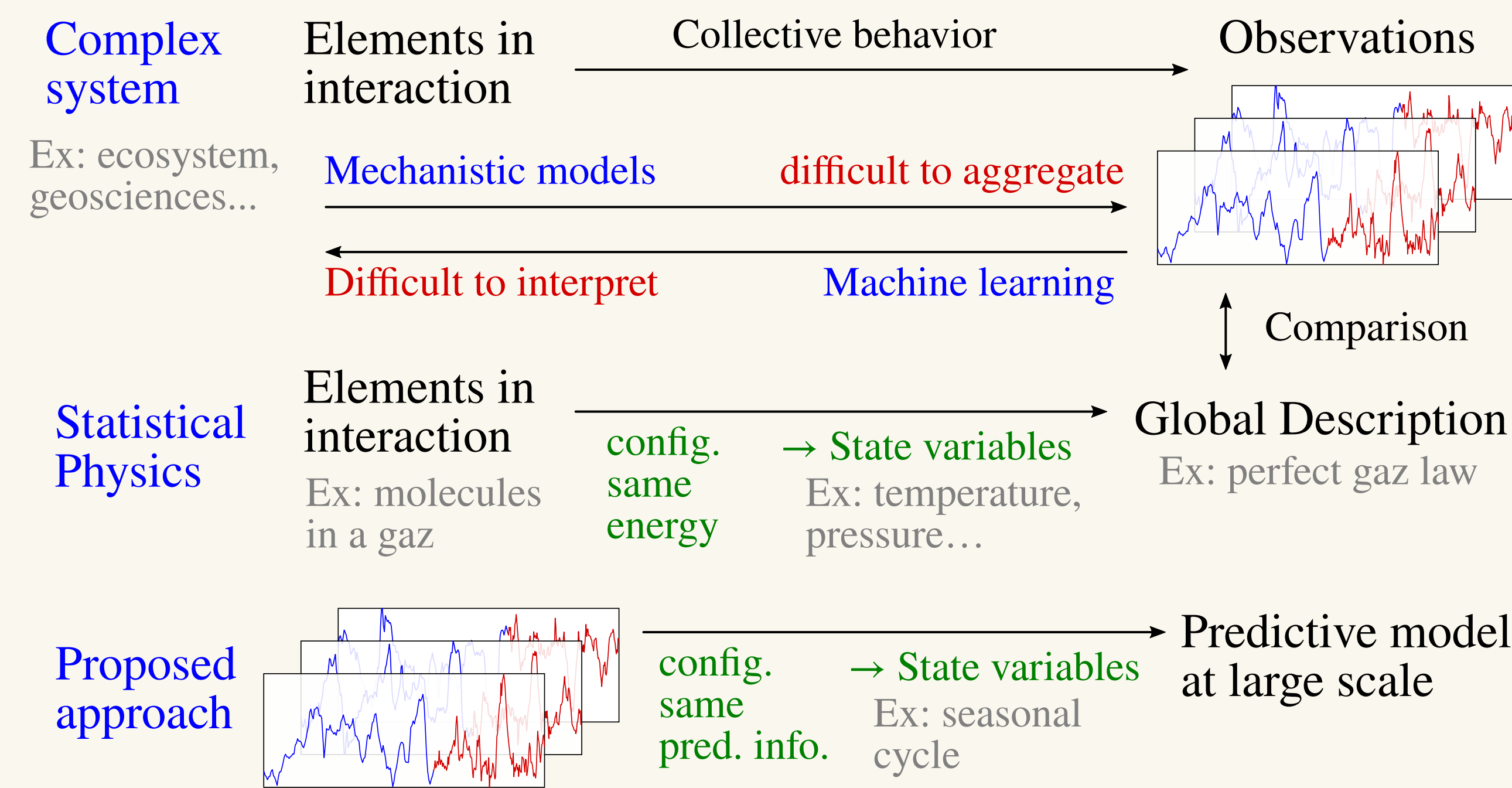
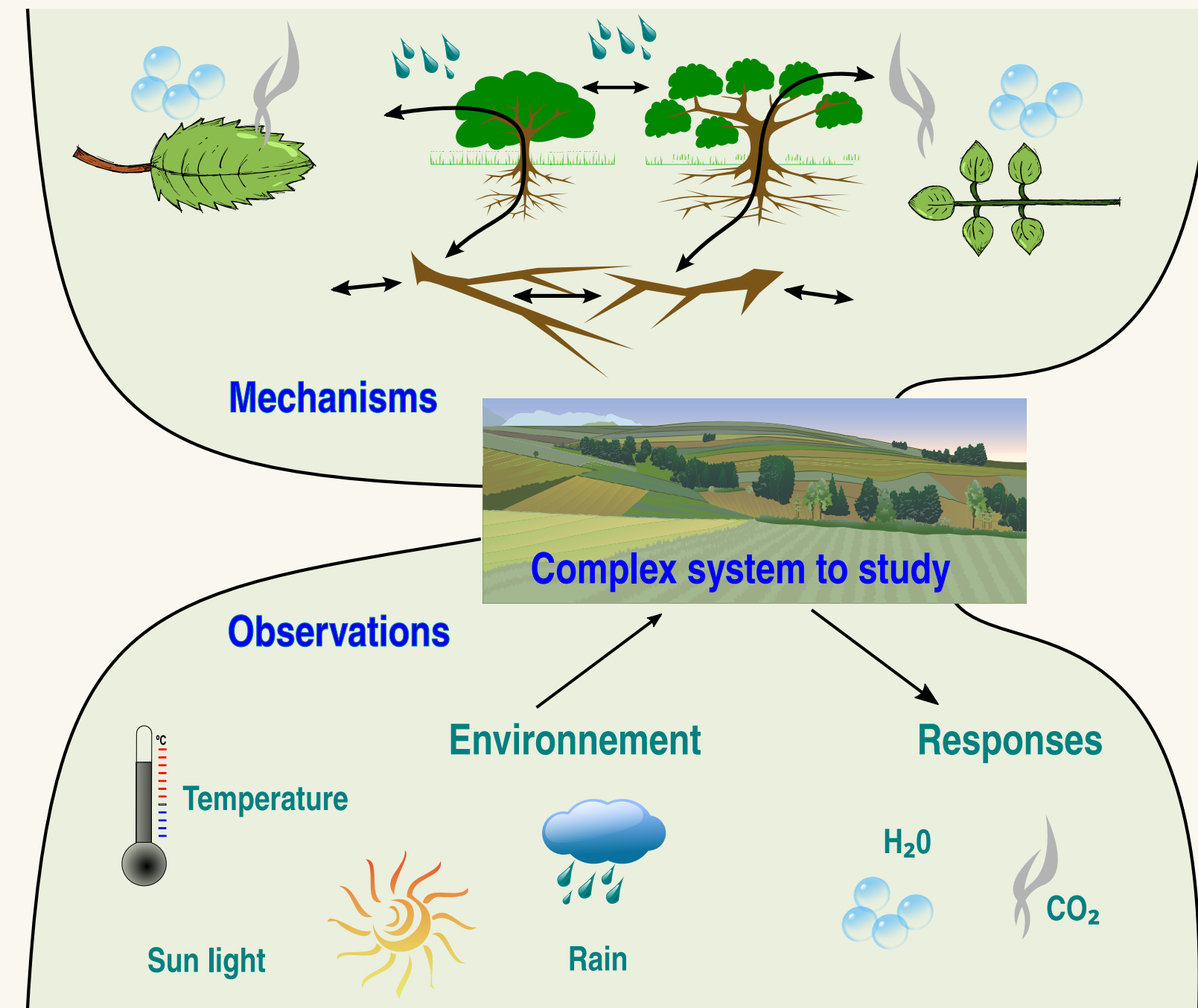


