

On abnormal length minimizers in sub-Riemannian groups

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Journée McTAO
Dijon, December 4-5, 2017

From collaborations with
Hakavuori [Inventiones, 2016],
Montgomery, Ottazzi, Pansu, Vittone [Annales de l'IHP, 2016].

- geodesics in SR groups
normal & abnormal curves.
- Sard-type problems
abnormal varieties.
- Limits of geodesics
blow-ups & blow-downs.

Sub-Riemannian geometry

- M manifold
- Δ bracket-generating subbundle of the tangent bundle of M
- $\|\cdot\|$ norm on Δ coming from a smoothly varying scalar product

The **SR distance** is

$$d_{SR}(p, q) = \inf \left\{ \int \|\dot{\gamma}\| \mid \gamma : [0, 1] \xrightarrow{AC} M, \quad p \rightsquigarrow q, \quad \dot{\gamma} \in \Delta \right\}$$

In this talk, the structure will be invariant under left translations with respect to a **group** structure.

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In this talk, the structure will be invariant under left translations with respect to a **group** structure.

Polarized groups

G connected Lie group with Lie algebra \mathfrak{g} .

$V \subseteq \mathfrak{g}$ linear subspace, called *polarization*.

For $u \in L^2([0, 1], V)$, let γ_u be the curve in G that solves

$$\frac{d\gamma}{dt}(t) = (dL_{\gamma(t)})_{1_G} u(t), \quad (\text{ODE})$$

with initial condition $\gamma(0) = 1_G$.

If $\gamma : [0, 1] \rightarrow G$ is an AC curve that solves the ODE for some $u \in L^2([0, 1], V)$, then γ is said *horizontal* with respect to V and $u = u_\gamma$ is its *control*.

γ is horizontal \iff the derivatives of γ lie in the left-invariant subbundle Δ that coincides with V at the origin 1_G .

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The *endpoint map starting at 1_G with controls in V* is the map

$$\begin{aligned} \text{End} : L^2([0, 1], V) &\rightarrow G \\ u &\mapsto \gamma_u(\mathbf{1}). \end{aligned}$$

Differential of Endpoint map and its image

Theorem

The endpoint map $\text{End} : u \mapsto \gamma_u(1)$ is smooth and

$$d\text{End}_u v = (dR_{\gamma_u(1)})_{1_G} \int_0^1 \text{Ad}_{\gamma_u(t)} v(t) dt, \quad \forall u, v \in L^2([0, 1], V),$$

where $\text{Ad}_g : \mathfrak{g} \rightarrow \mathfrak{g}$ is $\text{Ad}_g = (C_g)_*$ with $C_g h = ghg^{-1}$.

Corollary

$$\text{Im}(d\text{End}_u) = (dR_{\gamma_u(1)})_{1_G} (\text{span}\{\text{Ad}_{\gamma_u(t)} V : t \in [0, 1]\}).$$

Sketch of the proof

Easier in matrix groups, so $\text{Ad}_B(A) = BAB^{-1}$.

$$\sigma_1(t) := \left. \frac{d}{d\epsilon} \gamma_{u+\epsilon v}(t) \right|_{\epsilon=0}$$

$$\sigma_2(t) := \int_0^t \text{Ad}_{\gamma(s)}(v(s)) \, ds \cdot \gamma(t)$$

$\implies \sigma_1$ and σ_2 satisfy the ODE

$$\frac{d\sigma_i}{dt}(t) = \gamma(t) \cdot v(t) + \sigma_i(t) \cdot u(t),$$

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Extended Endpoint map

Fix a Euclidean norm $\|\cdot\|$ on V .

Then $\Omega := L^2([0, 1]; V)$ is normed:

$$\|u\| := \left(\int_0^1 \|u(t)\|^2 dt \right)^{\frac{1}{2}}.$$

The *extended endpoint map* is

$$\begin{aligned} \widetilde{\text{End}} : \Omega &\rightarrow G \times \mathbb{R} \\ u &\mapsto \left(\gamma_u(1), \frac{1}{2} \|u\|^2 \right). \end{aligned}$$

We are interested in those curves that start from 1_G and reach a given point $p = \gamma_u(1)$ minimizing the *energy* $\frac{1}{2} \|u\|^2$.

