



# Hyperbolic and dispersive models of shear shallow water

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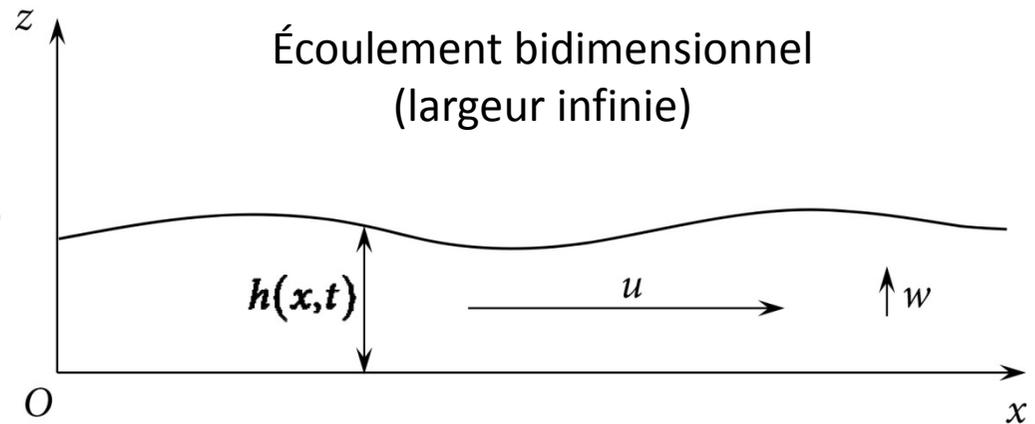
(joint work with Gaël Richard)

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# Modélisation

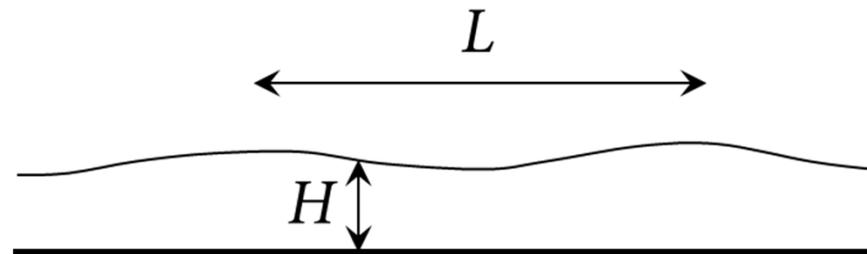
$$\text{Re} > 10^4$$

Fluide parfait incompressible



Faible profondeur

$$\varepsilon = \frac{H}{L} \ll 1.$$



# Deux Modèles classiques

## Saint-Venant (1871) : hyperbolique

(partie conservative) 
$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0,$$

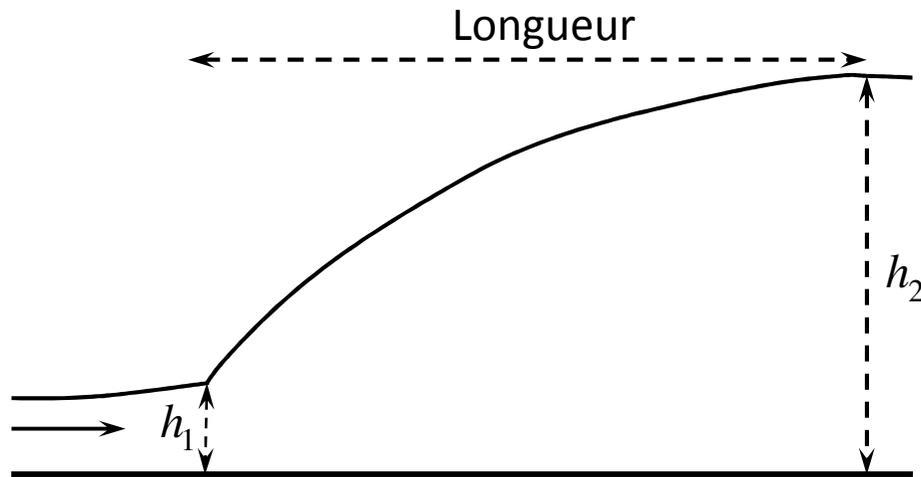
Pression hydrostatique 
$$\frac{\partial hU}{\partial t} + \frac{\partial (hU^2 + gh^2/2)}{\partial x} = 0.$$

## Serre (1953), Su & Gardner (1969), Green & Naghdi (1976) : dispersif

(partie conservative) 
$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (hU) = 0,$$

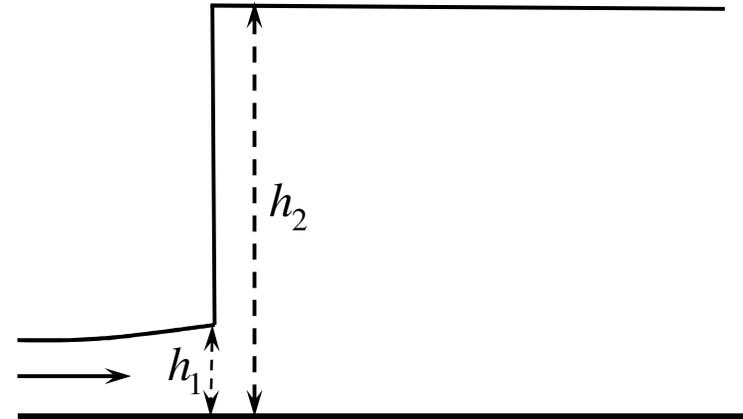
Pression non hydrostatique 
$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + \frac{h^2}{3} \frac{D^2 h}{Dt^2} \right) = 0.$$

## Ressaut réel



- Longueur non nulle
- Profil de profondeur
- Non stationnaire (oscillant)
- Faible écart à la relation de Bélanger (Hager *et al.* 1989)

