

General solution of the Inhomogeneous Div-Curl system and Consequences

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We will give a complete solution to the reconstruction of a vector field from its divergence and curl, i.e., the system

$$\begin{aligned}\operatorname{div} \vec{W} &= g_0, \\ \operatorname{curl} \vec{W} &= \vec{g},\end{aligned}\tag{1}$$

for appropriate assumptions on the scalar field g_0 and the vector field \vec{g} and their domain of definition in three-space.

Let \mathbb{H} the non-commutative algebra of quaternions over the real field \mathbb{R} . Let $x = x_0 + \sum_{i=1}^3 e_i x_i \in \mathbb{H}$, where $x_i \in \mathbb{R}$. The subspace $\text{Vec}\mathbb{H} := \text{span}_{\mathbb{R}} \{e_1, e_2, e_3\}$ of \mathbb{H} is identified with the Euclidean space \mathbb{R}^3 as follows

$$x_1 e_1 + x_2 e_2 + x_3 e_3 \leftrightarrow (x_1, x_2, x_3) \in \mathbb{R}^3.$$

Let $\Omega \subset \mathbb{R}^3$ be an open subset with smooth boundary. Define the Cauchy-Riemann type differential operator as

$$D = e_1 \frac{\partial}{\partial x_1} + e_2 \frac{\partial}{\partial x_2} + e_3 \frac{\partial}{\partial x_3}.$$

It acts over differentiable functions $w : \Omega \rightarrow \mathbb{H}$ of the form $w(x) = w_0(x) + \sum_{i=1}^3 e_i w_i(x)$, where $w_i : \Omega \rightarrow \mathbb{R}$, $i = 0, 1, 2, 3$.

The following result tell us that is impossible to define an \mathbb{H} -holomorphic functions via the existence of the limit of the difference quotient, like in the complex case:

Theorem

Let $w \in C^1(\Omega)$ be a function defined in a domain $\Omega \subset \mathbb{H}$. If for all points in Ω the limit

$$\lim_{h \rightarrow 0} h^{-1}[w(x+h) - w(x)],$$

exists, then in Ω the function w has the form

$$w(x) = a + xb \quad a, b \in \mathbb{H}.$$

Definition

A C^1 function $w : \Omega \rightarrow \mathbb{H}$ is called *left-monogenic* (resp. *right-monogenic*) in Ω if

$$Dw = 0 \text{ en } \Omega \quad (wD = 0 \text{ in } \Omega).$$

We will say simply "monogenic" to refer to left-monogenic functions. Even more, since $Dw = -\operatorname{div} \vec{w} + \operatorname{curl} \vec{w} + \nabla w_0$, then

$$Dw = 0 \iff \begin{cases} \operatorname{div} \vec{w} & = 0, \\ \operatorname{curl} \vec{w} & = -\nabla w_0. \end{cases}$$

Examples:



$$E(x) := \frac{1}{4\pi} \frac{\bar{x}}{|x|^3}, \quad x \neq 0,$$

is an example of a left- and right-monogenic function, called Cauchy kernel.



$$w(x) = -x_3 + x_1 e_2 - x_3 e_3,$$

is left-monogenic but no right-monogenic, since $Dw = 0$ y $wD = -2e_3$.

Let us denote $\vec{\mathfrak{M}}(\Omega) = \text{Sol}(\Omega, \mathbb{R}^3) \cap \text{Irr}(\Omega, \mathbb{R}^3)$, where

$$\begin{aligned}\text{Sol}(\Omega, \mathbb{R}^3) &= \{ \vec{w} : \text{div } \vec{w} = 0 \text{ in } \Omega \} \subseteq C^1(\Omega, \mathbb{R}^3), \\ \text{Irr}(\Omega, \mathbb{R}^3) &= \{ \vec{w} : \text{curl } \vec{w} = 0 \text{ in } \Omega \} \subseteq C^1(\Omega, \mathbb{R}^3),\end{aligned}$$

the Solenoidal e Irrotational vector fields, respectively. The elements $\vec{w} \in \vec{\mathfrak{M}}(\Omega)$ are locally the gradient of real valued harmonic functions. We write

$\text{Har}(\Omega, A) = \{ w : \Omega \rightarrow A, \Delta w = 0 \}$, where $A = \mathbb{R}, \mathbb{R}^3$ or \mathbb{H} , for the corresponding sets of harmonic functions defined in A . Since $\Delta = -D^2$, then left and right monogenic functions are harmonic.

