### Well balancedness and error balance observations and ideas related to the approximation of (hyperbolic) balance laws

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### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

with some initial data

### $u(t = 0, x) = u_0(x)$

and appropriately prescribed boundary data





#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

short notation for the source

 $S(u; d) = S(u, \partial_x u, \partial_t u, etc.; d)$ 

external data d = d(x) provided in some form (often not analytically)







#### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

short notation for the source

 $S(u; d) = S(u, \partial_x u, \partial_t u, etc.; d)$ 





#### Iwate prefecture (2011 Tohoku tsunami) L. Arpaia and MR, J.Comput.Phys. 2020

#### external data d = d(x) provided in some form (often not analytically)



### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

hyperbolic balance law

 $\partial_{\mathsf{t}} \mathscr{U}(\mathsf{u};\mathsf{d}) + \partial_{\mathsf{x}} \mathscr{F}(\mathsf{u};\mathsf{d}) \leq 0$ 

entropy pair/inequality





# $A := f_u = R \Lambda L = R \operatorname{diag}(\lambda_i) L$

### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

what is consistency for this problem ?

#### f(u) = const - u = const

no longer admissible states





### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

particular (un)steady states

#### $\partial_{x} f(u) + S(u; d) = 0$





### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

particular (un)steady states

#### $\partial_{x} f(u) + S(u; d) = 0$







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### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

what is consistency for this problem ?

#### Well-Balanced and related questions:

- natural way of expressing consistency for balance laws
- most basic formulation generalised notion of consistency wrt constants
- one problem is: what should be constant here ?
- another problem is : how about multi D ?





#### $\partial_t u + a \partial_x u - q(x) = 0$ , a > 0

Once upon a time ... :

P.L. Roe. Upwind differencing schemes for hyperbolic conservation laws with source terms. In Claude Carasso, Denis Serre, and Pierre-Arnaud Raviart, editors, Nonlinear Hyperbolic *Problems*, pages 41–51, Berlin, Heidelberg, 1987. Springer Berlin Heidelberg.





### $\partial_t u + a \partial_x u - q(x) = 0$ , a > 0

Once upon a time ... :

$$u_{i}^{n+1} = u_{i}^{n} - v(u_{i}^{n} - u_{i-1}^{n}) + \frac{1}{2}v(1 - v)S_{i-1} - \frac{1}{2}v(1 - v)S_{i}$$
$$+ [(1 - \frac{1}{2}v)q_{i} + \frac{1}{2}vq_{i-1}]\Delta t$$

Upwind fluxes, source integration along characteristics, piecewise linear data, constant source Ínia



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#### $\partial_t u + a \partial_x u - q(x) = 0$ , a > 0

Once upon a time ... :

several authors [6,7,8] have felt the attraction of considering data which is in piecewise equilibrium. That is, the data is projected into a representation such that the steady flow equations are satisfied within each In our simple model equation, that means choosing cell.

$$S_i = \frac{q_i \Delta x}{a} = \frac{q_i \Delta t}{v}$$









### $\partial_t u + a \partial_x u - q(x) = 0$ , a > 0

Once upon a time ... :

$$u_{i}^{n+1} = u_{i}^{n} - \frac{\Delta t}{\Delta x} \overset{\emptyset}{i} - \frac{1}{2}$$

 $\phi_{i-\frac{1}{2}} = a(u_i - u_{i-1}) - \frac{1}{2}\Delta x(q_{i-1} + q_i)$ 





we can measure the extent to which they are out of equilibrium (with each other now, now internally) by the quantity (17)



### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

#### Residual distribution/fluctuation splitting:

$$\phi^{i\pm 1/2} = \int_{\Delta_{i\pm 1/2} x} (\partial_x f + S) dx$$

$$\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \frac{\max(a, 0)}{a} \phi^{i-1/2} + \frac{\min(a, 0)}{a} \phi^{i+1/2} = 0$$





continuous approximation

#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

#### Residual distribution/fluctuation splitting:

$$\phi^{i\pm 1/2} = \int_{\Delta_{i\pm 1/2} x} (\partial_x f + S)$$

$$\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \phi_{i}^{i-1/2} + \phi_{i}^{i+1/2} = 0$$





$$\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi^{i+1/2}$$

distribution/splitting

 $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$ 

#### Consistent fluxes





### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent fluxes

$$\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi^{i+1/2} := f_{i+1} - f_{i+1}$$
$$\hat{f}_{i+1/2} = f_{i} + \phi_{i}^{i+1/2} = f_{i+1} - \phi_{i+1}^{i+1/2}$$









### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent fluxes

Notion of consistency wrt constants







$$\Delta_{i} \mathbf{x} \frac{\mathbf{u}_{i}^{n+1} - \mathbf{u}_{i}^{n}}{\Delta t} + \hat{\mathbf{f}}_{i+1/2} - \hat{\mathbf{f}}_{i-1/2} =$$





#### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

Residual distribution/fluctuation splitting:

$$\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \phi_{i}^{i-1/2} + \phi_{i}^{i+1/2} = 0$$

 $\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi^{i+1/2}$ 





$$\phi^{i\pm 1/2} = \int_{\Delta_{i\pm 1/2} x} (\partial_x f + S)$$

#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

Residual distribution and global fluxes

$$S_{i\pm 1/2} := \frac{1}{\Delta_{i\pm 1/2} x} \int S(u(x));$$
  
$$\Delta_{i\pm 1/2} x$$





#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

Residual distribution and global fluxes

$$\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \phi_{i}^{i-1/2} + \phi_{i}^{i+1/2} = 0$$

 $\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi_{i+1}^{i+1$ 





$$b^{i+1/2} = \int_{\Delta_{i+1/2} \mathsf{x}} (\partial_{\mathsf{x}} \mathsf{f} + \mathsf{S}) = \Delta_{i+1/2} g = \int_{\Delta_{i+1/2} \mathsf{x}} \partial_{\mathsf{x}} g$$

### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

#### Consistent global fluxes





#### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

Consistent global fluxes

$$\phi_{i}^{i-1/2} + \phi_{i-1}^{i-1/2} = \phi^{i+1/2} := f_{i+1} - f_{i} + \Delta_{i-1}$$
$$= g_{i+1} - g_{i}$$
$$\hat{g}_{i+1/2} = g_{i} + \phi_{i}^{i+1/2} = g_{i+1} - \phi_{i+1}^{i+1/2}$$









### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

#### Consistent global fluxes

(surrogate) notion of consistency: consistency wrt constant global fluxes

no info on the structure of the solution (in the source quadrature, cf later)









### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

Consistent global fluxes: work fine

Delis and Katsaounis, IJNMF 2003 Chertock et al, J.Comput.Phys. 2018 Cheng et al, J.Sci.Comp. 2019

Roe, 1987

Castro, Pares and co. : Well-Balanced/path conservative Karni, Hernandez-Duenas, Balbas RD stuff in 1D: Abgrall, MR Inia

# $\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \phi_{i}^{i-1/2} + \phi_{i}^{i+1/2} = 0$

#### Residual distribution



### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

#### Consistent global fluxes

First order accurate !





### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

#### Consistent global fluxes + reconstruction

Delis and Katsaounis, IJNMF 2003 Chertock et al, J.Comput.Phys. 2018 Cheng et al, J.Sci.Comp. 2019

cf. talk by Alina





×1-1/2

x 1+1/2

### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = 0$

particular (un)steady states

#### $\partial_{x} f(u) + S(u; d) = 0$









#### particular (un)steady states





### $\mathcal{S}(\mathbf{u};\mathbf{d}) = \partial_{\mathbf{t}}\mathbf{u}$

propagating waves...