# INFERRING EFFECTIVE STATE VARIABLES AND DYNAMICS FROM DATA

## 1. MODELING COMPLEX SYSTEMS



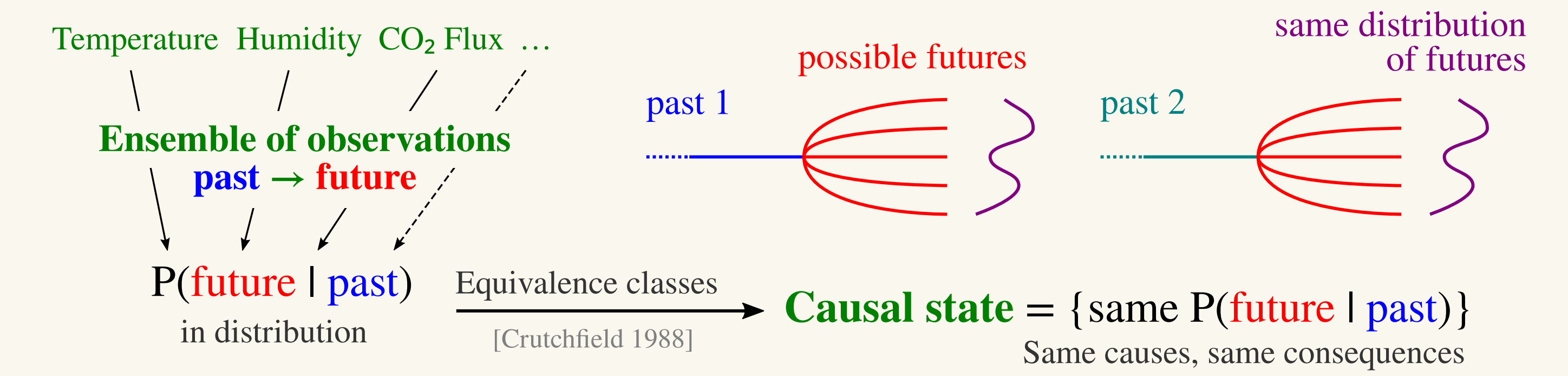
**Properties**

- No new observation can distinguish two past sequences in the same causal state  $\Rightarrow$  equivalent for all modeling purposes
- States do not depend on the frame of reference distribution shapes change but not the classes  $\Rightarrow$  intrinsic property of the observed process