The *monogenic completion operator*

$$\vec{S}_\Omega: \text{Har}(\Omega, \mathbb{R}) \rightarrow \text{Har}(\Omega, \mathbb{R}^3)$$

is given by

$$\begin{aligned}\vec{S}_\Omega[w_0](x) &= \text{Vec} \left(\int_0^1 -tDw_0(tx)x dt \right) \\ &= \int_0^1 -tDw_0(tx) \times x dt, \quad x \in \Omega.\end{aligned}$$

for harmonic functions w_0 defined in star-shaped open sets Ω with respect to the origin.

Let $\Omega \subset \mathbb{R}^3$ be an open set with smooth boundary and $w \in C^0(\Omega, \mathbb{H})$. The operator T_Ω defined by

$$T_\Omega[w](x) := - \int_\Omega \frac{\overline{y-x}}{4\pi|y-x|^3} w(y) dy, \quad x \in \Omega,$$

is called the Teodorescu transform, which acts like a right inverse of D . More even, if $w \in L^1(\Omega, \mathbb{H})$, then

$$DT_\Omega[w] = w,$$

weakly. Let $w \in C^1(\overline{\Omega}, \mathbb{H})$. The Cauchy-Bitsadze operator is defined as

$$F_{\partial\Omega}[w](x) := \int_{\partial\Omega} E(y-x) dy^* w(y), \quad x \in \mathbb{R}^3 \setminus \partial\Omega,$$

And $DF_{\partial\Omega}[w] = 0$.

The operator T_Ω can be decomposed in the following way

$$\begin{aligned}T_{0,\Omega}[\vec{w}](x) &= \int_{\Omega} E(y-x) \cdot \vec{w}(y) dy, \\ \vec{T}_{1,\Omega}[w_0](x) &= - \int_{\Omega} w_0(y) E(y-x) dy, \\ \vec{T}_{2,\Omega}[\vec{w}](x) &= - \int_{\Omega} E(y-x) \times \vec{w}(y) dy,\end{aligned}$$

where \cdot denotes the scalar (or inner) product of vectors and \times denotes the cross product. That is,

$$T_\Omega[w_0 + \vec{w}] = T_{0,\Omega}[\vec{w}] + \vec{T}_{1,\Omega}[w_0] + \vec{T}_{2,\Omega}[\vec{w}].$$

The following fact is essential in the construction of the right inverse of curl:

$$T_{0,\Omega}[\vec{w}] \in \text{Har}(\Omega, \mathbb{R}) \Leftrightarrow \vec{w} \in \text{Sol}(\Omega, \mathbb{R}^3).$$

Theorem

Let $\Omega \subseteq \mathbb{R}^3$ be a star-shaped open set. The operator

$$\vec{T}_{2,\Omega} - \vec{S}_{\Omega} T_{0,\Omega} \quad (2)$$

is a right inverse for the curl on the class of functions $\text{Sol}(\Omega, \mathbb{R}^3)$.

Where \vec{S}_{Ω} is the monogenic completion operator. Furthermore,
 $(\vec{T}_{2,\Omega} - \vec{S}_{\Omega} T_{0,\Omega}): \text{Sol}(\Omega, \mathbb{R}^3) \rightarrow \text{Sol}(\Omega, \mathbb{R}^3)$.

Then we can solve the homogeneous div-curl system under the assumptions $\vec{g} \in \text{Sol}(\Omega, \mathbb{R}^3)$:

$$\begin{aligned}\operatorname{div} \vec{W} &= 0, \\ \operatorname{curl} \vec{W} &= \vec{g},\end{aligned}\tag{3}$$

And the solution is given by

$$\vec{W} = \vec{T}_{2,\Omega}[\vec{g}] - \vec{S}_{\Omega} T_{0,\Omega}[\vec{g}] + \nabla h,$$

where $h \in \text{Har}(\Omega, \mathbb{R})$ is arbitrary.

Applying a correction, and with $g_0 \in C^0(\Omega, \mathbb{R})$, and $\vec{g} \in \text{Sol}(\Omega, \mathbb{R}^3)$. Then a general solution to the inhomogeneous Div-Curl system

$$\begin{aligned}\operatorname{div} \vec{W} &= g_0, \\ \operatorname{curl} \vec{W} &= \vec{g},\end{aligned}\tag{4}$$

is given by

$$\vec{W} = -\vec{T}_{1,\Omega}[g_0] + \vec{T}_{2,\Omega}[\vec{g}] - \vec{S}_\Omega T_{0,\Omega}[\vec{g}] + \nabla h,\tag{5}$$

where $h \in \text{Har}(\Omega, \mathbb{R})$ is arbitrary.