## Ressaut selon Saint-Venant

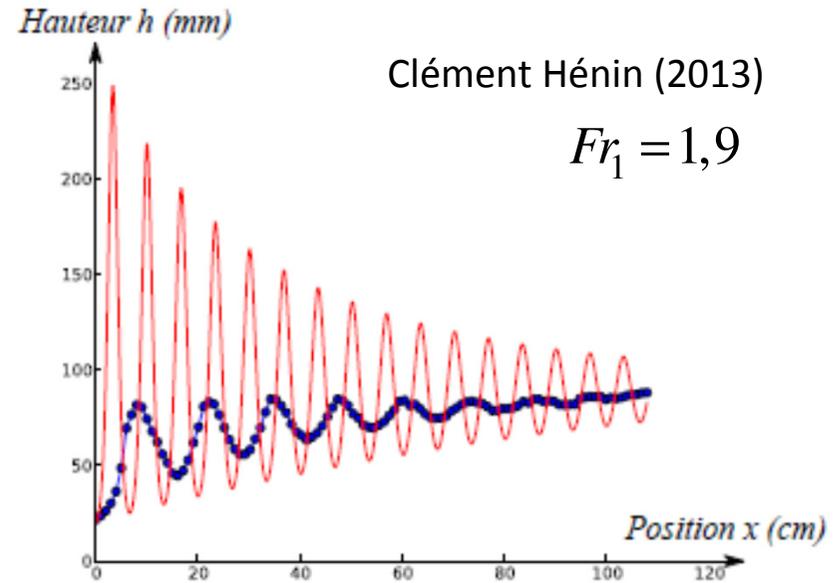


- Longueur nulle (choc)
- Pas de profil
- Stationnaire
- Relation de Bélanger

## Modèle de Green-Naghdi et ressaut ondulatoire

Amplitude : trop grande

Distance entre crêtes : trop petite



## Modèle de Green-Naghdi et onde solitaire

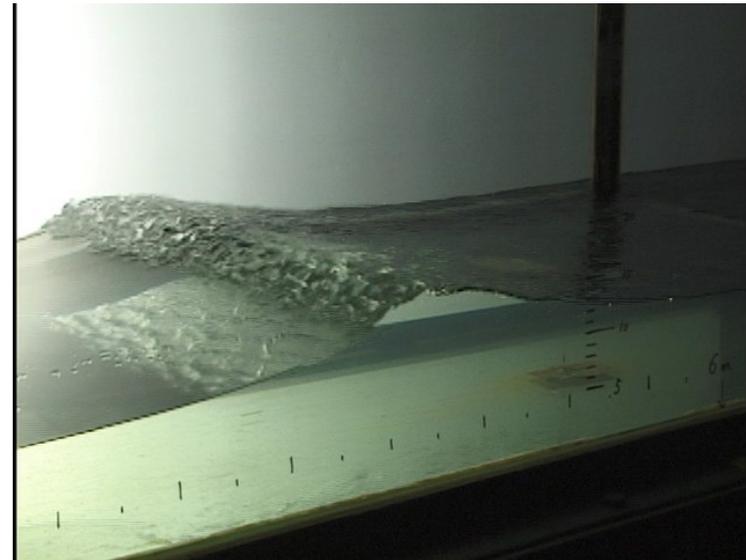
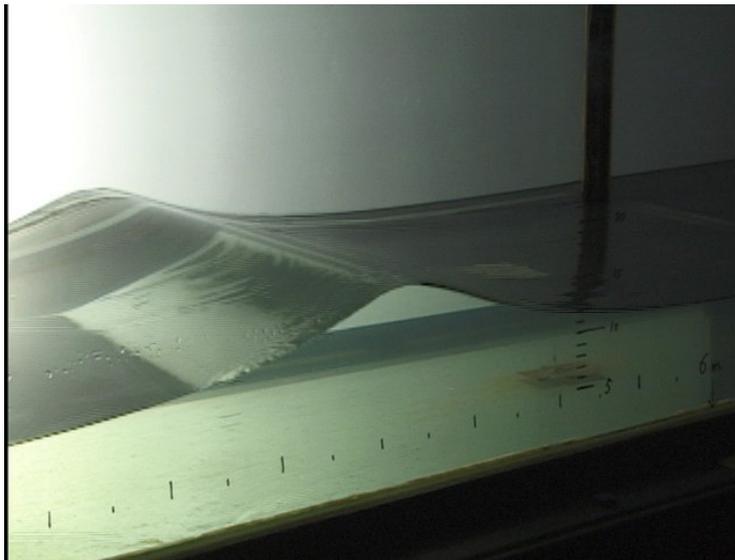
$F_\infty < 1,29$  Onde solitaire classique

Profil : petit écart avec l'expérience

(Daily & Stephan 1952)

Watanabe *et al.* (2007)

$F > 1,29$  Structure turbulente  
(micro-instabilité)



# Saint-Venant, Green-Naghdi

La vitesse horizontale est supposée **constante** dans la profondeur.

Pas de **cisaillement**.

Les modèles sont en désaccord avec l'expérience dès qu'apparaît une **structure turbulente**.

Pas **d'énergie turbulente**.

# Équations d'Euler adimensionnées

Adimensionnement  $\tilde{x} = \frac{x}{L}$ ;  $\tilde{z} = \frac{z}{H}$ ;  $\tilde{u} = \frac{u}{V}$ ;  $\tilde{w} = \frac{w}{\varepsilon V}$ ;  $\tilde{t} = \frac{Vt}{L}$ ;  $\tilde{p} = \frac{p}{\rho gH}$ ;  $V = \sqrt{gH}$ .

$$\left\{ \begin{array}{l} \frac{\partial \tilde{u}}{\partial \tilde{x}} + \frac{\partial \tilde{w}}{\partial \tilde{z}} = 0 \end{array} \right.$$

Masse

$$\left\{ \begin{array}{l} \frac{\partial \tilde{u}}{\partial \tilde{t}} + \frac{\partial \tilde{u}^2}{\partial \tilde{x}} + \frac{\partial \tilde{u}\tilde{w}}{\partial \tilde{z}} = -\frac{\partial \tilde{p}}{\partial \tilde{x}} \end{array} \right.$$

Quantité de mouvement

$$\left\{ \begin{array}{l} \varepsilon^2 \left( \frac{\partial \tilde{w}}{\partial \tilde{t}} + \frac{\partial \tilde{u}\tilde{w}}{\partial \tilde{x}} + \frac{\partial \tilde{w}^2}{\partial \tilde{z}} \right) = -1 - \frac{\partial \tilde{p}}{\partial \tilde{z}} \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial \tilde{E}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} (\tilde{u}\tilde{E} + \tilde{p}\tilde{u}) + \frac{\partial}{\partial \tilde{z}} (\tilde{w}\tilde{E} + \tilde{p}\tilde{w}) = 0 \end{array} \right.$$