#### $\partial_{\mathbf{x}} \mathbf{f}(\mathbf{u}) + \mathcal{S}(\mathbf{u}; \mathbf{d}) = \mathbf{0}$



#### $\mathcal{S}(u) + \partial_{x} f(u) = 0$





$$\hat{g}_{i+1/2} - \hat{g}_{i-1/2} = 0$$

### $\mathcal{S}(u) + \partial_{\mathsf{x}}\mathsf{f}(\mathsf{u}) = \mathsf{0}$

#### Upwind (global) flux

$$\hat{g}_{i+1/2}^{u} = \frac{g_{i+1} + g_{i}}{2} - \frac{\operatorname{sign}(A)_{i+1/2}}{2}(g_{i+1} - g_{i})$$

 $g_{i+1} = f_{i+1} + s_{i+1} = f_{i+1} + s_i + \Delta_{i+1/2} x \mathcal{S}_{i+1/2}$ 





$$\hat{g}_{i+1/2} - \hat{g}_{i-1/2} = 0$$

### $\mathcal{S}(u) + \partial_{x} f(u) = 0$

#### Upwind (global) flux

$$\hat{g}_{i+1/2}^{u} = \frac{g_{i+1} + g_{i}}{2} - \frac{\operatorname{sign}(A)_{i+1/2}}{2}(g_{i+1} - g_{i})$$
$$g_{i+1} = f_{i+1} + s_{i+1} = f_{i+1} + (s_{i} + \Delta_{i+1/2} \times \mathcal{S}_{i+1/2})$$





$$\hat{g}_{i+1/2} - \hat{g}_{i-1/2} = 0$$

### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

#### Upwind (global) flux



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$$\hat{f}_{i+1/2}^{u} - \hat{f}_{i-1/2}^{u} = 0$$

$$\frac{\text{sign}(A)_{i+1/2}}{2}(f_{i+1} - f_i)$$

### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Upwind (global) flux







$$\Delta_{i} x \frac{d \widehat{u}_{i}^{u}}{dt} + \widehat{f}_{i+1/2}^{u} - \widehat{f}_{i-1/2}^{u} = 0$$

$$n(A)\frac{du}{dt}\bigg)\bigg\}_{i+1/2} - \bigg\{\frac{\Delta x}{2}\left(\frac{1}{2}\Delta\frac{du}{dt} + \text{sign}(A)\frac{du}{dt}\right)\bigg\}$$



### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

#### Upwind (global) flux



Formal order of accuracy  $\Delta x^2$  (e.g. by truncated Taylor series)





$$\hat{f}_{i+1/2}^{u} - \hat{f}_{i-1/2}^{u} = 0$$

### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent global fluxes: uFEM/SUPG $\int (\varphi_{i} + A \nabla \varphi_{i} \tau) \{\partial_{t} u + \partial_{x} f(u)\} = 0$ 




### $\partial_t u + \partial_x f(u) = 0$

Consistent global fluxes: uFEM/SUPG  $(\varphi_{i} + A \nabla \varphi_{i} \tau) \{\partial_{t} u + \partial_{x} f(u)\} = 0$ 





# $\phi_{i}^{i\pm 1/2} = \int_{\Delta_{i\pm 1/2} x} (\varphi_{i} + A \nabla \varphi_{i} \tau) \{\partial_{t} u + \partial_{x} f(u)\}$

### $\partial_t u + \partial_x f(u) = 0$

Consistent global fluxes: uFEM/SUPG  $(\varphi_{i} + A \nabla \varphi_{i} \tau) \{\partial_{t} u + \partial_{x} f(u)\} = 0$  $\checkmark \Delta_{i\pm 1/2} X$ 







#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent global fluxes: uFEM/SUPG

$$\hat{g}_{i+1/2} - \hat{g}_{i-1/2} = 0$$

 $\hat{g}_{i+1/2} = g_i + \phi_i^{i+1/2} = g_{i+1} - \phi_{i+1}^{i+1/2}$  $= \hat{f}_{i+1/2}^u + \hat{s}_{i+1/2}(\partial_t u)$ 





#### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent global fluxes: uFEM/SUPG









$$-\hat{f}_{i+1/2}^{u} - \hat{f}_{i-1/2}^{u} = 0$$

$$n(A)\frac{du}{dt}\bigg)\bigg\}_{i+1/2} - \bigg\{\frac{\Delta x}{2}\left(\frac{1}{3}\Delta\frac{du}{dt} + \operatorname{sign}(A)\frac{du}{dt}\right)\bigg\}$$



### $\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0$

Consistent global fluxes: uFEM/SUPG

 $\Delta_i x \frac{d \, \widehat{u}_i^{\text{uFEM}}}{dt}$ 

Formal order of accuracy  $\Delta x^3$  (e.g. by truncated Taylor series)





$$-\hat{f}_{i+1/2}^{u} - \hat{f}_{i-1/2}^{u} = 0$$

### $\partial_t u + \partial_x f(u) = 0$

Time stepping with mass matrix

 $\Delta_i x \frac{d\hat{u}_i}{dt} + \hat{f}_{i+1/2} -$ 

 $\Delta_{i} x \frac{d \hat{u}_{i}}{dt} = \sum_{i} m_{ij} \frac{d u_{j}}{dt}$ 





$$-\hat{f}_{i-1/2} = 0$$

42

### $\partial_t u + \partial_x f(u) = 0$

Time stepping with mass matrix: option 1 is go implicit

 $\Delta_{i} x \frac{d \hat{u}_{i}}{dt} + \hat{f}_{i+1/2} -$ 







$$-\hat{f}_{i-1/2} = C$$

$$\sum_{i>0} \alpha_i \Delta_i \hat{f}^{n+1-i} = 0, \quad \Delta_i \hat{f} := \hat{f}_{i+1/2} - \hat{f}_{i-1/2}$$

### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC\* (O2)







\*cf. talks by P Öffner and D. Torlo



### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

 $\Delta_{i} x \, \Delta^{*} u_{i} + \Delta t \, \Delta_{i} \hat{f}^{n} = 0$ 

 $\Delta^* u_i := u_i^* - u_i^n$  $\Delta_{i}\hat{f} := \hat{f}_{i+1/2} - \hat{f}_{i-1/2}$ 









Euler explicit



### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)







### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

 $\Delta_i x \, \Delta^* u_i + \Delta t \, \Delta_i \hat{f}^n = 0$ 







#### the time derivative is in here



### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

 $\Delta_i x \Delta^* u_i + \Delta t \Delta$ 







$$\Delta_{i}\hat{f}^{n}=0$$

this is what's in the code



extra correction

### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

 $\Delta_{i} x \Delta^{*} u_{i} + \Delta t$ 







$$\Delta_{i}\hat{f}^{n}=0$$

 $\Delta_{\mathbf{i}} \mathbf{x} \, \Delta^{\mathbf{n+1}} \mathbf{u}_{\mathbf{i}} + \int \Delta_{\mathbf{i}} \hat{\mathbf{f}} = \left\{ \Delta \mathbf{x}_{\mathbf{i}} \, \Delta^* \mathbf{u}_{\mathbf{i}} + \int \Delta_{\mathbf{i}} \hat{\mathbf{f}} \right\} - \int \Delta_{\mathbf{i}} \hat{\mathbf{g}}$ Higher than second order and ADER variants are possible (cf. talks by D. Torlo and P Öffner) 49



### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

Prototype (notation reminder mostly)

$$\Delta_{\rm i} \mathbf{x} \frac{\mathrm{d}\,\hat{\mathbf{u}}_{\rm i}}{\mathrm{d}\mathbf{t}} = -\,\Delta_{\rm i}\hat{g}$$