More even, \vec{W} is a weak solution of the div-curl system (4) when $g_0 \in L^2(\Omega, \mathbb{R})$, $\vec{g} \in L^2(\Omega, \mathbb{R}^3)$ and $\operatorname{div} \vec{g} = 0$ weakly.

Let $W : \Omega \rightarrow \mathbb{H}$, $f : \Omega \rightarrow \mathbb{R}$ a non-vanishing function. Define the **main Vekua equation** by

$$DW = \frac{Df}{f} \overline{W}.$$

The operator $D - \frac{Df}{f} C_H$ corresponding to this equation appears in different factorizations, for example when u is scalar

$$\begin{aligned} \nabla \cdot \sigma \nabla u &= \sigma^{1/2} \left(\Delta - \frac{\Delta \sigma^{1/2}}{\sigma^{1/2}} \right) \sigma^{1/2} u \\ &= -\sigma^{1/2} (D + M \frac{Df}{f}) \left(D - \frac{Df}{f} C_H \right) \sigma^{1/2} u, \end{aligned}$$

where $\sigma = f^2$, C_H is the quaternion conjugate operator and $M \frac{Df}{f}$ is the right multiplication operator.

We said that $W = W_0 + \vec{W} = W_0 + \sum_{i=1}^3 e_i W_i$ satisfies the main Vekua equation if and only if the scalar part W_0 and the vector part \vec{W} satisfy

$$\begin{aligned}\operatorname{div}(f\vec{W}) &= 0, \\ \operatorname{curl}(f\vec{W}) &= -f^2 \nabla \left(\frac{W_0}{f} \right).\end{aligned}$$

In other words,

$$D(f\vec{W}) = -f^2 \nabla \left(\frac{W_0}{f} \right).$$

And we have a div-curl system, we will give an explicit solution to solve them.

Let W such that $DW = \frac{Df}{f} \bar{W}$. Then



$$\nabla \cdot f^2 \nabla \frac{W_0}{f} = 0.$$

- W_0 is a solution of the stationary Schrödinger equation

$$-\Delta W_0 + r_0 W_0 = 0, \text{ with } r_0 = \frac{\Delta f}{f}.$$



$$\text{rot} \left(f^{-2} \text{rot} (f \vec{W}) \right) = 0.$$

- $u = \frac{W_0}{f} + f \vec{W}$ is a solution of the \mathbb{R} -linear Beltrami equation

$$Du = \frac{1 - f^2}{1 + f^2} D\bar{u}.$$

In the complex case, $\Omega \subset \mathbb{C}$, $W = W_0 + iW_1 : \Omega \rightarrow \mathbb{C}$ $f : \Omega \rightarrow \mathbb{R}$,
the main Vekua equation is given by

$$\bar{\partial}W = \frac{\partial f}{f} \bar{W},$$

where $\bar{\partial} = \frac{1}{2}(\partial_x + i\partial_y)$.

And the imaginary part W_1 also satisfies a conductivity and a Schrödinger equation:

$$\begin{aligned}\nabla \cdot f^{-2} \nabla (fW_1) &= 0, \\ -\Delta W_1 + r_1 W_1 &= 0,\end{aligned}$$

where $r_1 = \Delta \left(\frac{1}{f}\right) f$. And the corresponding *conjugate* Beltrami equation is

$$\bar{\partial}W = \frac{1 - f^2}{1 + f^2} \bar{\partial}W.$$

If the scalar part $W_0: \Omega \rightarrow \mathbb{R}$ is known, how to construct f^2 -hyperconjugate pairs?

Theorem

Let f^2 be a conductivity of class C^2 in an open star-shaped set $\Omega \subseteq \mathbb{R}^3$. Suppose that $W_0 \in C^2(\Omega, \mathbb{R})$ satisfies the conductivity equation $\nabla \cdot f^2 \nabla (W_0/f) = 0$ in Ω . Then exists a function \vec{W} such that $W_0 + \vec{W}$ such that

$$DW = \frac{Df}{f} \vec{W}.$$

The function $f \vec{W}$ is unique up to the gradient of a real harmonic function.