Énergie

**Conditions aux limites**

où  $\tilde{E} = \frac{\tilde{u}^2}{2} + \varepsilon^2 \frac{\tilde{w}^2}{2} + \tilde{z}$

$$\tilde{p}(\tilde{h}) = 0; \quad \tilde{w}(0) = 0$$

$$\tilde{w}(\tilde{h}) = \frac{\partial \tilde{h}}{\partial \tilde{t}} + \tilde{u}(\tilde{h}) \frac{\partial \tilde{h}}{\partial \tilde{x}}$$

## Moyennisation sur la profondeur

$$\langle X \rangle = \frac{1}{h} \int_0^h X \, dz \quad \langle u \rangle = U$$

Masse  $\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h} \tilde{U}}{\partial \tilde{x}} = 0$  (exact)

Quantité de mouvement  $\frac{\partial \tilde{h} \tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left( \tilde{h} \langle \tilde{u}^2 \rangle + \int_0^{\tilde{h}} \tilde{p} \, d\tilde{z} \right) = 0$  (exact)

Énergie  $\frac{\partial}{\partial \tilde{t}} \left[ \tilde{h} \left( \frac{\langle \tilde{u}^2 \rangle}{2} + \frac{\tilde{h}}{2} + \varepsilon^2 \frac{\langle \tilde{w}^2 \rangle}{2} \right) \right] +$  (exact)

$$+ \frac{\partial}{\partial \tilde{x}} \left[ \frac{\tilde{h} \langle \tilde{u}^3 \rangle}{2} + \int_0^{\tilde{h}} \tilde{z} \tilde{u} \, d\tilde{z} + \int_0^{\tilde{h}} \tilde{p} \tilde{u} \, d\tilde{z} + \varepsilon^2 \frac{\tilde{h} \langle \tilde{u} \tilde{w}^2 \rangle}{2} \right] = 0$$

Décomposition de la vitesse :  $u(x, z, t) = U(x, t) + u_1(x, z, t)$

où  $\langle u \rangle = U$      $\langle u_1 \rangle = 0$      $u_1 = O(\varepsilon^\beta)$      $\tilde{u} = \tilde{U} + \varepsilon^\beta \tilde{u}_1$

$$\langle \tilde{u}^2 \rangle = \tilde{U}^2 + \varepsilon^{2\beta} \langle \tilde{u}_1^2 \rangle$$

$$\langle \tilde{u}^3 \rangle = \tilde{U}^3 + 3\varepsilon^{2\beta} \tilde{U} \langle \tilde{u}_1^2 \rangle + \varepsilon^{3\beta} \langle \tilde{u}_1^3 \rangle$$

Masse  $\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{x}} = 0$  (exact)

Quantité de mouvement  $\frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left( \tilde{h}\tilde{U}^2 + \epsilon^{2\beta} \tilde{h}^3 \langle \tilde{\Psi}_1^2 \rangle + \int_0^{\tilde{h}} \int_0^{\tilde{h}} \tilde{p} \, d\tilde{z} d\tilde{\xi} \right) = 0$  (exact)

Énergie  $\frac{\partial}{\partial \tilde{t}} \left[ \tilde{h} \left( \frac{\tilde{U}^2}{2} + \epsilon^{2\beta} \frac{\langle \tilde{h}^2 \tilde{\Psi}_1^2 \rangle}{2} + \frac{\tilde{h}}{2} + \epsilon^2 \frac{\langle \tilde{w}^2 \rangle}{2} \right) \right] +$  (exact)

$+ \frac{\partial}{\partial \tilde{x}} \left[ \frac{\tilde{h}\tilde{U}^3}{2} + \frac{3}{2} \epsilon^{2\beta} \tilde{h}^3 \tilde{U} \langle \tilde{\Psi}_1^2 \rangle + \epsilon^{3\beta} \frac{\tilde{h} \langle \tilde{h}^2 \tilde{U}_1^3 \rangle}{2} + \int_0^{\tilde{h}} \int_0^{\tilde{h}} \tilde{z} \tilde{u} \tilde{z} \, d\tilde{z} d\tilde{\xi} + \int_0^{\tilde{h}} \int_0^{\tilde{h}} \tilde{p} \tilde{u} \, d\tilde{z} d\tilde{\xi} + \epsilon^2 \frac{\tilde{h} \langle \tilde{h} \langle \tilde{w}^2 \rangle^2 \rangle}{2} \right] = 0$

**Pression  
Enstrophie**

$$\tilde{p}(\tilde{z}) = \underbrace{u_1^2 \tilde{h} - \tilde{z}}_{\text{hydrostatique}} + \underbrace{\frac{\epsilon^2 \tilde{p}_{NH}}{g}}_{\text{non-hydrostatique}}$$

$$\int_0^{\tilde{h}} (\tilde{h} - \tilde{z}) \, d\tilde{z} = \frac{\tilde{h}^2}{2}$$

Masse  $\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{x}} = 0$  (exact)

Quantité de mouvement  $\frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left( \tilde{h}\tilde{U}^2 + \varepsilon^{2\beta} \tilde{h}^3 \tilde{\Psi} + \frac{\tilde{h}^2}{2} + \varepsilon^2 \int_0^{\tilde{h}} \tilde{p}_{NH} d\tilde{z} \right) = 0$  (exact)

Énergie  $\frac{\partial}{\partial \tilde{t}} \left[ \tilde{h} \left( \frac{\tilde{U}^2}{2} + \varepsilon^{2\beta} \frac{\tilde{h}^2 \tilde{\Psi}}{2} + \frac{\tilde{h}}{2} + \varepsilon^2 \frac{\langle \tilde{w}^2 \rangle}{2} \right) \right] +$  (exact)

$+ \frac{\partial}{\partial \tilde{x}} \left[ \frac{\tilde{h}\tilde{U}^3}{2} + \frac{3}{2} \varepsilon^{2\beta} \tilde{h}^3 \tilde{U} \tilde{\Psi} + \varepsilon^{3\beta} \frac{\tilde{h} \langle \tilde{u}_1^3 \rangle}{2} + \right.$

$\left. + \tilde{h}^2 \tilde{U} + \varepsilon^2 \tilde{U} \int_0^{\tilde{h}} \tilde{p}_{NH} d\tilde{z} + \varepsilon^{2+\beta} \int_0^{\tilde{h}} \tilde{p}_{NH} \tilde{u}_1 d\tilde{z} + \varepsilon^2 \frac{\tilde{h} \langle \tilde{u} \tilde{w}^2 \rangle}{2} \right] = 0$