 $= -(\phi_{i}^{i+1/2} + \phi_{i}^{i-1/2})$ 

### $\partial_t u + \partial_x f(u) + S(u; d) = 0$

Prototype (notation reminder mostly)

$$\Delta_{\mathbf{i}} \mathbf{x} \frac{\mathrm{d} \,\widehat{\mathbf{u}}_{\mathbf{i}}}{\mathrm{d} \mathbf{t}} = \begin{bmatrix} -\Delta_{\mathbf{i}} \,\widehat{g} = -\left(\phi_{\mathbf{i}}^{\mathbf{i}+1/2} + \phi_{\mathbf{i}}^{\mathbf{i}-1/2}\right) \end{bmatrix}$$





#### the source term is in here

nodal global fluxes are never explicitly evaluated

$$\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \int_{\Delta_{i+1/2} x} (\partial_{x} f + \Delta_{i+1/2} x)$$







### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

$$\Delta_{\mathbf{i}} \mathbf{x} \, \Delta^{*} \mathbf{u}_{\mathbf{i}} = -\Delta \mathbf{t} \, \Delta_{\mathbf{i}} \hat{g}^{\mathbf{n}} = -(\phi_{\mathbf{i}}^{\mathbf{i}+1/2} + \phi_{\mathbf{i}}^{\mathbf{i}-1/2})^{\mathbf{n}}$$
  
$$\Delta_{\mathbf{i}} \mathbf{x} \, \Delta^{\mathbf{n}+1} \mathbf{u}_{\mathbf{i}} + \int_{\mathbf{t}^{\mathbf{n}}}^{\mathbf{t}^{\mathbf{n}+1}} \Delta_{\mathbf{i}} \hat{g} = \left\{ \Delta \mathbf{x}_{\mathbf{i}} \, \Delta^{*} \mathbf{u}_{\mathbf{i}} + \int_{\mathbf{t}^{\mathbf{n}}}^{\mathbf{t}^{\mathbf{n}+1}} \Delta_{\mathbf{i}} \hat{g} \right\} - \int_{\mathbf{t}^{\mathbf{n}}}^{\mathbf{t}^{\mathbf{n}+1}} \Delta_{\mathbf{i}} \hat{g}$$





### $\partial_t u + \partial_x f(u) = 0$

Fully explicit schemes: predictor-corrector/DeC (O2)

$$\Delta_{i} \mathbf{x} \, \Delta^{*} \mathbf{u}_{i} = \left[ -\Delta t \, \Delta_{i} \hat{g}^{n} = -\left(\phi_{i}^{i+1/2} + \phi_{i}^{i-1/2}\right)^{n} \right]^{\text{the source term is in}}$$
  
$$\mathbf{u}_{i} \mathbf{x} \, \Delta^{n+1} \mathbf{u}_{i} + \left[ \int \Delta_{i} \hat{g}_{i} - \left\{ \Delta \mathbf{x}_{i} \, \Delta^{*} \mathbf{u}_{i} + \left[ \int \Delta_{i} \hat{g}_{i} \right] \right]^{-1} \right]^{t^{n+1}} \left[ \int \Delta_{i} \hat{g}_{i} \right]$$

$$\Delta_{i} \mathbf{x} \, \Delta^{*} \mathbf{u}_{i} = \left[ -\Delta t \, \Delta_{i} \hat{g}^{n} = -\left(\phi_{i}^{i+1/2} + \phi_{i}^{i-1/2}\right)^{n} \right]^{\text{the source term is in}}$$
$$\Delta_{i} \mathbf{x} \, \Delta^{n+1} \mathbf{u}_{i} + \int_{t^{n}}^{t^{n+1}} \Delta_{i} \hat{g} = \left\{ \Delta \mathbf{x}_{i} \, \Delta^{*} \mathbf{u}_{i} + \int_{t^{n}}^{t^{n+1}} \Delta_{i} \hat{g} \right\} - \left[ \int_{t^{n}}^{t^{n+1}} \Delta_{i} \hat{\mathcal{G}} \right]$$





source term and time derivative are in here



# 1D examples using RD







#### $\partial_t u + \partial_x f(u) + S(u; d) = 0$



Standard discrete kinetic approach Jin and Xin Comm. Pure Appl. Math. 1995 D. Aregba-Driollet and R. Natalini, SINUM 2000