The assumptions of the above Theorem can be relaxed to say that $f, W_0 \in H^1(\Omega, \mathbb{R})$ and satisfy the conductivity equation weakly.

The following system of equations corresponds to the **static Maxwell system**, in a medium when just the permeability f^2 is variable:

$$\begin{aligned}\operatorname{div}(f^2 \vec{H}) &= 0, \\ \operatorname{div} \vec{E} &= 0, \\ \operatorname{curl} \vec{H} &= \vec{g}, \\ \operatorname{curl} \vec{E} &= f^2 \vec{H}.\end{aligned}\tag{6}$$

Here \vec{E} and \vec{H} represent electric and magnetic fields, respectively. We will apply our results to this system and to the double curl equation

$$\operatorname{curl}(f^{-2} \operatorname{curl} \vec{E}) = \vec{g},\tag{7}$$

which is immediate from the last two equations of (6).

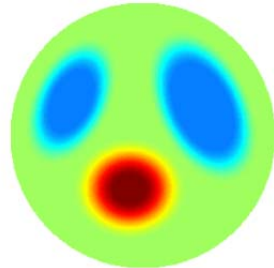
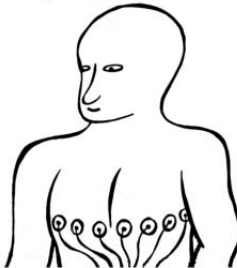
Theorem

Let the domain $\Omega \subseteq \mathbb{R}^3$ be a star-shaped open set, and assume that f^2 is a continuous proper conductivity in Ω . Let $\vec{g} \in L^2(\Omega, \mathbb{R}^3)$ satisfy $\operatorname{div} \vec{g} = 0$. Then there exists a generalized solution (\vec{E}, \vec{H}) to the system (6) and its general form is given by

$$\begin{aligned}\vec{E} &= \vec{T}_{2,\Omega}[f^2(\vec{B} + \nabla h)] - \vec{S}_{\Omega}[T_{0,\Omega}[f^2(\vec{B} + \nabla h)] + \nabla h_1, \\ \vec{H} &= \vec{B} + \nabla h,\end{aligned}\tag{8}$$

where h_1 is an arbitrary real valued harmonic function, h satisfy the inhomogeneous conductivity equation $\operatorname{div}(f^2 \nabla h) = -\nabla f^2 \cdot \vec{B}$ and $\vec{B} = \vec{T}_{2,\Omega}[\vec{g}] - \vec{S}_{\Omega}[T_{0,\Omega}[\vec{g}]]$.

In impedance tomography one aims to determine the internal structure of a body from electrical measurements on its surface. Such methods have a variety of different applications for instance in engineering and medical diagnostics.



Sobolev spaces

In particular, we are interested in the Sobolev spaces $H^1(\Omega)$ and $H^{1/2}(\partial\Omega)$, where

$$H^1(\Omega) = \{u \in L^2(\Omega) : \nabla u \in L^2(\Omega)\},$$
$$\|u\|_{H^1}^2 = \|u\|_{L^2}^2 + \|\nabla u\|_{L^2}^2.$$

While $H^{1/2}(\partial\Omega)$ are the "boundary value" functions in $H^1(\Omega)$:

$$H^{1/2}(\partial\Omega) = \{u \in L^2(\partial\Omega) \mid \exists \bar{u} \in H^1(\Omega) \text{ con } \bar{u}|_{\partial\Omega} = u\},$$
$$\|u\|_{H^{1/2}} = \inf \{\|\bar{u}\|_{H^1} \mid \bar{u}|_{\partial\Omega} = u\}.$$

In 1980 A. Calderón showed that the impedance tomography problem admits a clear and precise mathematical formulation:

Let $\Omega \subset \mathbb{R}^n$ be a bounded domain with connected complement and $\sigma : \Omega \rightarrow (0, \infty)$ is measurable, with σ and $1/\sigma$ bounded. Given the boundary values $\phi \in H^{1/2}(\partial\Omega)$ exists a unique solution $u \in H^1(\Omega)$ to

$$\begin{aligned}\nabla \cdot \sigma \nabla u &= 0 \text{ in } \Omega, \\ u|_{\partial\Omega} &= \phi.\end{aligned}$$

This so-called conductivity equation describes the behavior of the electric potential in a conductive body.