$\tilde{p}_{NH} = - \int_{\tilde{h}}^{\tilde{z}} \left( \frac{\partial \tilde{w}}{\partial \tilde{t}} + \frac{\partial \tilde{u} \tilde{w}}{\partial \tilde{x}} + \frac{\partial \tilde{w}^2}{\partial \tilde{z}} \right) d\tilde{z}$   $\tilde{w}(\tilde{z}) ?$

$$\frac{\partial \tilde{u}}{\partial \tilde{x}} + \frac{\partial \tilde{w}}{\partial \tilde{z}} = 0$$

$$\tilde{w}(\tilde{z}) = - \int_0^{\tilde{z}} \frac{\partial \tilde{u}}{\partial \tilde{x}} d\tilde{z}$$

$$\tilde{u} = \tilde{U} + \varepsilon^\beta \tilde{u}_1$$

$$\tilde{w}(\tilde{z}) = -\tilde{z} \frac{\partial \tilde{U}}{\partial \tilde{x}} - \varepsilon^\beta \int_0^{\tilde{z}} \frac{\partial \tilde{u}_1}{\partial \tilde{x}} d\tilde{z}$$

$$\dot{h} = \frac{\partial h}{\partial t} + U \frac{\partial h}{\partial x} = -h \frac{\partial U}{\partial x}$$

$$\tilde{w}(\tilde{z}) = \tilde{z} \frac{\dot{\tilde{h}}}{\tilde{h}} - \varepsilon^\beta \int_0^{\tilde{z}} \frac{\partial \tilde{u}_1}{\partial \tilde{x}} d\tilde{z}$$

$$\tilde{p}_{NH} = \underbrace{\frac{\tilde{h}^2 - \tilde{z}^2}{2} \frac{\ddot{\tilde{h}}}{\tilde{h}}}_{\text{Green-Naghdi}} + \varepsilon^\beta \tilde{p}_{NGN} + O(\varepsilon^{2\beta})$$

$$\varepsilon^2 \int_0^{\tilde{h}} \tilde{p}_{NH} d\tilde{z} = \underbrace{\varepsilon^2 \frac{\tilde{h}^2 \ddot{\tilde{h}}}{3}}_{\text{Green-Naghdi}} + \varepsilon^{2+\beta} \int_0^{\tilde{h}} \tilde{p}_{NGN} d\tilde{z} + O(\varepsilon^{2+2\beta})$$

Termes  $O(\varepsilon^{2+\beta})$

$$\int_0^{\tilde{h}} \tilde{p}_{NGN} d\tilde{z} = \frac{\partial}{\partial \tilde{x}} \frac{D\tilde{A}}{D\tilde{t}} + 2\tilde{A} \frac{\partial}{\partial \tilde{x}} \left( \frac{\dot{\tilde{h}}}{\tilde{h}} \right)$$

$$\text{où } \tilde{A} = \int_0^{\tilde{h}} d\tilde{z} \int_{\tilde{h}}^{\tilde{z}} d\tilde{z} \int_0^{\tilde{z}} \tilde{u}_1 d\tilde{z} = \int_0^{\tilde{h}} \frac{\tilde{z}^2}{2} \tilde{u}_1 d\tilde{z}$$

$$\varepsilon^2 \langle \tilde{w}^2 \rangle = \varepsilon^2 \frac{\dot{\tilde{h}}^2}{3} + 2\varepsilon^{2+\beta} \frac{\dot{\tilde{h}}}{\tilde{h}^2} \frac{\partial \tilde{A}}{\partial \tilde{x}} + O(\varepsilon^{2+2\beta})$$

$$\varepsilon^{2+\beta} \int_0^{\tilde{h}} \tilde{p}_{NH} \tilde{u}_1 d\tilde{z} = -\varepsilon^{2+\beta} \tilde{A} \frac{\ddot{\tilde{h}}}{\tilde{h}} + O(\varepsilon^{2+2\beta})$$

$$\varepsilon^2 \tilde{h} \langle \tilde{u} \tilde{w}^2 \rangle = \varepsilon^2 \frac{\tilde{h} \tilde{U} \dot{\tilde{h}}^2}{3} + 2\varepsilon^{2+\beta} \tilde{A} \left( \frac{\dot{\tilde{h}}}{\tilde{h}} \right)^2 + 2\varepsilon^{2+\beta} \frac{\dot{\tilde{h}}}{\tilde{h}} \tilde{U} \frac{\partial \tilde{A}}{\partial \tilde{x}} + O(\varepsilon^{2+2\beta})$$

Finalemment :

$$\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{x}} = 0$$

$$\frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} [\tilde{h}\tilde{U}^2 + \tilde{P}] = O(\varepsilon^{2+2\beta})$$

$$\frac{\partial \tilde{h}\tilde{e}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left[ \tilde{h}\tilde{U} \left( \tilde{e} + \frac{\tilde{P}}{\tilde{h}} \right) + \varepsilon^{2+\beta} \tilde{A} \left( \frac{\dot{\tilde{h}}^2}{\tilde{h}^2} - \frac{\ddot{\tilde{h}}}{\tilde{h}} \right) + \varepsilon^{3\beta} \frac{\tilde{h} \langle \tilde{u}_1^3 \rangle}{2} \right] = O(\varepsilon^{2+2\beta})$$

où

$$\tilde{e} = \frac{\tilde{U}^2}{2} + \varepsilon^{2\beta} \frac{\tilde{h}^2 \tilde{\Psi}}{2} + \frac{\tilde{h}}{2} + \varepsilon^2 \frac{\dot{\tilde{h}}^2}{6} + \varepsilon^{2+\beta} \frac{\dot{\tilde{h}}}{\tilde{h}^2} \frac{\partial \tilde{A}}{\partial \tilde{x}}$$

$$\tilde{P} = \frac{\tilde{h}^2}{2} + \varepsilon^{2\beta} \tilde{h}^3 \tilde{\Psi} + \varepsilon^2 \frac{\tilde{h}^2 \ddot{\tilde{h}}}{3} + \varepsilon^{2+\beta} \left[ \frac{\partial}{\partial \tilde{x}} \frac{D\tilde{A}}{D\tilde{t}} + 2\tilde{A} \frac{\partial}{\partial \tilde{x}} \left( \frac{\dot{\tilde{h}}}{\tilde{h}} \right) \right]$$

## Valeur de $\beta$

Vorticité : 
$$\omega = \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x}$$

Équation d'évolution de la vorticité : 
$$\frac{D\omega}{Dt} = 0$$

Si, à  $t = 0$ ,  $\omega = O(\varepsilon^\alpha)$ , alors pour  $t > 0$ ,  $\omega = O(\varepsilon^\alpha)$ . 
$$\tilde{\omega} = \frac{\omega}{\varepsilon^\alpha} \frac{H}{V}$$

$$\varepsilon^\beta \frac{\partial \tilde{u}_1}{\partial \tilde{z}} = \underbrace{\varepsilon^\alpha \tilde{\omega}}_{\text{terme rotationnel}} + \varepsilon^2 \underbrace{\frac{\partial \tilde{w}}{\partial \tilde{x}}}_{\text{terme irrotationnel}} \quad \beta = \min(\alpha, 2)$$

Si  $\alpha \geq 2$        $\beta = 2$

Si  $\alpha < 2$        $\beta = \alpha$       
$$\frac{\partial \tilde{u}_1}{\partial \tilde{z}} = \tilde{\omega} + O(\varepsilon^{2-\alpha})$$
      Le cisaillement est essentiellement dû à la vorticité.