Perturbation to account for bathymetry and friction:  $P\tilde{s}^{\epsilon} = S(Pf^{\epsilon}; d)$ Delis and Katsaounis, IJNMF 2003 Delis and Katsaounis, Appl.Math.Mod. 2005





# etc.

$$\begin{aligned} f_{i}^{\epsilon,n+1} - f_{i}^{\epsilon,*} + \frac{\Delta t}{\epsilon} (f^{\epsilon,n+1} - \mathsf{M}^{n+1})_{i} + \frac{\Delta t}{\Delta_{i} \mathsf{x}} \sum_{\mathsf{C} \ni \mathsf{i}} \phi_{\mathsf{i}}(f^{\epsilon,*}, f^{\epsilon,n}) &= 0 \\ \text{IMEX part} \\ \text{BD + DeC} \end{aligned}$$



time derivative, sources, relaxation terms

#### Discretization by well balanced RD + IMEX DeC

- Abgrall and Torlo, SISC 2020
  - MR, J.Comput.Phys. 2015



Jointly with D. Torlo (CARDAMOM Inria Bordeaux Sud-Ouest, France)

Discretization by well balanced RD + IMEX DeC

Formal equivalence (CE expansion, within  $\epsilon$ ) with DK formulation of global flux PDE

$$\partial_{\mathbf{t}} \mathbf{u}^{\epsilon} + \partial_{\mathbf{x}} g(\mathbf{u}^{\epsilon}; \mathbf{d}) =$$

The remainder is non-vanishing in both formulations, and can be written as

$$\epsilon \partial_{\mathbf{x}} (\mathbf{B}^{\epsilon} \partial_{\mathbf{x}} \mathbf{u}^{\epsilon}) + \epsilon \partial_{\mathbf{x}} \Delta$$

Positive definite under a sub-char. condition

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 $= \mathcal{O}(\epsilon)$ 

Spatial/temporal derivatives of the source(flux)







Manufactured (Steady) smooth solution: kinetic var.s initialised using Maxwellians, and computation for finite times



(linear schemes)











Perturbation of the classical transcritical case (linear schemes)





#### Delestre et al, IJNMF 2013





Perturbation of the classical lake at rest case (linear schemes)





Delestre et al, IJNMF 2013







#### (linear schemes)

66



Perturbation of the constant slope equilibrium :  $gh \nabla b = -c_f(h, ||\vec{u}||)\vec{u}$ 





#### (linear schemes)





 $\partial_t h + \partial_x (hu) = 0$  $\partial_t(hu) + \partial_x(hu^2 + gh^2/2) + gh\partial_x b = \mathcal{D}$  $\mathscr{D} = \mathsf{Bd}^2 \partial_{\mathsf{xxt}}(\mathsf{hu}) + \frac{\mathsf{d}\partial_{\mathsf{x}}\mathsf{d}}{\mathsf{z}} \partial_{\mathsf{xt}}(\mathsf{hu}) + \beta \mathsf{g}\mathsf{d}^3 \partial_{\mathsf{xxx}}\eta - 2\beta \mathsf{g}\mathsf{d}^2 \partial_{\mathsf{x}}\mathsf{d}\partial_{\mathsf{xx}}\eta$ 



depth at rest free surface  $d = h_0 - b , \ \eta = h + b$ 



 $\partial_t h + \partial_x (hu) = 0$ 

 $\partial_t(hu) + \partial_x(hu^2 + gh^2/2) + gh\partial_x b = \mathcal{D}$ 



conservative flux, topography, dispersion

$$\sum_{j} m_{ij} \frac{U_{j}^{n+1} - U_{j}^{n}}{\Delta t} + \sum_{l \ge 0} \alpha_{l} \sum_{C \ni i} \phi_{i}(U^{n+1-l})$$