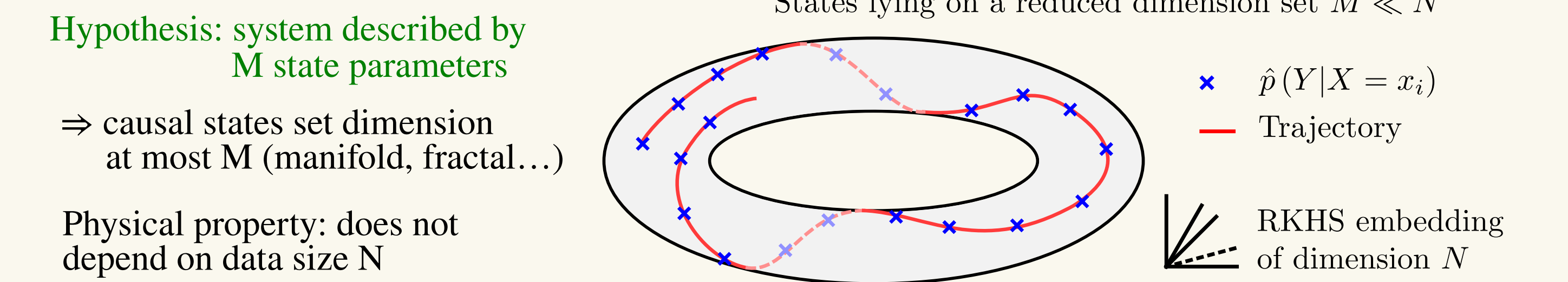
**Reconstruction of state variables**

- No reason to find back the original frame
- Work in progress for the correspondance

## 2. CAUSAL STATES



## 3. STATE VARIABLES



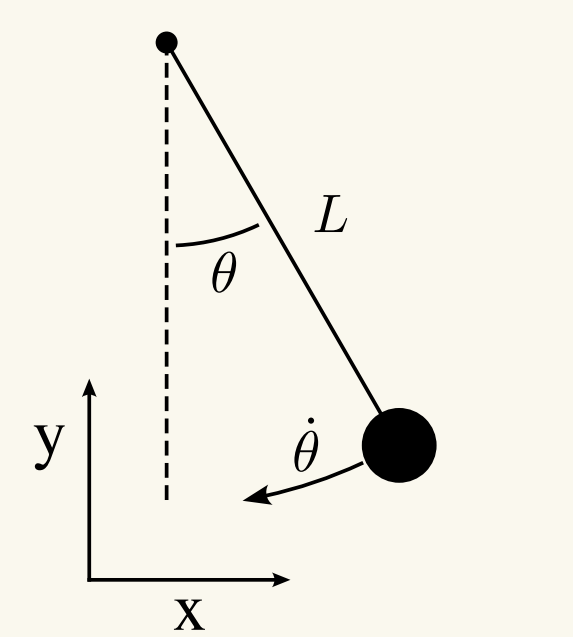
Choice of coordinates = eigenbasis of Laplace-Beltrami operator  $\Delta$  [Brodu & Crutchfield 2022]

- Estimated with diffusion maps  $\Rightarrow$  geometry robust to the sampling density
- Eigenbasis  $\Leftrightarrow$  generalized Fourier modes of the manifold
- Each added coordinate best refines the (diffusion) distance between states  $\Rightarrow$  hence better encodes causal states, hence predictive info.

3. & 4.  $\Rightarrow$  Interpretation : « as if » macroscopic system driven by hidden state variables + SDE