Si  $\alpha = 0$   $\beta = 0$  Le problème n'est pas fermé.

Si  $\alpha > 0$   $\beta > 0$  Alors : à l'ordre  $O(1)$   $\longrightarrow$  Saint-Venant (1871)

à un ordre supérieur :

Si  $\alpha < 1$  à l'ordre  $O(\varepsilon^{2\beta})$   $\longrightarrow$  Teshukov (2007)  
Richard & Gavriluyk (2013)

Si  $\alpha > 1$  à l'ordre  $O(\varepsilon^2)$   $\longrightarrow$  Su-Gardner (1969),  
Green-Naghdi (1976)

à l'ordre  $O(\varepsilon^{2+\beta})$   $\longrightarrow$  Nouveau modèle

Si  $\alpha = 1$  à l'ordre  $O(\varepsilon^2)$   $\longrightarrow$  Teshukov-Green-Naghdi

à l'ordre  $O(\varepsilon^3)$   $\longrightarrow$  Termes  $O(\varepsilon^{2+\beta})$   
+ Termes  $O(\varepsilon^{3\beta})$

Cf. Castro & Lannes (2014)

$$\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{x}} = 0$$

$$\frac{\partial \tilde{h}\tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} [\tilde{h}\tilde{U}^2 + \tilde{P}] = O(\varepsilon^{2+2\beta})$$

$$\frac{\partial \tilde{h}\tilde{e}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left[ \tilde{h}\tilde{U} \left( \tilde{e} + \frac{\tilde{P}}{\tilde{h}} \right) + \varepsilon^{2+\beta} \tilde{A} \left( \frac{\dot{\tilde{h}}^2}{\tilde{h}^2} - \frac{\ddot{\tilde{h}}}{\tilde{h}} \right) + \varepsilon^{3\beta} \frac{\tilde{h} \langle \tilde{u}_1^3 \rangle}{2} \right] = O(\varepsilon^{2+2\beta})$$

$$\tilde{e} = \frac{\tilde{U}^2}{2} + \varepsilon^{2\beta} \frac{\tilde{h}^2 \tilde{\Psi}}{2} + \frac{\tilde{h}}{2} + \varepsilon^2 \frac{\dot{\tilde{h}}^2}{6} + \varepsilon^{2+\beta} \frac{\dot{\tilde{h}}}{\tilde{h}^2} \frac{\partial \tilde{A}}{\partial \tilde{x}}$$

$$\tilde{P} = \frac{\tilde{h}^2}{2} + \varepsilon^{2\beta} \tilde{h}^3 \tilde{\Psi} + \varepsilon^2 \frac{\tilde{h}^2 \ddot{\tilde{h}}}{3} + \varepsilon^{2+\beta} \left[ \frac{\partial}{\partial \tilde{x}} \frac{D\tilde{A}}{D\tilde{t}} + 2\tilde{A} \frac{\partial}{\partial \tilde{x}} \left( \frac{\dot{\tilde{h}}}{\tilde{h}} \right) \right]$$

# Le Modèle hyperbolique

$$0 < \beta < 1$$

Teshukov (2007)

Richard & Gavrilyuk (2013)

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left[ hU^2 + h^3 \Psi(\varphi + \Phi) + \frac{gh^2}{2} \right] = 0$$

$$\frac{\partial he}{\partial t} + \frac{\partial}{\partial x} \left[ hU \left( e + \frac{P}{h} \right) \right] = 0 - \frac{\Phi}{\varphi + \Phi} C_r U^2 |U|$$

$$e \equiv \frac{1}{2} \left[ U^2 + gh + h^2 \Psi(\varphi + \Phi) \right]$$

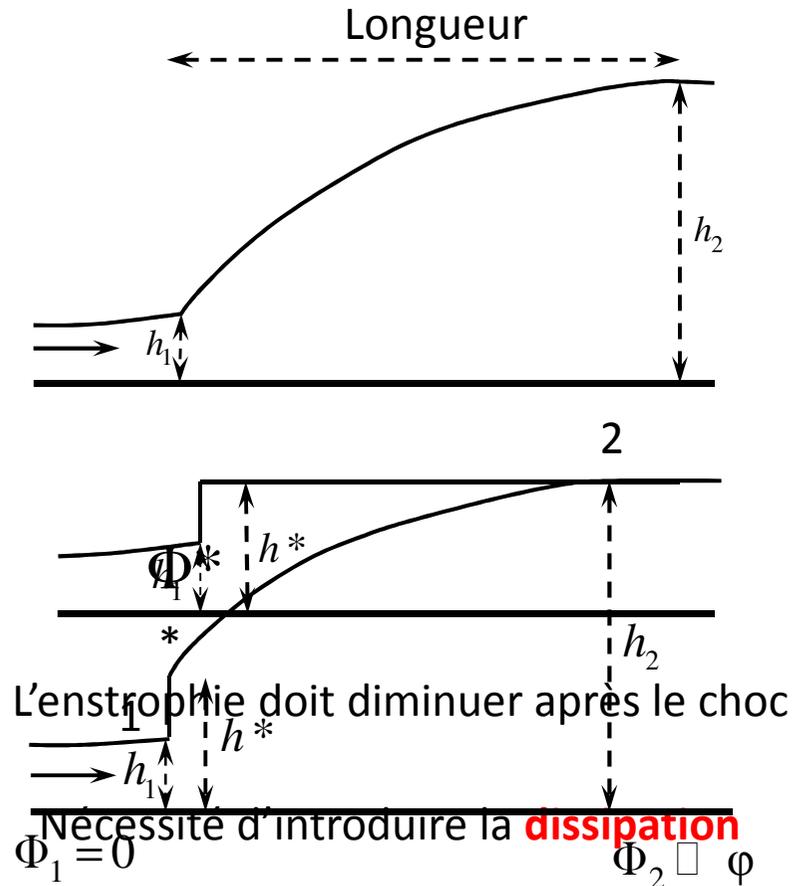
$$P \equiv \frac{gh^2}{2} + h^3 \Psi(\varphi + \Phi)$$

Équation d'évolution de l'énstrophie

$$\frac{D\Phi}{Dt} = 0 - 2C_r \frac{\Phi}{\varphi + \Phi} \frac{U^2 |U|}{h^3} \quad \varphi = Cte$$

L'énstrophie est créée par les **chocs**.