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Consequence of minimizing energy

u is a minimizer for the energy

$\iff \widetilde{\text{End}}$ not open at u

\implies [Open Mapping Theorem] $d\widetilde{\text{End}}$ is not surjective at u

$\iff \exists (\xi, \xi_0) \in (T_{\text{End}(u)}\mathbf{G})^* \times \mathbb{R} \setminus \{(0, 0)\}$:

$$\langle (\xi, \xi_0), d\widetilde{\text{End}}_u(v) \rangle = 0, \quad \forall v \in \Omega.$$

Formula:

$$d\widetilde{\text{End}}_u : \Omega \rightarrow T_{\widetilde{\text{End}}(u)}(\mathbf{G} \times \mathbb{R}) = T_{\text{End}(u)}\mathbf{G} \times \mathbb{R} = (dR_{\gamma_u(1)})_{1_G} \mathfrak{g} \times \mathbb{R}$$
$$v \mapsto \left((dR_{\gamma_u(1)})_{1_G} \int_0^1 \text{Ad}_{\gamma_u(t)}(v(t)) dt, \langle u, v \rangle \right).$$

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Consequence of minimizing energy

u is a minimizer for the energy

\implies

$\exists \lambda \in \mathfrak{g}^*$ and $\xi_0 \in \mathbb{R}$ such that $(\lambda, \xi_0) \neq (0, 0)$ and

$$\lambda \left(\int_0^1 \text{Ad}_{\gamma_u(t)} v(t) dt \right) = \xi_0 \langle u, v \rangle, \quad \forall v \in \Omega. \quad (1)$$

Two cases

- (1) $\xi_0 \neq 0$. *normal curve*
- (2) $\xi_0 = 0$. *abnormal curve*

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Normal curves

First case: May assume $\xi_0 = 1$.

$$\langle u, v \rangle = \lambda \left(\int_0^1 \text{Ad}_{\gamma_u(t)} v(t) dt \right).$$

(e_1, \dots, e_r) o.n. basis for $(V, \|\cdot\|)$.

In this basis, the controls are

$$\begin{aligned} u_i(t) &= \langle u, \delta_t e_i \rangle \\ &= \lambda \int_0^1 \text{Ad}_{\gamma_u(s)}(\delta_t e_i) ds \\ &= \lambda(\text{Ad}_{\gamma_u(t)}(e_i)). \end{aligned}$$

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Normal curves

γ is a normal curve

$\iff \gamma$ satisfies the *normal equation* (or geodesic equation):

$\exists \lambda \in \mathfrak{g}^*$:

$$\dot{\gamma}(t) = \sum_{i=1}^r \lambda(\text{Ad}_{\gamma_u(t)}(\mathbf{e}_i)) X_i(\gamma_u(t)), \quad (2)$$

for the left-invariant vector fields $X_i(g) := (dL_g) \mathbf{e}_i$.

Facts:

- * Every normal curve is analytic & constant-speed param.
- * Every normal curve is locally energy minimizing.

The converse is not true.

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Folk-conjectures:

- 1 \exists full-measure set $A \subset G$:
 $\forall p \in A \exists$ normal energy-minimizing curve from 1_G to p .
- 2 Every energy-minimizing curve is differentiable
(or even analytic!)

Second case: $\xi_0 = 0$.

$\iff \gamma$ satisfies the *abnormal equation*:

$\exists \lambda \in \mathfrak{g}^* \setminus \{0\}$:

$$\lambda \left(\int_0^1 \text{Ad}_{\gamma_u(t)} v(t) dt \right) = 0, \quad \forall v \in \Omega.$$

Equivalently,

$$\lambda (\text{Ad}_{\gamma_u(t)} V) = \{0\}. \quad (3)$$

Abnormal curves & abnormal varieties

Corollary

(G, V) polarized group, $\gamma : [0, 1] \rightarrow G$ horizontal curve. TFAE

- 1 γ is abnormal;
- 2 $\exists \lambda \in \mathfrak{g}^* \setminus \{0\} : \lambda(\text{Ad}_{\gamma(t)} V) = \{0\}, \forall t \in [0, 1]$;
- 3 \exists right-invariant 1-form α on G : $\alpha(\Delta_{\gamma(t)}) = \{0\}, \forall t \in [0, 1]$, where Δ is the left-invariant distribution induced by V .

Given $\lambda \in \mathfrak{g}^* \setminus \{0\}$, set $Z^\lambda := \{g \in G : ((\text{Ad}_g)^* \lambda)|_V = 0\}$.

Z^λ is a proper real analytic variety.