## 4. ODE AS A SPECIAL CASE

Dissipative pendulum

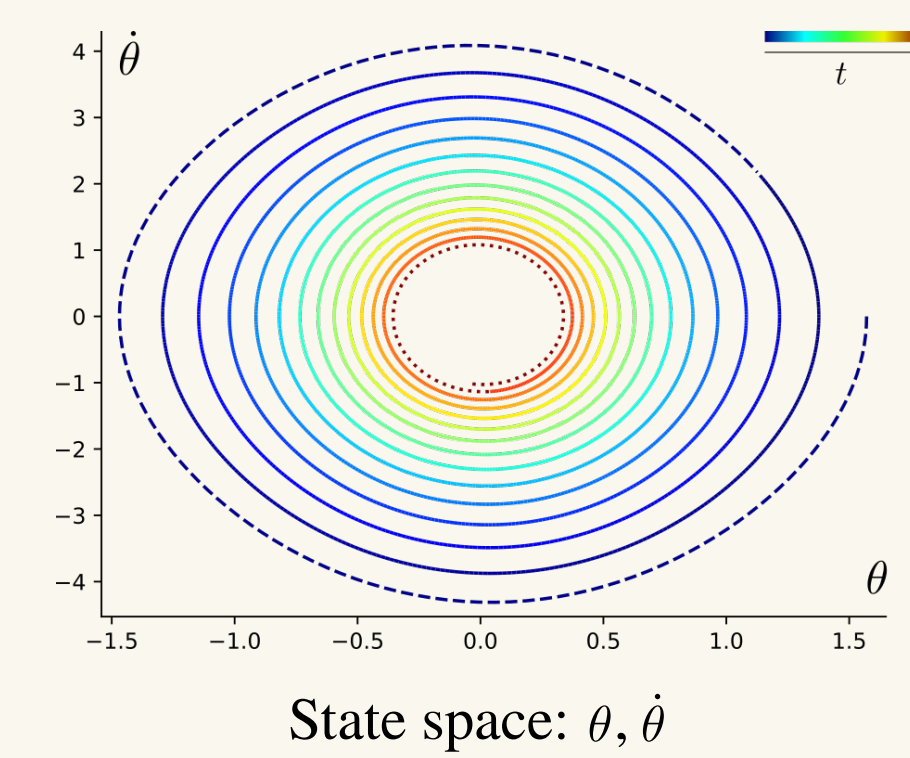


$$\frac{d\theta}{dt} = \dot{\theta}$$

$$\frac{d\dot{\theta}}{dt} = -\frac{b}{m}\dot{\theta} - \frac{g}{L}\sin\theta$$

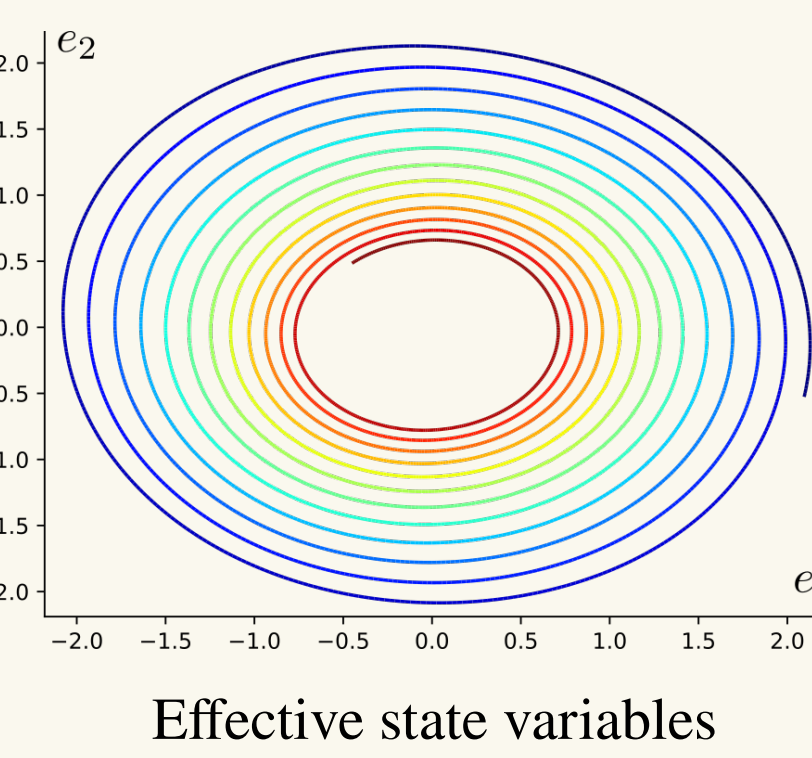
Each point in phase space is a causal state

- Unique trajectory = future
- No dependency on the past



Reconstruction from data  
 - Positions (x,y) for 1 period

Causal states encoded in a set of coordinates  $\Rightarrow$  state variables



Noisy Lorenz system (SDE)

$$du = -a(u - v) dt + \eta dW$$

$$dv = (bu - v - uv) dt + \eta dW$$

$$dw = (-cw + uv) dt + \eta dW$$

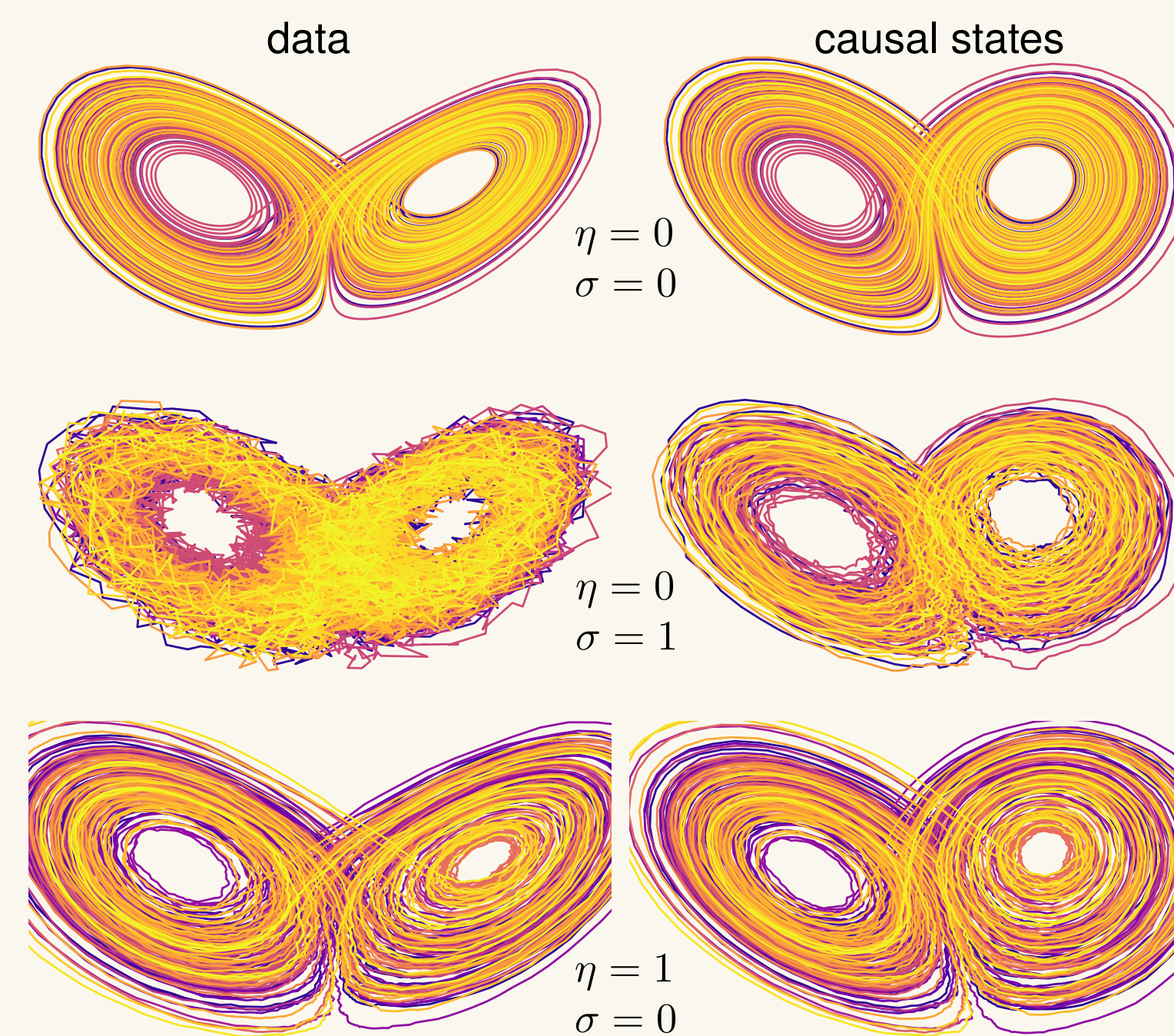
(a, b, c) = (10, 28, 8/3)