## Ressaut hydraulique



## Résultats

### Profil du ressaut hydraulique

Comparaison avec la loi expérimentale de Chanson (2011)

$$\frac{h - h_1}{h_2 - h_1}$$

Disparition du rouleau turbulent si

$$\tilde{\Phi} < \tilde{\Phi}_{cr} \approx 2.5 \cdot 10^{-3}$$

### Oscillations de la position du ressaut hydraulique

Fréquence adimensionnée (nombre de Strouhal)

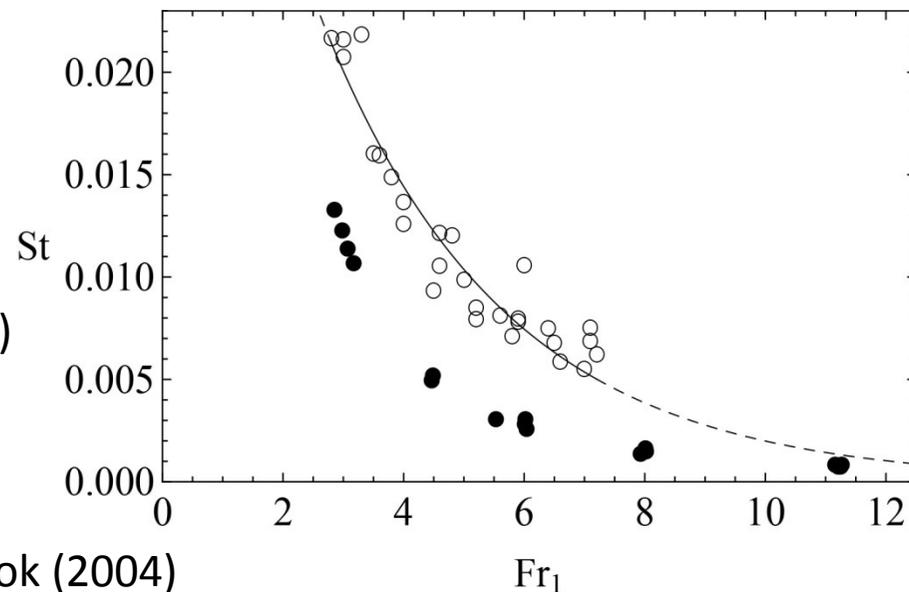
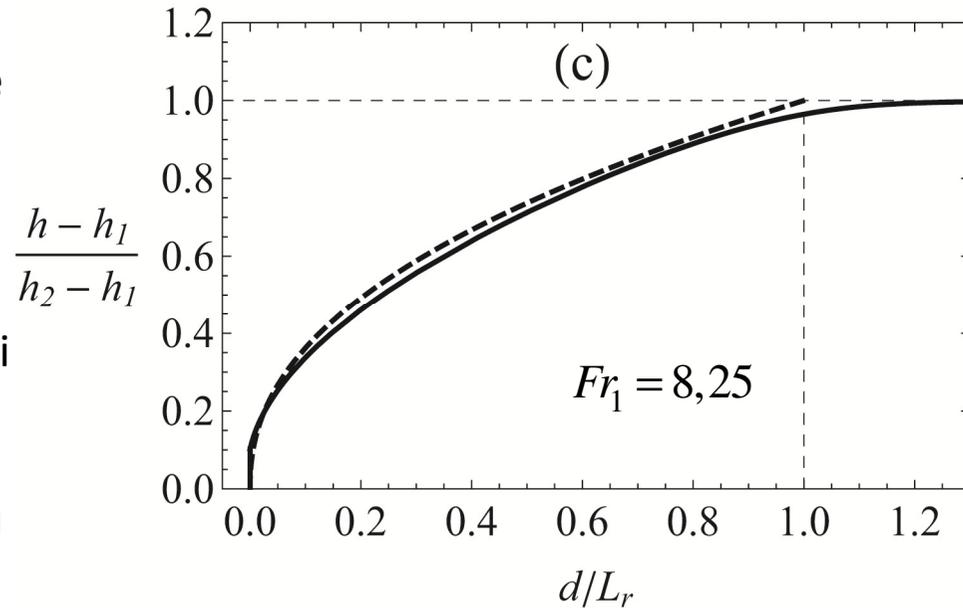
$$St = \frac{h_1^2 f}{q}$$

Comparaison avec les résultats expérimentaux de Zhang *et al.* (2013)

Pas d'oscillations pour  $Fr_1 < 1,5$

Oscillations pour  $Fr_1 > 1,5$

En accord avec les expériences de Mok (2004)

