# HEXOTIC : AN AUTOMATED HEXAHEDRAL MESH GENERATOR

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#### 1 / Basics of octree meshing :

-Set of subdivision criteria : geometry's thickness, curvature, a posteriori error estimate. -Balancing rule : a cell should not be more than two time bigger or smaller than it neighbors. -Pairing rule : if a cell is to be subdivided, then it "brothers" should be subdivided too.





### 2 / Dual mesh :

2D :

- element <-> node
- edge <-> edge

#### 3D :

- element <-> node
- face <-> edge





2b / Dual mesh :



3 / Surface meshing :

Analysis of edges (triangles) intersecting each octant :

#### 2D :

1 group -> median line.

- 2 groups -> two intersecting lines making a sharp angle.
- 3+ too complex.

#### 3D :

- 1 group -> median plane.
- 2 groups -> two intersecting planes making a sharp edge.
- 3 groups -> three intersecting planes making a sharp corner.
- 4+ too complex.



#### 4 / Subdomain recovering :

-Basic inside/outside algorithm.

- -It can handle internal surfaces (non-manifold geometries).
- -Domains must be two-element thick in any direction.





### 5 / Surface projection :

Problem : octree generates a so called "staircase mesh".

-Hexes may have two or three faces to be projected on the same plane -> degenerated.
-Surface quad may have two edges to be projected on the same sharp line.

Solution : buffer-layer insertion

-A first layer of hexes is inserted around the staircase mesh so that new boundary elements have only one face to be projected on the real geometry.

-Likewise, a second layer of element is inserted around sharp edges.



5b / Boundary after projection :



5c / Second layer :



6 / Quality optimization via node smoothing :

-Each solver has its own quality criterion.

-Only one common ground : each hex must have a positive volume.

-So we can only try to get as close as possible to the perfect cube.

-The optimizing process finds the closest perfect cube from each hex and adds the contributions to a new set of nodes' coordinates which eventually will result in a better mesh.



### 7 / Boundary constrained optimization scheme :

-Boundary elements could be treated the same way as others and surface node could be projected on the geometry afterward -> interlocking : smoothing may move nodes in one direction and projection may move them back !

-Geometry should be part of the smoothing scheme : the perfect cube is rotated and pushed away so that its surface face matches the geometry it should represent.



8 / Strong limitation : he lack of topological operators on hex meshes :



8b / Strong limitation : the lack of topological operators on hex meshes :



## 9 / Mesh adaptation :

-Only isotropic adaptation because of the octree method : no anisotropy like in tet meshes. -Twofold size ratio between neighboring elements : no smooth size transitions.



### 9b / Mesh adaptation : the apollo capsule



## 9c / Mesh adaptation : the apollo capsule



### 10 / Plus and Minuses of this method :

+ Robust : it always produces a result (but it may not be the meshed you dreamed of...)
+ Fast : 2.000.000 elements / minute on this laptop.

+ Simple : command-line program requiring few arguments (min,max sizes, sharp angle threshold)

+ 100 % hexahedral and conformal meshes (no pyramids, prisms or hanging nodes).

-Generates too many elements when it comes to thin geometries (blades, wings, etc...) -Isotropic meshing only.

- -Present version cannot handle very sharp angles : hexes gets too distorted.
- -Unstructured meshes (although larger parts of meshes are grid-like).

Work is under way to limit the number of elements in thin geometries via a hybrid method using octree in thick parts and surface extrusion in thin ones.

This method will also allows for more accurate meshing of very sharp angles.

Conclusion : there is still a long way to go to reach the "holly grail" of hex meshing !