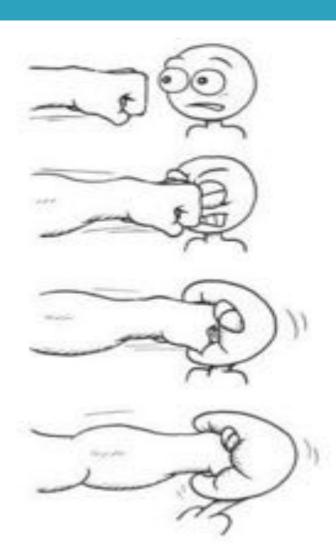
# Computer Animation Lesson 8 - Rigging and skinning Remi Ronfard, Nov 2019

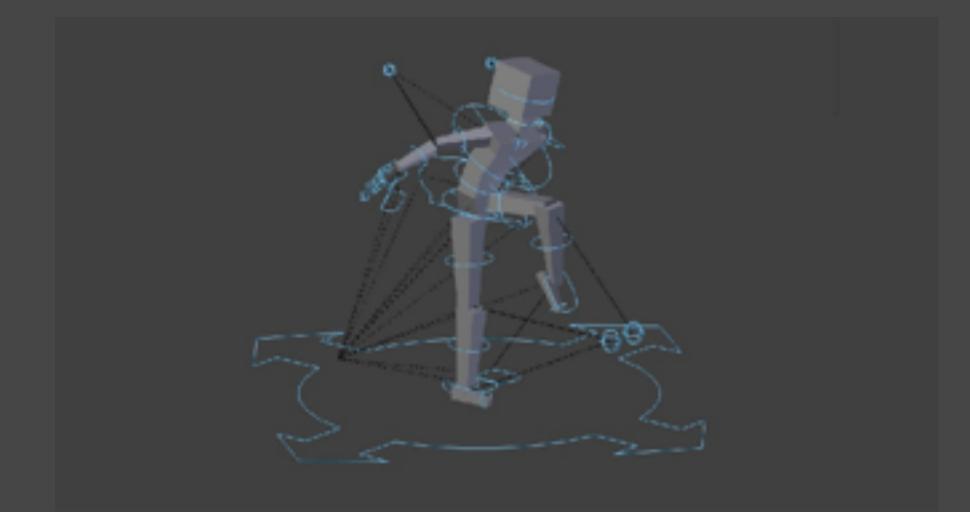
# 8 Exaggeration

The meaning of exaggeration is, in general, obvious. However, the principle of *exaggeration* in animation does not mean arbitrarily distorting shapes or objects or making an action more violent or unrealistic. The animator must go to the heart of anything or any idea and develop its essence, understanding the reason for it, so that the audience will also understand it. If a character is sad, make him sadder; if he is bright, make him shine; worried, make him fret; wild, make him frantic.