If G is nilpotent, then Z^λ is a proper real algebraic variety.

Proposition

A horizontal curve γ is abnormal \iff
 γ is contained in Z^λ for some nonzero $\lambda \in \mathfrak{g}^*$.

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How many abnormal
curves are there?

Size of abnormal set

The *abnormal set* of (G, V) is the subset $\text{Abn} \subset G$ of all singular values of the endpoint map. Equivalently, Abn is the union of all *abnormal curves* passing through 1_G .

Sub-Riemannian Sard Conjecture:

Abn has measure zero.

Theorem (LMOPV 2016)

In the following polarized groups Abn is contained in a proper algebraic subvariety:

- 1 *Carnot groups of step 2;*
- 2 *The free-nilpotent group of rank 3 and step 3;*
- 3 *The free-nilpotent group of rank 2 and step 4.*

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- 3 *The free-nilpotent group of rank 2 and step 4.*

Theorem (LMOPV 2016)

In every sub-Riemannian Carnot group G of step 3, the union of all locally length-minimizing abnormal curves passing through 1_G is contained in a proper algebraic subvariety.

Regularity of geodesics

What is the regularity of SR energy minimizers?

(1) They are Lipschitz / AC.

[Sussmann, 2014] They are analytic on an open dense set.

(2) All known examples are analytic.

But, even corners were not excluded until 2016.

- 1 In every (constant-rank, smooth) SR manifold, geodesics cannot have corners [HL2016].
- 2 ... and among tangents we always have some line [Monti-Pigati-Vittone 2017].
- 3 On SR Carnot groups, infinite geodesics blow down to lines [work-in-progress 2018].

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Setting & tangents

$(M, \Delta, \|\cdot\|)$ SR manifold (equiregular), $p \in M$.
 $\implies \exists G$ SR group:

$$\lim_{\epsilon \rightarrow 0}^{\text{GH}} (M, \Delta, \frac{1}{\epsilon} \|\cdot\|) = G.$$

Moreover, \exists maps $\delta_\lambda : M \rightarrow M$ that are isometries from $(M, \Delta, \frac{1}{\epsilon} \|\cdot\|, p)$ to $(M, \Delta, \frac{\lambda}{\epsilon} \|\cdot\|, p)$.
In the limit, $\delta_\lambda : G \rightarrow G$ are dilations by λ .

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In the limit, $\delta_\lambda : G \rightarrow G$ are dilations by λ .

A group as blow-up space

We call G the *tangent space* (or *blow-up*) at p .

Extra property – G is a Carnot group:

$$\text{Lie}(G) = V_1 \oplus \dots \oplus V_s$$

with

$$[V_1, V_j] = V_{j+1},$$

and

$$\delta_\lambda(v) = \lambda^j v, \quad v \in V_j.$$

The polarization on G is given by V_1 .

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Blow-ups and blow-downs of curves

G Carnot group, $\gamma : I \rightarrow G$ Lipschitz curve, $t \in I$

Blow-ups: **tangents**

$\text{Tang}(\gamma, t_0)$ – set of all curves limits of $\delta_{1/h}(\gamma(t_0 + ht))$, as $h \rightarrow 0$.

Blow-downs: **asymptotes**

$\text{Asymp}(\gamma)$ – set of all curves limits of $\delta_{1/h}(\gamma(t_0 + ht))$, as $h \rightarrow \infty$.

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G SR Carnot group. $\gamma : \mathbb{R} \rightarrow G$ energy-minimizer.

$\implies \exists H < G$ proper Carnot subgroup such that $\text{Asymp}(\gamma) \subseteq H$.

Corollary

$\gamma : \mathbb{R} \rightarrow G$ energy-minimizer in SR Carnot group.

\implies some element in $\text{Asymp}(\gamma)$ is a line.

Corollary (already proved by MPV following HL)

$\gamma : I \rightarrow G$ energy-minimizer in SR mfd, $t_0 \in I$

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Simpler version – For you today

Simpler version

G rank 2 SR Carnot group $\gamma : I \rightarrow G$ energy-minimizer
 $\implies \text{Asymp}(\gamma)$ consists of a line.

Stronger claim

$\pi_1 \circ \gamma : \mathbb{R} \rightarrow G/G^2 \simeq \mathbb{R}^2$
is at bounded distance from a line.