Data

- Simulation of trajectories
- Gaussian noise added to data, var.  $\sigma^2$

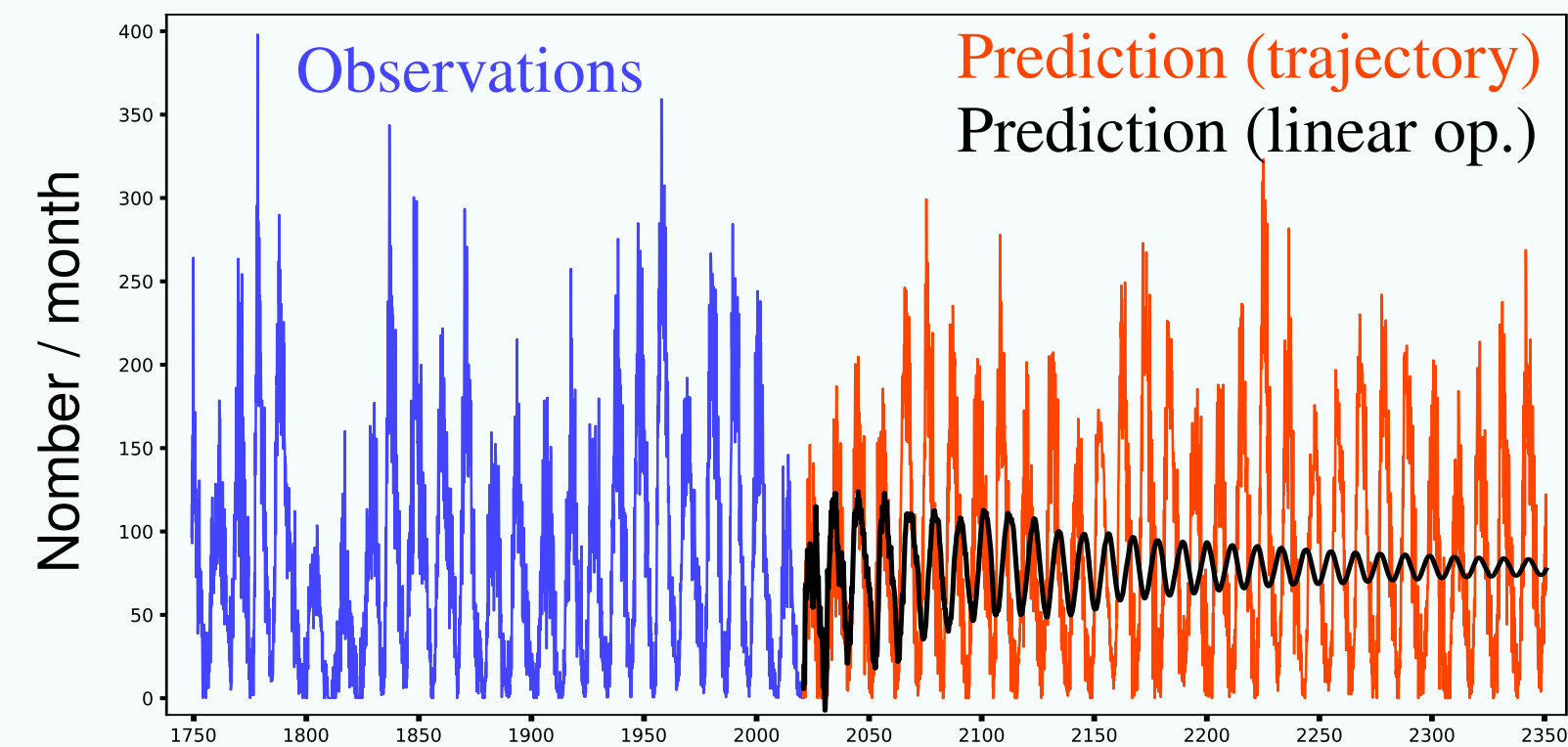
Causal states

- Adding noise does not change equiv. classes  $\Rightarrow$  robust to measurement noise!
- Intrinsic noise: SDE details preserved