## 10. Exaggeration

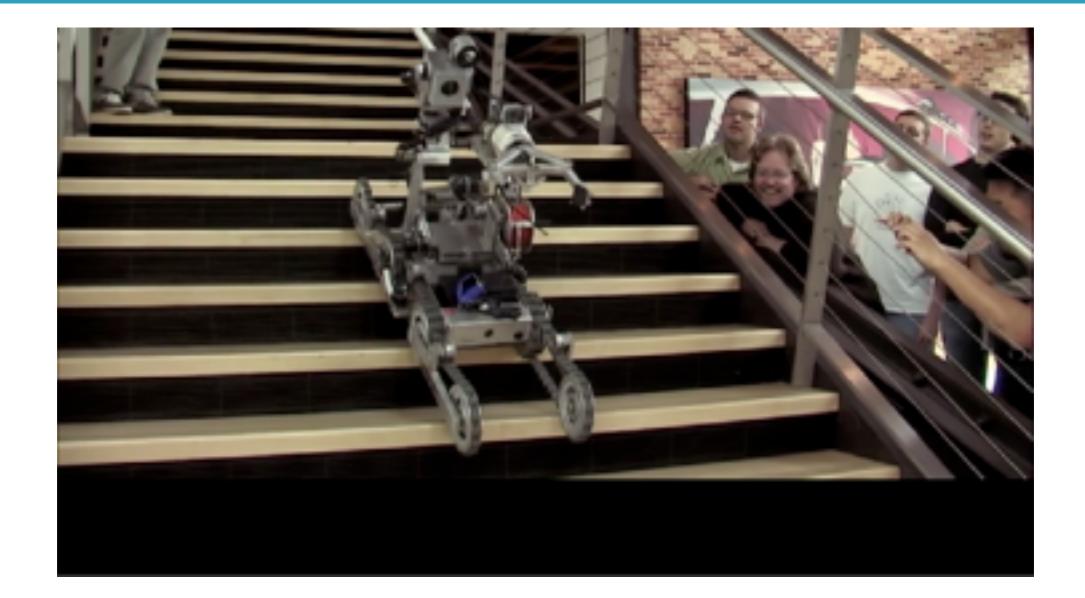
### RIGGING AND SKINNING



# Rigging and skinning

- How do we animate complex characters?
  - Skeleton/armature: rigging
  - Skin and flesh: skinning, smooth skinning, muscles, fat, wrinkles
  - Clothing : particle systems, finite elements

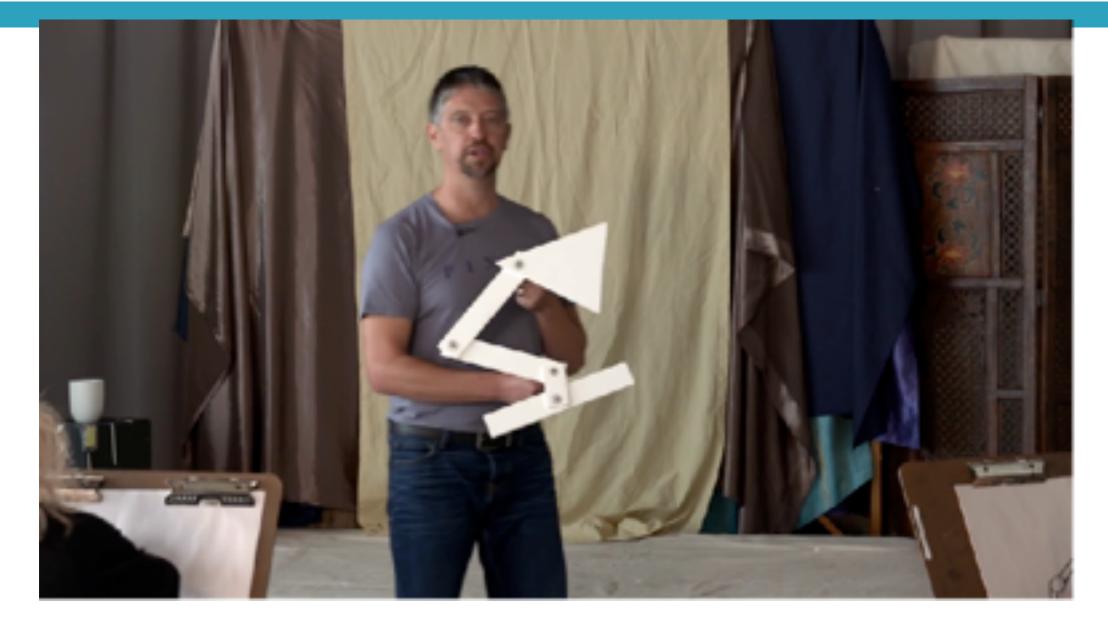
# **Rigging introduction**



# Rigging a lamp (part 1)



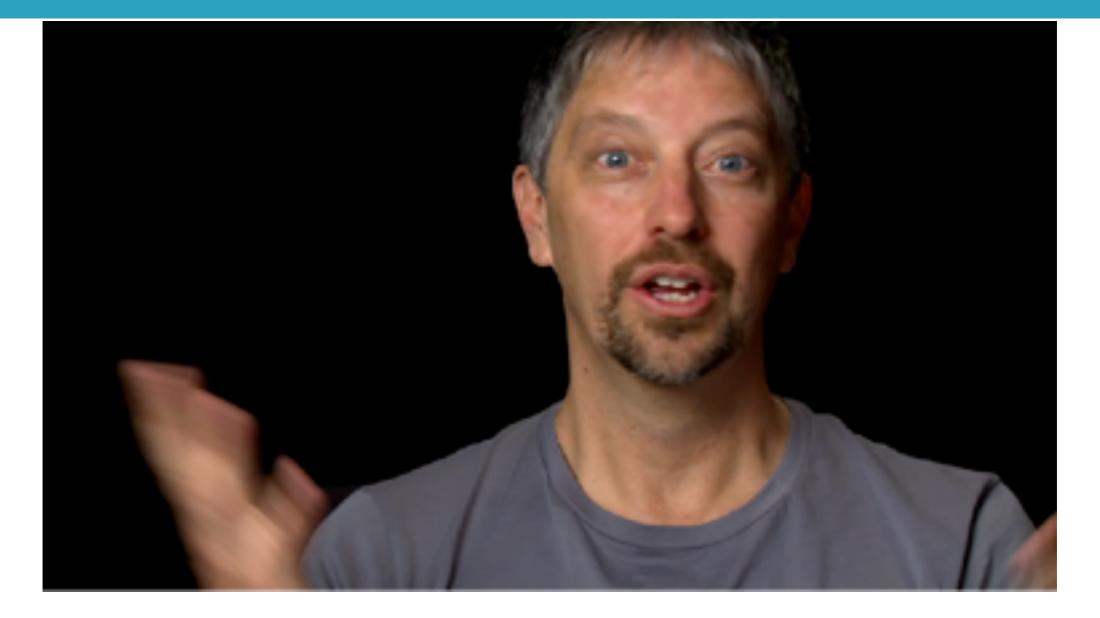
# Rigging a lamp (part 2)