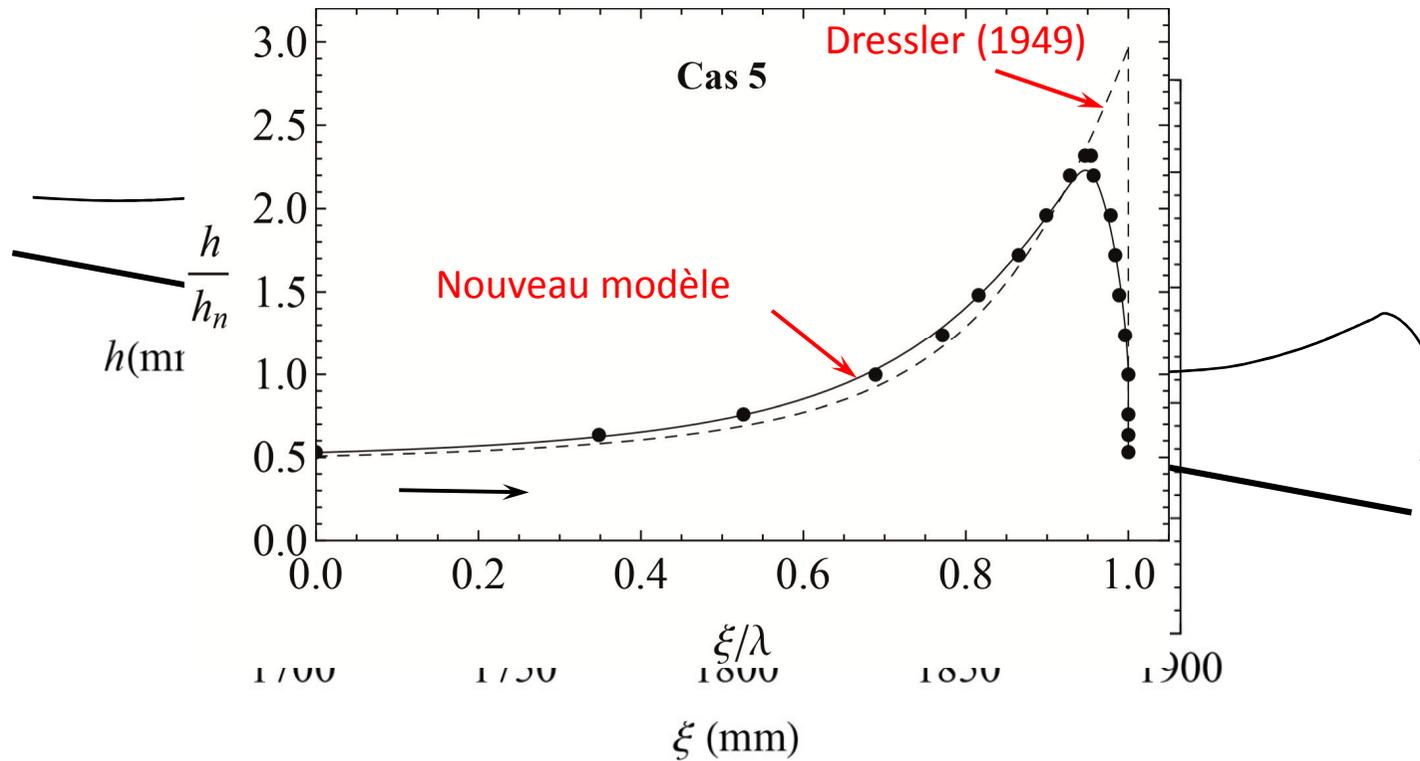


# Application aux trains de rouleaux (roll-waves)

$g \rightarrow g \cos \theta$

pente  $\text{tg} \theta$

Terme dissipatif supplémentaire :  $gh \sin \theta - C_f U |U|$   
 $(gh \sin \theta - C_f U |U|)U$



# Le Modèle dispersif

$1 < \beta \leq 2$  On garde les termes  $O(\varepsilon^{2+\beta})$   
 $3\beta > 2 + \beta$   
 $2\beta \leq 2 + \beta$   
 (cas conservatif)

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} [hU^2 + P] = 0$$

$$\frac{\partial he}{\partial t} + \frac{\partial}{\partial x} \left[ hU \left( e + \frac{P}{h} \right) + A \left( \frac{\dot{h}^2}{h^2} - \frac{\ddot{h}}{h} \right) \right] = 0$$

$$e = \frac{U^2}{2} + \frac{h^2 \Psi}{2} + \frac{gh}{2} + \frac{\dot{h}^2}{6} + \frac{\dot{h}}{h^2} \frac{\partial A}{\partial x}$$

$$P = \frac{gh^2}{2} + h^3 \Psi + \frac{h^2 \ddot{h}}{3} + \left[ \frac{\partial}{\partial x} \frac{DA}{Dt} + 2A \frac{\partial}{\partial x} \left( \frac{\dot{h}}{h} \right) \right]$$

Équation d'évolution de l'énstrophie

$$\frac{D\Psi}{Dt} = \frac{2A}{h^3} \frac{\partial}{\partial x} \left( \frac{\ddot{h}}{h} \right)$$

Si on néglige les termes  $O(\varepsilon^{2+\beta})$ , l'énstrophie se conserve.

# Profil de l'onde solitaire

Su-Gardner

$$h = h_\infty + a \operatorname{sech}^2 \left[ \frac{x}{h_\infty} \sqrt{\frac{3a}{4(h_\infty + a)}} \right]$$

Boussinesq (1872)

$$h = h_\infty + a \operatorname{sech}^2 \left[ \frac{x}{h_\infty} \sqrt{\frac{3a}{4h_\infty}} \right]$$

$$\tilde{a} = \frac{a}{h_\infty} = F^2 - 1$$

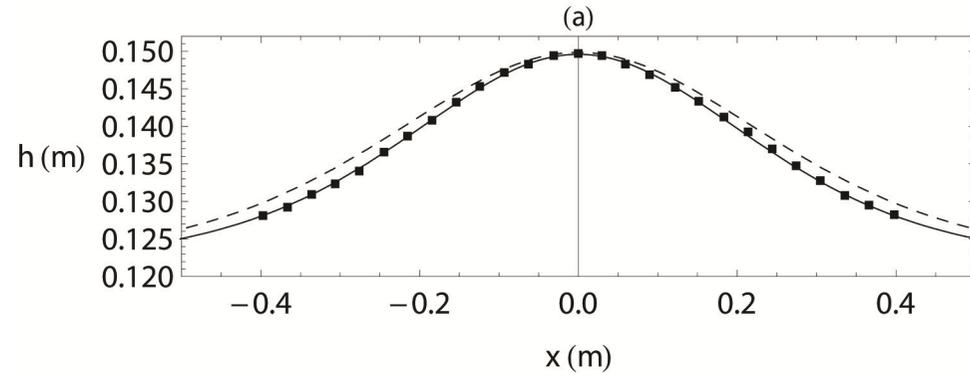
Nouveau Modèle

$$A = A_0 h^2 \quad \varphi = \Phi_\infty \quad \tilde{A}_0 = A_0 / \sqrt{gh_\infty^3}$$

$$h = h_\infty + \frac{2a(F^2 - 1 - 3\tilde{\varphi})}{F^2 - 1 - (3 + \tilde{a}^2)\tilde{\varphi} + [F^2 - 1 - (3 - \tilde{a}^2)\tilde{\varphi}] \operatorname{ch} \left[ \frac{x}{h_\infty} \sqrt{3 \frac{F^2 - 1 - 3\tilde{\varphi}}{F^2 + 18\tilde{A}_0 F}} \right]}$$