## 6. SUNSPOTS

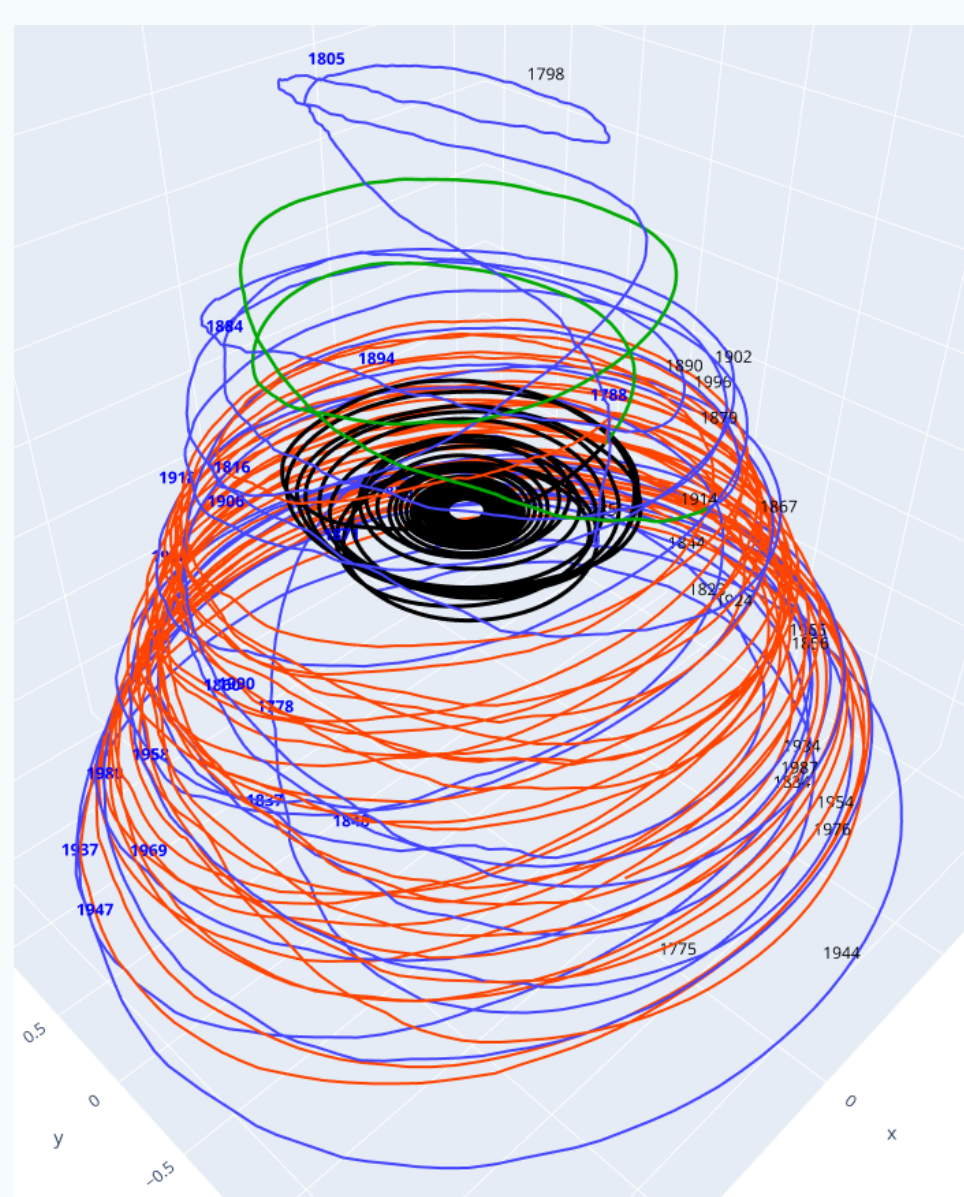
Data : SILSO



Inferred state variables

- 11-years cycle (x,y)
- Amplitude modulations (z)