# Rigging a lamp (part 3)



# Rigging a lamp (part 4)



# Rigging a human character

### Skeleton = "bones" Geometry = "skin"



# **Typical Character**

- Mechanics of movement must be convincing
- Skin and clothing moves & bends appropriately
- This process of preparing character controls is called rigging
  - Fully rigged character has
    - Skeleton joints, surfaces, deformers, expressions,
      Set Driven Key, constraints, IK, Blendshapes, etc

# **Typical Character Rig**

#### SHEEPER JOINTS

Joints are used to create a framework for a character's hierarchy. The rotation of the skeleton joints defines the motion of the character; you can use inverse kinematics for even more control.

#### CHARACTER CONTROLS

Daing animation bechniques such as tell briven Key and expressions, you can set up attributes for controlling different parts of a character. For example, a hand joint is could have attributes used to control the different finger joints.

#### CONSTRAINTS

It is possible to constrain the kinematic controls of a skeleton to objects in your scene or even simple locators. You can then animate the constraint weights to make a character pick something up or grab hold of a fixed object.

#### SELECTEON HANDLES

Selection Handles give you quick access to parts of a character's hierarchy that are to be animated. This makes it easier to work with a character ofter it has been rigged up for animation.

#### FACIAL REPARTION

To animate facial features, you can use deformers such as Blend Shape to create facial poses that can be used for talking and for showing emotion.

#### KINGMATICS.

to control your skeleton joints, you can choose from Forward or inverse kinematics. Parward Kinematics allows you to set the joint rotations directly. 2K allows you to position 2K Handles, which rotates the joints.

#### BOUND SUBPRCES

Surfaces of a character's skin and clothing can be either parented or bound to the skeleton joints to make them move topether, binding places points from a surface into clusters that are then associated with particular joints.

#### DEFORMERS

To help the surfaces bend realistically at joints, deformers such as flexers and influence objects can be used.

# **Character Resolution**

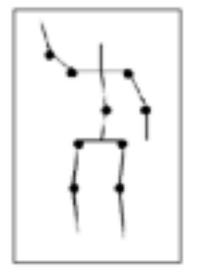
- Use low resolution character that has surfaces "parented" to skeleton
  - Allows interactive animations
  - Switch to full resolution character later

## Typical Character Animation Workflow

- Character Design
- Model
- Skeleton Rigging
- Binding
- Animation
- Integration
- Rendering

# Animation and interpolation

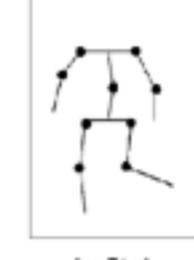
- Series of pairs (time, parameter values)
- interpolate inbetween