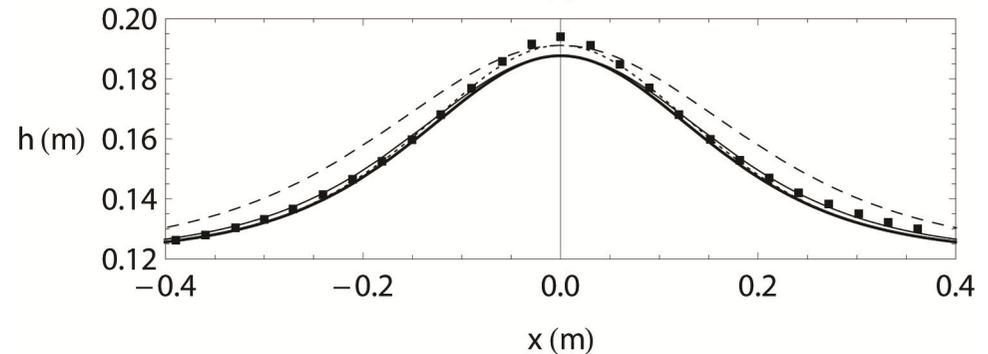
$$\text{Si } \varphi = 0, \quad h = h_\infty + a \operatorname{sech}^2 \left[ \frac{x}{h_\infty} \sqrt{\frac{3a}{4h_\infty + a + 18\tilde{A}_0 \sqrt{h_\infty} \sqrt{a + h_\infty}}} \right]$$

$$F = 1,11; \quad \tilde{a} = 0,23; \quad \tilde{A}_0 = -0,0116; \quad \tilde{\varphi} = 5,33 \cdot 10^{-4}.$$



$$F = 1,25; \quad \tilde{a} = 0,6; \quad \tilde{A}_0 = -0,0252(-0,020); \quad \tilde{\varphi} = 5,19 \cdot 10^{-3}.$$

(b)



$$F = 1,28$$

Pas de structure turbulente  
onde solitaire stable

$$F = 1,30$$

Structure turbulente  
Onde solitaire instable

Apparition d'une structure turbulente si

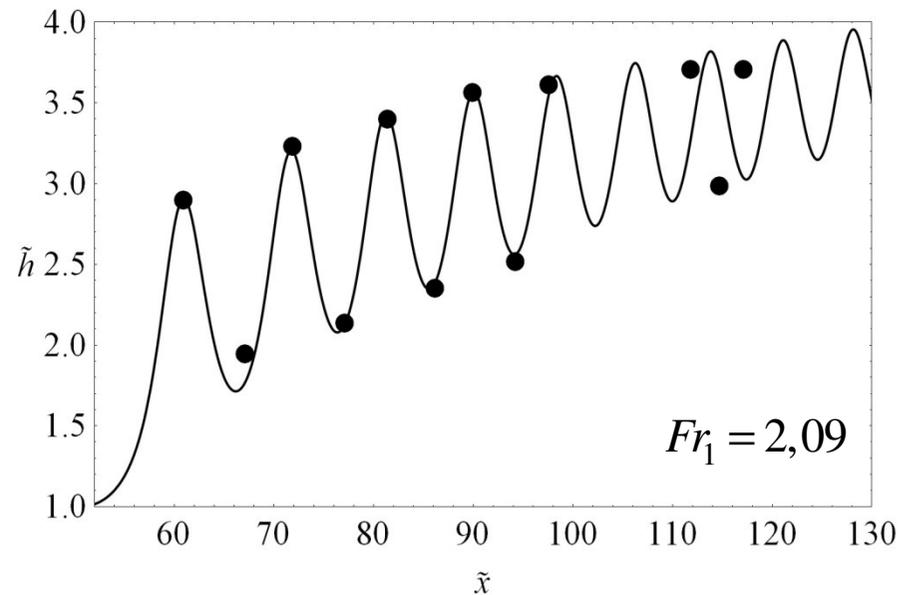
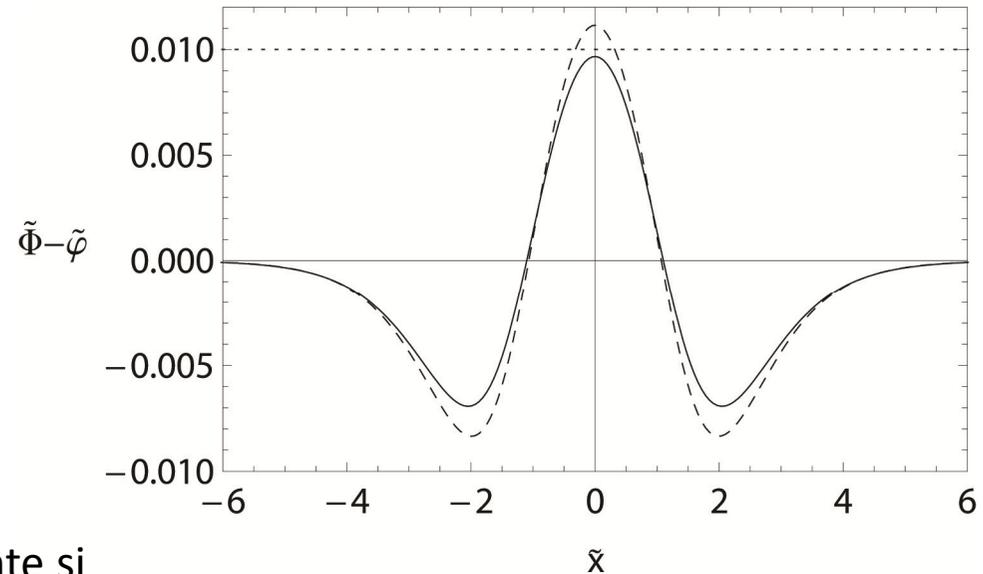
$$\tilde{\Phi} - \tilde{\varphi} > 10^{-2}$$

## Profil du ressaut ondulaire

(avec dissipation)

Comparaison avec les résultats  
expérimentaux de Chanson (1993)

Le bon accord des distances crête à crête  
est dû **aux termes**  $O(\varepsilon^{2+\beta})$  **en A.**



## Conclusion et Perspectives

- Importance de la prise en compte du cisaillement ;
- Structures turbulentes (rouleaux, etc.) ;
- Perspective : modélisation du déferlement dans le cadre d'un modèle dispersif ;
- Modèle 2D à élaborer.