Structure resembling an attractor embedding



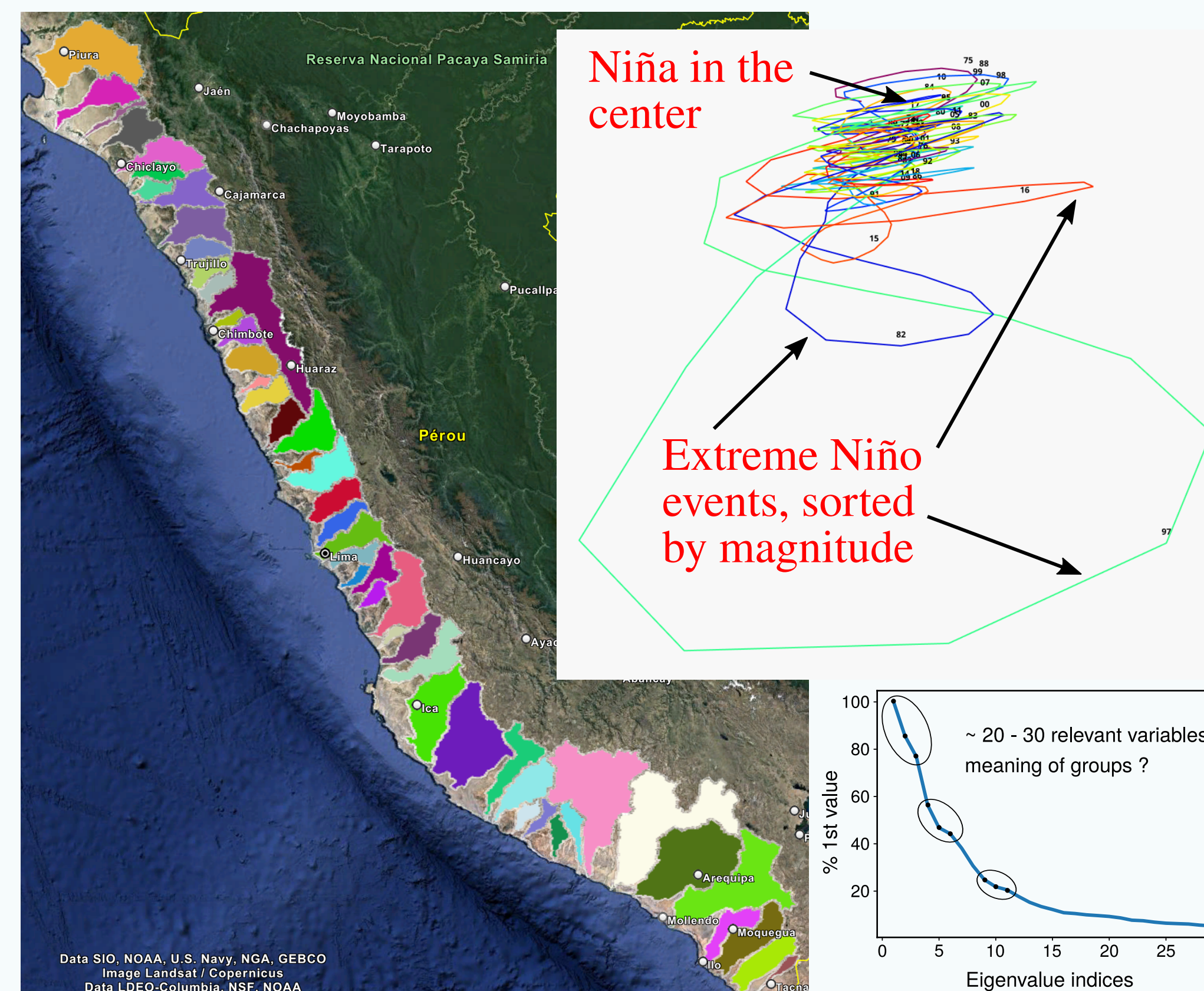
Predictions

- Trajectory constrained on the structure
- Linear operator converging to the expected value

## 7. EL NIÑO / LA NIÑA (ENSO)

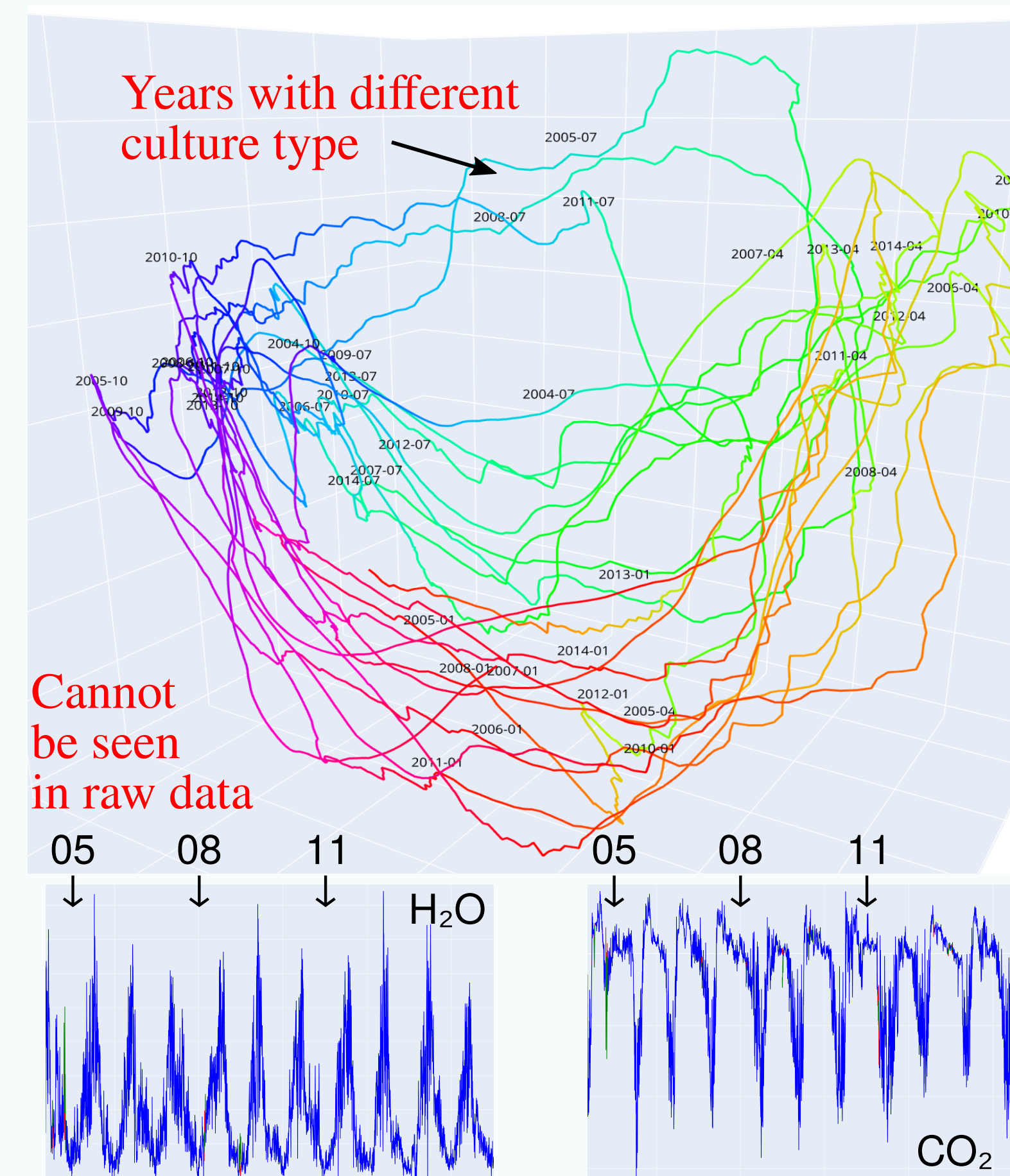
- 50 years of measurements, very high quality
- 49 watersheds, Peruvian coast
- Pacific Ocean : 4 indices of sea surface temperature
- Per watershed: precipitations, runoff, evapotranspiration, temperature