key T0,q0



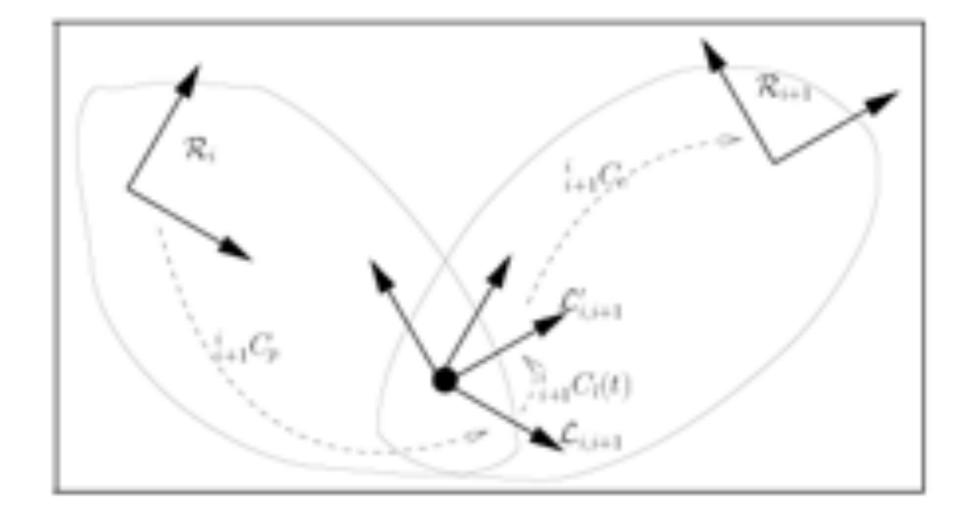
L interpolated q



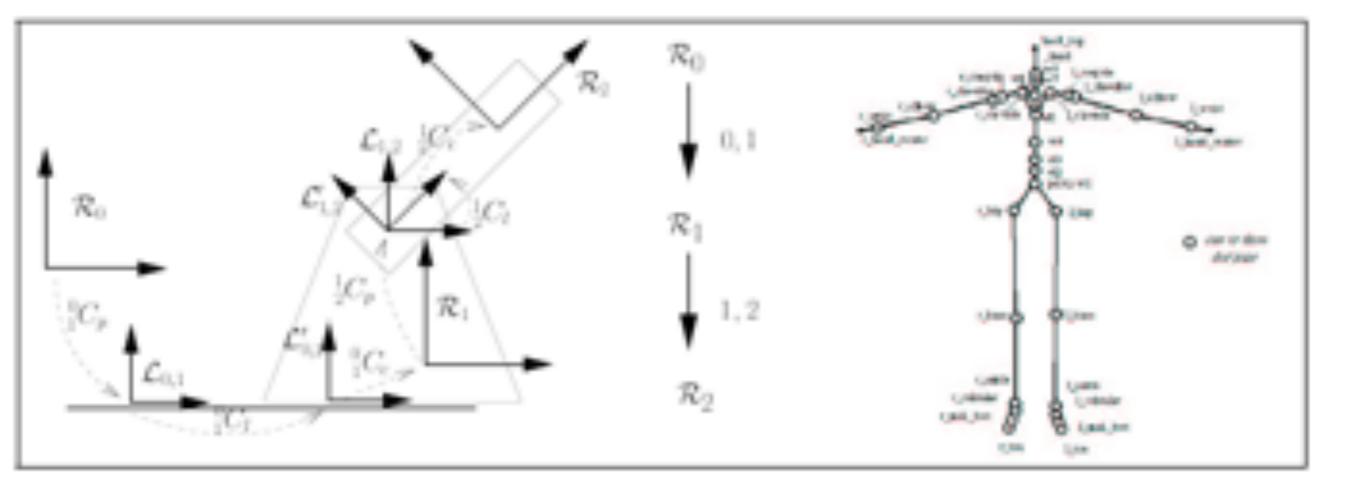
key T1,q1

- Keyframe animation
  - How to interpolate motion between key-frames

## Articulated motion



## Articulated motion



# Articulated and rigid motion

- Motion of body part is rigid
  - In the parent's frame
  - In the word frame
- Rigid motion can be represented as a 3
  x 4 matrix

$$M_{b,f} = (S_{b,f}R_{b,f}T_{b,f}) M_{p,f} \qquad S_{b,f}R_{b,f}T_{b,f} = \begin{pmatrix} S_x R_{11} & S_x R_{12} & S_x R_{13} \\ S_y R_{21} & S_y R_{22} & S_y R_{23} \\ S_z R_{31} & S_z R_{32} & S_z R_{33} \\ T_x & T_y & T_z \end{pmatrix}$$

# Skinning

- We have a structure of bones, organized as a kinematic tree
- Problem : how do we animate the « skin » of the characters given the motion of their bones ?
- Rigid skinning : each body part is modeled as a rigid body

 $\square$  P(v<sub>i</sub>)= T<sub>f</sub> P<sub>0</sub>(v<sub>i</sub>) where T is the bone transformation