Sketch of the proof

- #. If not, \exists triples of points on $\pi_1 \circ \gamma$ forming triangles with every height arbitrarily big.
- #. $\pi_1 \circ \gamma$ is not a (Euclidean) geodesic. We may assume:
 - γ is a geodesic, but
 - $\sigma := \pi_{s-1} \circ \gamma$ is not a geodesic.
 - Here, $\pi_j : G \rightarrow G/G^{j+1} \simeq V_1 \oplus \dots \oplus V_j$.
- #. Shorten σ in an interval $[a, b]$, and lift it to $\tilde{\gamma}$ on G .
 - $\implies \tilde{\gamma}(t) = \gamma(t)$, for $t < a$, and
 - $\tilde{\gamma}(t) = \exp(Z)\gamma(t)$, for $t > b$, for some $Z \in V_s$.
- #. Take $t_0, t_1, t_2 > b$ s.t. $\pi_1 \circ \gamma(t_i)$ form a big triangle (in terms of Z). Find small $Y_1, Y_2 \in V_{s-1}$ s.t.

$$[Y_1, \log((\gamma(t_0))^{-1}\gamma(t_1))] + [Y_2, \log(\gamma(t_1)^{-1}\gamma(t_2))] = Z.$$

- #. Let α_j geodesics from 1 to $\exp(Y_j)$. Construct a curve shorter than γ with same endpoints. Contradiction. □

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Conclusions

With the same methods we expect that one might prove:

1. Every tangent is a line
2. Differentiability of geodesics

We don't expect to go beyond $C^{1,\alpha}$

JYVÄSKYLÄ, FINLAND
19TH – 23RD FEBRUARY 2018

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Merci

Thanks

Definition of Carnot group

\mathfrak{g} stratified Lie algebra $\mathfrak{g} = V_1 \oplus \dots \oplus V_s$.

G simpl. conn. Lie group with $\text{Lie}(G) = \mathfrak{g}$.

$\|\cdot\|$ norm in V_1 .

The CC distance is $d_{cc}(p, q) = \inf \left\{ \int \|\dot{\gamma}\| : \begin{array}{l} \gamma: [0,1] \xrightarrow{AC} G, \\ \dot{\gamma} \in V_1 \end{array} \quad x \rightsquigarrow y \right\}$

(G, d_{cc}) is a (subFinsler) Carnot group.

Theorem

Carnot groups are the only metric spaces that are

- 1 *locally compact,*
- 2 *geodesic,*
- 3 *homogeneous,*
- 4 *admit a dilation.*

Definition of Carnot group

\mathfrak{g} stratified Lie algebra $\mathfrak{g} = V_1 \oplus \dots \oplus V_s$.

G simpl. conn. Lie group with $\text{Lie}(G) = \mathfrak{g}$.

$\|\cdot\|$ norm in V_1 .

The CC distance is $d_{cc}(p, q) = \inf \left\{ \int \|\dot{\gamma}\| : \begin{array}{l} \gamma: [0,1] \xrightarrow{AC} G, \\ \dot{\gamma} \in V_1 \end{array} \quad x \rightsquigarrow y \right\}$

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SubRiemannian Heisenberg group

$$\begin{aligned} \text{In } \mathbb{R}^3, \quad X &= \partial_1 - \frac{y}{2} \partial_3 = (1, 0, -\frac{y}{2}) \\ Y &= \partial_2 + \frac{x}{2} \partial_3 = (0, 1, \frac{x}{2}) \end{aligned} \quad \text{vector fields}$$

Consider PWC^∞/AC curves $\gamma : [0, 1] \rightarrow \mathbb{R}^3$ s.t. \forall almost t
 $\dot{\gamma}(t) = a(t)X \circ \gamma(t) + b(t)Y \circ \gamma(t)$.

Call these curves *horizontal*, and set $\|\dot{\gamma}\| = \sqrt{a^2 + b^2}$.

Set $d(p, q) = \inf\{\int \|\dot{\gamma}\| : \gamma \text{ horizontal, } x \rightsquigarrow y\}$

$$= \inf \left\{ \int \|\dot{\gamma}_1, \dot{\gamma}_2\|_{\ell^2} : \begin{array}{l} \gamma : [0, 1] \xrightarrow{AC} \mathbb{R}^3, \quad x \rightsquigarrow y \\ \dot{\gamma}_3 = \frac{1}{2}(\gamma_1 \dot{\gamma}_2 - \gamma_2 \dot{\gamma}_1) \end{array} \right\}$$