Theorem

(Plemelj-Sokhotski formula)

Let f be Hölder continuous on a sufficiently smooth surface $\partial\Omega$.
Then at any regular point $t \in \partial\Omega$ we have

$$n.t.-\lim_{x \rightarrow t} F_{\partial\Omega}[w](x) = \frac{1}{2}[\pm w(t) + S_{\partial\Omega}[w](t)],$$

where $x \in \Omega^\pm$, with $\Omega^+ = \Omega$ and $\Omega^- = \mathbb{R}^3 \setminus \overline{\Omega}$. The notation $n.t.-\lim_{x \rightarrow t}$ means that the limit should be taken non-tangential.

Holomorphic functions in the Plane and n-dimensional Space from the authors Klaus Gürlebeck, Klaus Habetha and Wolfgang Spröβig, 2008.

Define the following principal value integral obtained from the Cauchy-Bitsadze integral

$$S_{\partial\Omega}[w](x) := 2PV \int_{\partial\Omega} E(y-x) dy^* w(y), \quad x \in \partial\Omega,$$

From now on, $\Omega = B^3 = \{x \in \mathbb{R}^3 : |x| < 1\}$ and $\partial\Omega = S^2 = \{x \in \mathbb{R}^3 : |x| = 1\}$. Since the unitary normal vector to $\partial\Omega$ is $\eta(y) = y$, then the Cauchy kernel multiplied by the normal vector is reduced to

$$\frac{\overline{y-x}}{4\pi|y-x|^3} y = \frac{1}{4\pi} \left(\frac{1}{2|y-x|} + \frac{x \times y}{|y-x|^3} \right).$$

The following operators appear in the decomposition of the singular integral $S_{\partial\Omega}$

$$M[w](x) := \frac{1}{4\pi} \int_{\partial\Omega} \frac{w(y)}{|y-x|} ds_y,$$

$$M^1[w](x) := \text{PV} \frac{1}{2\pi} \int_{\partial\Omega} \frac{x_2 y_3 - x_3 y_2}{|y-x|^3} w(y) ds_y,$$

$$M^2[w](x) := \text{PV} \frac{1}{2\pi} \int_{\partial\Omega} \frac{x_3 y_1 - x_1 y_3}{|y-x|^3} w(y) ds_y,$$

$$M^3[w](x) := \text{PV} \frac{1}{2\pi} \int_{\partial\Omega} \frac{x_1 y_2 - x_2 y_1}{|y-x|^3} w(y) ds_y.$$

$$S_{\partial\Omega} = M + \sum_{i=1}^3 e_i M^i.$$

According to the article [3], we define the *Hilbert transform* \mathcal{H} of u as

$$\mathcal{H} : L^2(\partial\Omega, \mathbb{R}) \rightarrow L^2(\partial\Omega, \mathbb{R}^3)$$
$$\mathcal{H}(u) := \left(\sum_{i=1}^3 e_i M^i \right) (I + M)^{-1} u.$$

The authors of the article noticed that if we define the following strategic \mathbb{R} -valued function

$$h := 2(I + M)^{-1} u = 2(I + \text{Sc}(S_{\partial\Omega}))^{-1} u.$$

[3] *Hilbert Transforms on the Sphere with the Clifford Algebra Setting*, 2009, from the authors Tao Qian and Yan Yang.

Thus

$$\mathcal{H}(u) := \frac{1}{2} \text{Vec} (S_{\partial\Omega} h).$$

And the monogenic extension in Ω is given by the Cauchy operator $F_{\partial\Omega}(h)$. On the other hand, if we take the non-tangential limit then

$$\begin{aligned} \text{n.t. } \lim_{x \rightarrow t} F_{\partial\Omega}(h)(x) &= \frac{1}{2} (h(t) + S_{\partial\Omega} h(t)) \\ &= \frac{1}{2} h(t) + \frac{1}{2} \text{Sc}(S_{\partial\Omega} h(t)) + \frac{1}{2} \text{Vec}(S_{\partial\Omega} h(t)) \\ &= \frac{1}{2} (I + M)h(t) + \mathcal{H}(u)(t) \\ &= (u + \mathcal{H}(u))(t). \end{aligned}$$

Now, we are interested in to define the Hilbert transform associated to the main Vekua equation $DW = \frac{Df}{f} \overline{W}$:

From now on the conductivity $\sigma = f^2 \in H^1(\Omega, \mathbb{R})$. Suppose that $\varphi \in H^{1/2}(\partial\Omega, \mathbb{R})$ is known, and $\sigma, \frac{1}{\sigma}: \Omega \rightarrow (0, \infty)$ are measurables and bounded. Then there exists an unique extension $W_0 \in H^1(\Omega)$ such that

$$\begin{aligned} \nabla \cdot f^2 \nabla \left(\frac{W_0}{f} \right) &= 0 \text{ in } \Omega, \\ W_0 \Big|_{\partial\Omega} &= \varphi \text{ in } \partial\Omega. \end{aligned}$$

Using the decomposition of the Teodorescu operator

$T_\Omega: L^2(\Omega) \rightarrow H^1(\Omega)$, we have that

$$T_\Omega [-f^2 \nabla(W_0/f)] = T_{0,\Omega} [-f^2 \nabla(W_0/f)] + \vec{T}_{2,\Omega} [-f^2 \nabla(W_0/f)].$$

And the corresponding boundary value function of the scalar and the vectorial part of T_Ω are denoted as

$$u_0(t) = \lim_{x \rightarrow t} T_{0,\Omega} [-f^2 \nabla(W_0/f)],$$
$$\vec{u}(t) = \lim_{x \rightarrow t} \vec{T}_{2,\Omega} [-f^2 \nabla(W_0/f)]$$

for $t \in \partial\Omega$.

Notice that $g \in H^{1/2}(\partial\Omega)$, since the trace operator $\gamma: H^1(\Omega) \rightarrow H^{1/2}(\partial\Omega)$.

Definition

Finally, define the *Hilbert transform* \mathcal{H}_f associated to the main Vekua equation as

$$\begin{aligned} \mathcal{H}_f : H^{1/2}(\partial\Omega, \mathbb{R}) &\rightarrow L^2(\partial\Omega, \mathbb{R}^3) \\ \varphi &\rightarrow \vec{u} - \mathcal{H}(u_0), \end{aligned}$$

where u_0 and \vec{u} are built as above using the extension for φ as solution of the conductivity equation.

Analogously, like in the monogenic case

$$h_f := 2(I + M)^{-1}u_0.$$

Then

$$\mathcal{H}_f(\varphi) = \vec{u} - \frac{1}{\sigma} \text{Vec}(S_{\partial\Omega} h_f).$$

- In particular, when $f \equiv 1$ we have that $\mathcal{H}_f = \mathcal{H}$.
- The Hilbert transform associated to the main Vekua equation $\mathcal{H}_f: H^{1/2}(\partial\Omega, \mathbb{R}) \rightarrow L^2(\partial\Omega, \mathbb{R}^3)$ is a bounded operator.
- More even $\mathcal{H}_f(u) \in \text{Sol}(\partial\Omega, \mathbb{R}^3)$, for all $u \in H^{1/2}(\partial\Omega, \mathbb{R})$.

Theorem

Let $\Omega = B^3$. Let $f \in H^1(\Omega, \mathbb{R})$ a proper conductivity. Suppose that $\varphi \in H^{1/2}(\partial\Omega, \mathbb{R})$. Then there exists an extension $W = W_0 + \sum_{i=1}^3 e_i W_i$ in Ω such that

$$DW = \frac{Df}{f} \overline{W} \quad \text{in } \Omega,$$
$$W_0 \Big|_{\partial\Omega} = \varphi.$$

Sketch of the proof:

The extension of the vector part \vec{W} is obtained directly from the Hilbert transform \mathcal{H}_f and the integral operators T_Ω and $F_{\partial\Omega}$:

$$\begin{aligned} f \vec{W} &:= T_\Omega[-f^2 \nabla(W_0/f)] + F_{\partial\Omega}[\mathcal{H}_f(\varphi)]. \\ &= T_{0,\Omega}[-f^2 \nabla(W_0/f)] + \vec{T}_{2,\Omega}[-f^2 \nabla(W_0/f)] \\ &\quad + F_{\partial\Omega}[\vec{u} - \mathcal{H}(u_0)]. \end{aligned}$$

Thus

- $W := W_0 + \vec{W}$ satisfy the main Vekua equation.
- $f \vec{W}$ is purely vectorial.

Although the above extension is not unique, it is the only one that satisfies

$$\text{n.t.} - \lim_{x \rightarrow t} f \overrightarrow{W}(x) = \mathcal{H}_f(\varphi), \quad , x \in \partial\Omega.$$



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