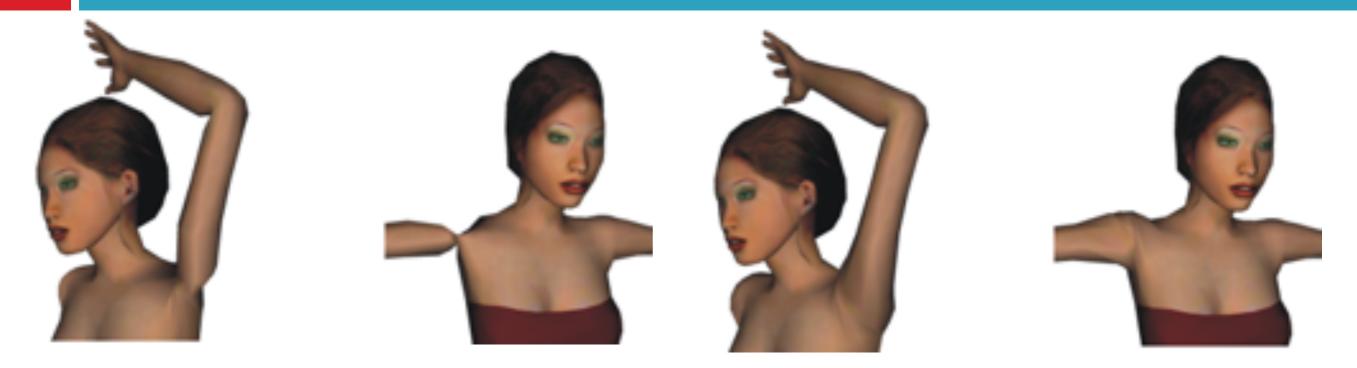
# Smooth skinning

- Also known as « Skeleton Subspace Deformation »
- Skin vertices move as a result of several body part motions
  - $\square P(v_i) = (sum_f w_{if} T_f) P_0(v_i)$
  - Normalized weights : sum\_f w<sub>if</sub> = 1)
  - Vertex weights can be computed automatically
  - For example  $w_{if} = 1/d_{if}^2$
- Or weights can be drawn by « painting » the skin

# Interpolation of matrices

- Transformation matrix  $T_f = [SR|t]$  with 12 parameters
- Non independent
- 3 translations, 3 rotations, 3 re-scalings
- Better to control them separately
- Automatic weight computation
- Wang et Philips, Multi-weight enveloping: least-squares approximation techniques for skin animation, SCA 2002

# Dual quaternion interpolation



<u>Skinning with Dual Quaternions</u>
 Ladislav Kavan, Steven Collins, Jiri Zara, Carol O'Sullivan.
 Symposium on Interactive 3D Graphics and Games, 2007.