Data: Luc Bourrel, Pedro Rau

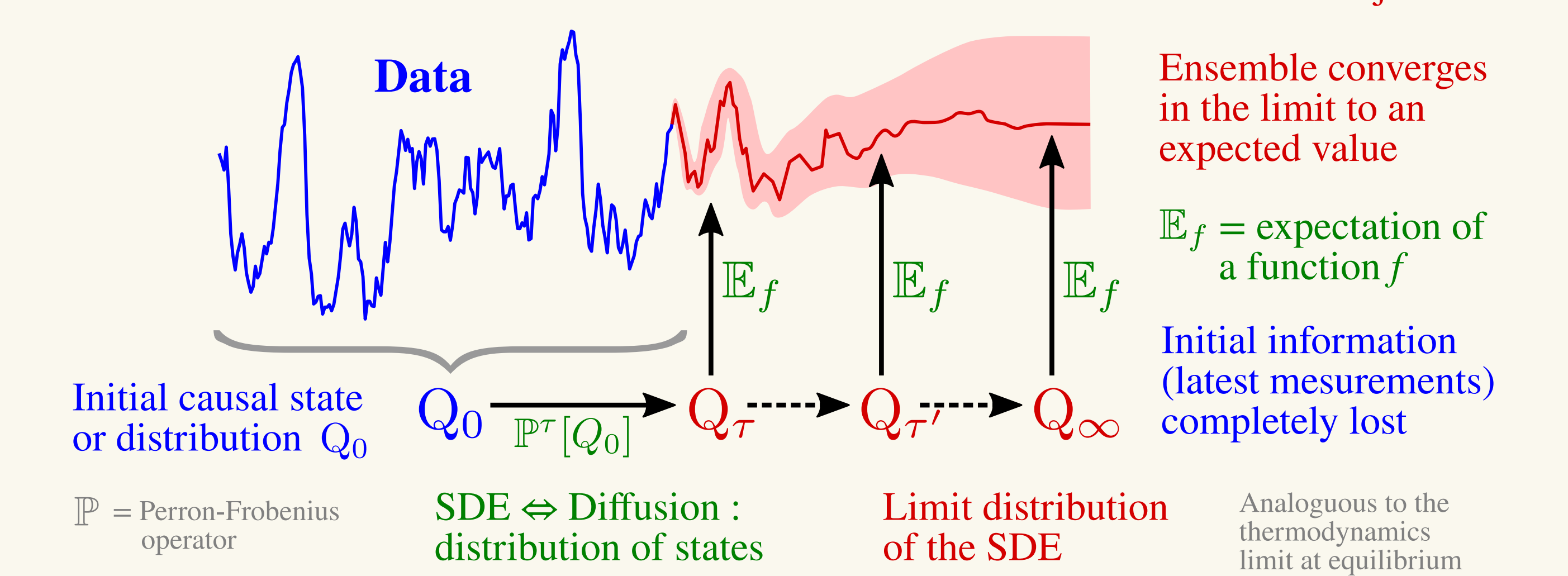


## 8. GRIGNON FIELD (FR)

- Temperature, soil humidity, sun illumination, evapotranspiration, precipitations, CO<sub>2</sub>
- ICOS data (flux tower + in situ sensors), 11 years of daily observations



## 5. PREDICTIVE MODEL



This model specifies how predictive information diffuses through time!

## 9. N-BUTANE CONFORMATIONS

- Data by Stefan Klus
- Positions x,y,z of atoms sampled every 200 fs
  - Local frame of reference

Results

- Clusters = molecular conformations (carbon)
- Fast transitions go through eclipsed conformations
- Sub-clusters for hydrogen atom positions (chemically equiv. but distinct in data)
- Shows structure other than cyclic attractor-like examples

