \otimes_{\sf m} {\sf y})
ight) \leq r_{\sf cp}(\psi)$$

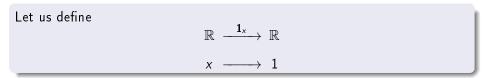
As consequence ...

$$\forall m, n, \quad r_{\mathsf{tt}} \left(\mathscr{D}(\psi, \mathbf{x} \otimes_{\mathsf{m}} \mathbf{y}) \right) \leq r_{\mathsf{cp}}(\psi)$$

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Image: A matrix

Discretization of polynomials (1/2)



Bivariate polynomial

$$P(x,y) = x^2 + 2xy + y^2$$

Then

$$P = x^2 \otimes \mathbf{1}_y + 2 x \otimes y + \mathbf{1}_x \otimes y^2$$

and

 $r_{\rm cp}(P) \leq 3$

and

$$\forall m, n \in \mathbb{N}, \quad r_{\mathsf{tt}}(\mathscr{D}(P, \mathbf{x} \otimes_{\mathsf{m}} \mathbf{y})) \leq r_{\mathsf{cp}}(\mathscr{D}(P, \mathbf{x} \otimes_{\mathsf{m}} \mathbf{y})) \leq 3$$

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Discretization of polynomials (2/2)

Any polynomial

$$\mathsf{P}(x_1,\ldots,x_d) = \sum_{\mathbf{n}} a_{n_1\ldots n_d} x_1^{n_1}\ldots x_d^{n_d}, \qquad N \text{ terms}$$

Then

$$\mathsf{P} = \sum_{\mathsf{n}} a_{n_1 \dots n_d} x_1^{n_1} \otimes \dots \otimes x_d^{n_d}, \quad \mathsf{CP} \mathsf{ rank} = N$$

and

 $\forall \ m_1, \ldots, m_d \in \mathbb{N}, \quad r_{\mathsf{tt}} \left(\mathscr{D}(\mathsf{P}, \mathsf{x}_1 \otimes_{\mathsf{m}} \ldots \otimes_{\mathsf{m}} \mathsf{x}_d) \right) \leq N$

• m_{μ} is the size of the Cartesian Grid for mode μ .

a remark

In general,
$$N = \prod_{\mu} n_{\mu}$$

 \implies rank is high if d is significant

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Extension to continuous functions

Stone-Weierstrass theorem

- $C(S) = \{f : S \longrightarrow \mathbb{R}, f \text{ continuous}\}$
- $A \subset C(S)$ s.t. $f, g \in A \Rightarrow fg \in S$
- $x \neq y \implies \exists f \in A : f(x) \neq f(y)$

Then

$\forall \epsilon > 0, \quad \forall f \in C(S), \quad \exists \varphi \in A : \forall x \in S, \quad |f(x) - \varphi(x)| < \epsilon$

- Any continuous function can be approximated with norm ℓ^∞ as close as wished by a polynomial, i.e. a low rank function
- This is automatially transported to approximation by low rank discretization on Cartesian grids
- And from CP to TT approximation (for working with TT toolbox)
 A well developed theory has been elaborated for l² norm as well (development on basis of orthogonal polynomials, leading to Tucker approximations).

There is a sound and standard algebraic theory for showing that tensors as discretization of multivariate functions are

- exactly low rank for polynomials
- well approximated by low rank tensors (CP, TT, Tucker) for continuous functions

Some details still deserve attention

• Better understanding of the link between CP et TT decomposition

- Why CP is numerically unstable sometimes and TT not ?
- at which boundaries ?
- is it expandable to non Cartesian meshes?

A tensor as a joint law

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Setting

- Let us have a discrete set Λ
- d random variables X_{μ} with values in Λ

Define

$$\mathbf{T}[i_1,\ldots,i_d]=t_{i_1\ldots i_d}\propto \mathbb{P}(X_1=i_1,\ldots,X_d=i_d)$$

• **T** is a d-modes tensor with elements ≥ 0

Classical examples

- Ising model
- Graphical models
- ...

Definition

In statistical physics, and statistical modeling, one is led to compute

$$Z(\mathsf{T}) = \sum_{i_1} \dots \sum_{i_d} t_{i_1 \dots i_d}$$

• requires n^d additions, with $d > 10^3$ often see Novikov & al. (2014) for large d.

Alexander Novikov & al. (2014) - Putting MRFs on a Tensor Train. Proceedings of the 31 st International Conference on Machine Learning, Beijing, China.

When does it work?

When T is written in TT format

$$t_{i_1...i_d} = G_1(i_1) \times \ldots \times G_\mu(i_\mu) \times \ldots \times G_d(i_d)$$

with $G_{\mu}(i_{\mu}) \in \mathbb{R}^{r_{\mu-1} imes r_{\mu}}$. Then, if $B_{\mu} = \sum_{i_{\mu}} G_{\mu}(i_{\mu})$

$$Z(\mathbf{T}) = B_1 B_2 \dots B_d$$

(Novikov & al., 2014)

When **T** has low CP-rank

$$T=x\otimes y\otimes z+x'\otimes y'\otimes z'$$

Observation

• All terms in T are ≥ 0 Then

$$Z(\mathsf{T}) = \|\mathsf{T}\|_1$$
 (norm ℓ^1)

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Variational approach

General approach

- a quantity $f(\mathbf{T})$ on a tensor (like $Z(\mathbf{T})$) is difficult to compute in general, but easy in a (closed) subset $\mathscr{A} \subset \mathbb{R}^{n_1 \times \ldots \times n_d}$
- Then, one computes $\widehat{\mathsf{T}}\in\mathscr{A}$ such that, for a selected distance δ

 $\delta(\mathsf{T}, \widehat{\mathsf{T}})$ is minimal

• and approximates

$$f(\mathbf{T}) \approx f(\widehat{\mathbf{T}})$$



Setting the problem

- given $A \in \mathbb{R}^{m \times n}$
- find \widehat{A} with rank $(\widehat{A}) = r$
- such that $\|A \widehat{A}\|_1$ minimal

State of the art

- Difficulty: it has been shown to be NP-hard (Gillis & Vavasis, 2015)
- Available algorithm with "provable approximation guarantees" (Song, Woodruff & Zhong, 2018)

What about tensors?

- Let $\mathbf{A} \in E \otimes F \otimes G$
- Let A_E be its first matricization

$$F \otimes G \xrightarrow{A_E} E$$

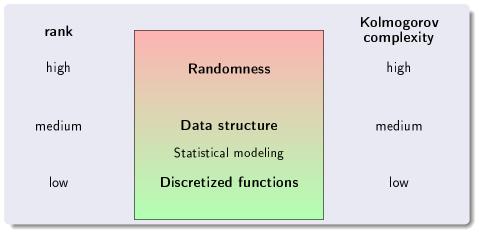
• Then $||A_E||_1 = ||\mathbf{A}||_1$

Proposed heuristics

for all matricizations A of A do computes the best rank one approximation A_{best} of A with norm ℓ^1 computes $\delta(A) = ||A - A_{best}||$ select A such that $\delta(A)$ is minimal computes $Z(A_{best})$ (easy) return $Z(A_{best}) \approx Z(\mathbf{A})$

- The theory behind best low rank approximation of a tensor as joint distribution is not as mature than links between multilinear algebra, PDE, functional analysis
- A difficulty is that a wider diversity of norms is relevant
 - Kullback-Leibler for mutual information
 - ℓ^1 for partition function
 - ...

which do not rely on Euclidean geometry



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