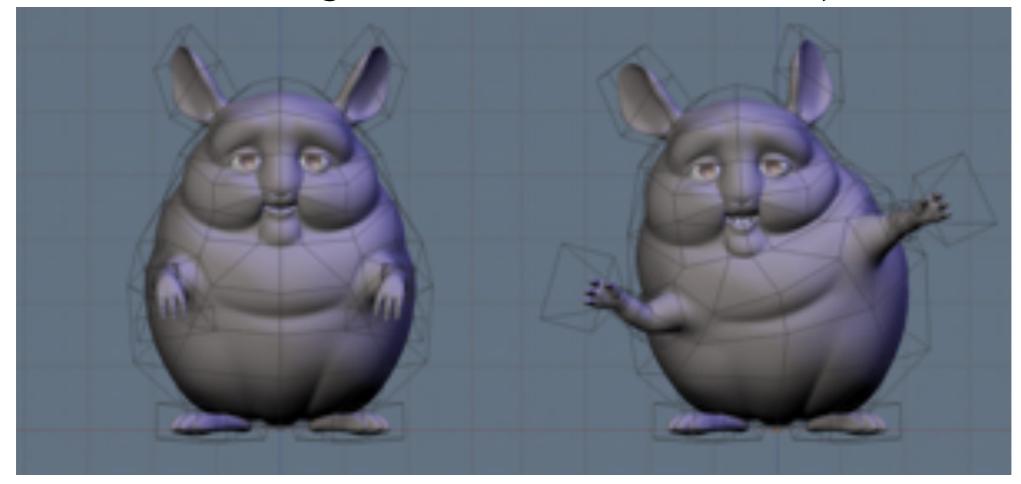
## Skinning with Dual Quaternions

### L. Kavan, S. Collins, J. Zara, C. O'Sullivan

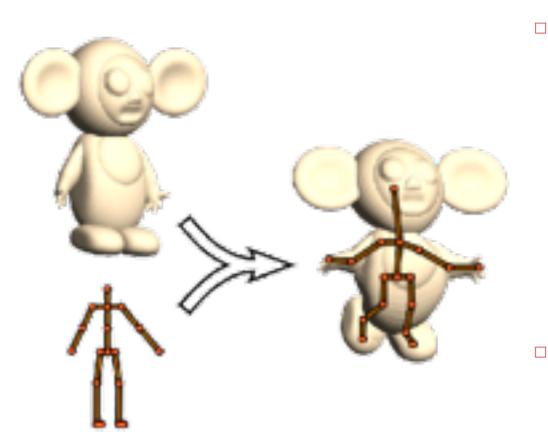
Trinity College Dublin Czech Technical University in Prague

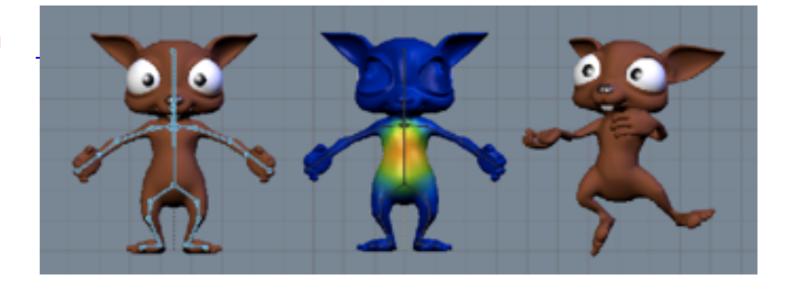
# Cage deformations

### Build a cage around bones (armatures)



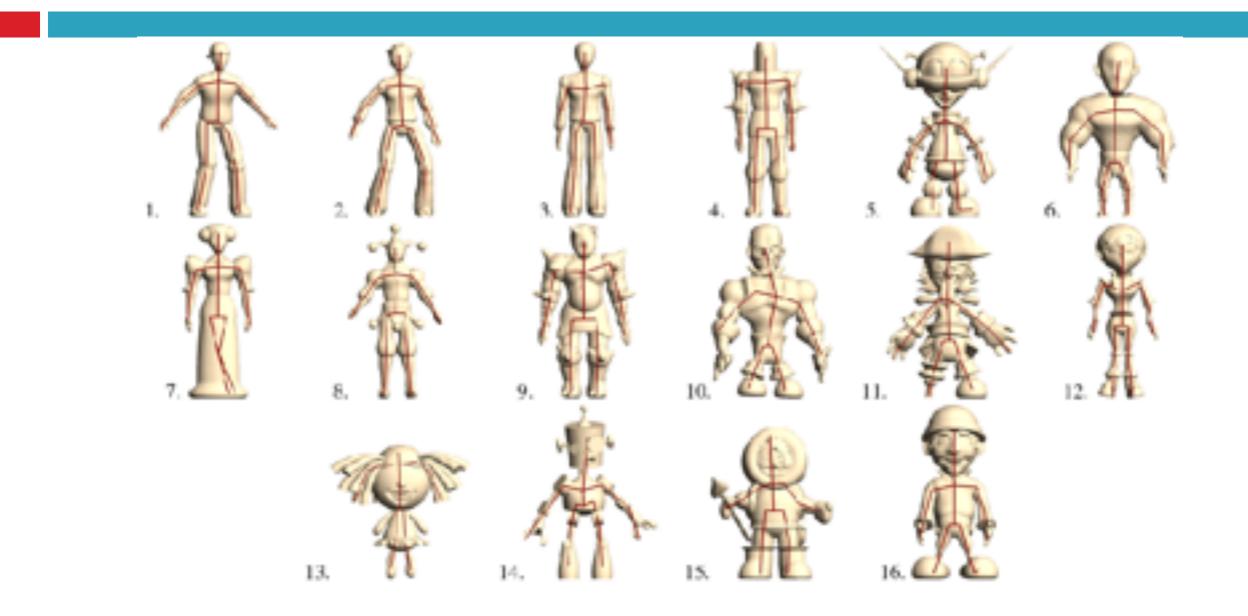
### Paper 8 - Automatic rigging and skinning: Bone Heat Weighting





<u>Automatic Rigging and Animation of 3D</u> <u>Characters</u> Ilya Baran and Jovan Popovic, SIGGRAPH 2007.

# Examples



# Pinocchio

Automatic Rigging and Animation of 3D Characters

SIGGRAPH 2007 papers\_0030