**Discretization** by well balanced RD + implicit time stepping

- MR and A. Filippini, J.Comput.Phys. 2014
  - R. Abgrall and MR, ECM 2017







# Solitary waves

Solitary waves travelling (on flat bathymetry) at speed C solution of the ODE

$$C^{2}h_{0}^{2}(B - \beta \frac{C_{0}^{2}}{C^{2}})\eta'' + C^{2}(\frac{C_{0}^{2}}{C^{2}} - 1)\eta + \frac{g}{2}\eta^{2} + C\frac{\eta}{\eta + h_{0}} = 0$$

with  $(h, hu) = (\eta - b, C\eta)$  and  $C_0^2 = gh_0$ 





Figure 5: Soliton profile for  $h_0 = 1 [m]$  and  $A/h_0 = 0.2$  obtained by numerically integrating (34)





# Solitary wave shoaling and fission





$$\partial_t h + \partial_x (hu) = 0$$
  
 $\partial_t (hu) + \partial_x (hu^2 + gh^2/2) + gh \partial_x b = 2$ 

no WB:

Well Balanced:  $\phi_i = \beta_i \ (\partial_x f - \mathcal{D})$  $\phi_{\rm i} = \beta_{\rm i} \left[ \partial_{\rm x} f - \int \varphi_{\rm i} \mathcal{D} \right]$ 


#### Solitary wave shoaling and fission





short time



#### Solitary wave shoaling and fission





long(er) time



#### Solitary wave shoaling and fission



#### (hyperbolic) balance laws: 1d summary

Error balance and residual distribution/fluctuation splitting

- **o** conservation laws —> equivalence with FV and consistent fluxes
- o balance laws —> equivalence with FV and consistent global fluxes
- o global flux and unsteady: mass matrix and error balance
- Time stepping: implicit or explicit predictor/corrector aka Defect Correction



O variety of source terms and so far no a-priori knowledge on the ex. sol !

#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$

Consistent global fluxes

Dimension by dimension extension: 1D consistency along on mesh aligned directions or more ?

Nice results in e.g. (Chertock et al, JCP 2018)



 $\partial_t \mathbf{u} + \partial_{\mathbf{x}} g(\mathbf{u}; \mathbf{x}) = 0$  $g(\mathbf{u};\mathbf{x}) = f(\mathbf{u}) + s(\mathbf{u};\mathbf{x})$  $s(\mathbf{u}; \mathbf{x}) = \int_{\mathbf{x}_0} S(\mathbf{u}(\mathbf{s}); \mathbf{d}(\mathbf{s}))$ 



#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = \mathbf{0}$

Consistent global fluxes

- $\partial_t \mathbf{u} + \nabla \cdot G(\mathbf{u}; \mathbf{x}) = 0$
- $G(\mathbf{u};\mathbf{x}) = f(\mathbf{u}) + \sigma(\mathbf{u};\mathbf{x})$

 $\nabla \cdot \sigma = \mathsf{S}$ 



Solenoidal involution !

#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u}; \mathbf{d}) = \mathbf{0}$

Consistent global fluxes

- $\partial_t \mathbf{u} + \nabla \cdot G(\mathbf{u}; \mathbf{x}) = \mathbf{0}$
- $G(\mathbf{u};\mathbf{x}) = f(\mathbf{u}) + \sigma(\mathbf{u};\mathbf{x})$

 $\nabla \cdot \sigma = \mathsf{S}$ 



Solenoidal involution !

- staggered methods
- vector decomposition & potentials

Hyman and Shashkov, CAMWA 1997 Mishra and Tadmor, CCP 2011 and SINUM 2011



Back to 1d to change paradigm



$$\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi^{i+1/2} = \int_{\Delta_{i+1/2} x} (\partial_{x} f + S)$$





$$\hat{g}_{i+1/2} = g_i + \phi_i^{i+1/2} = g_{i+1} - \phi_{i+1}^{i+1/2}$$

$$g_i := f_i + s_i$$

focus on this

$$s_i := s_{i-1} + \Delta_{i-1/2} \times S_{i-1}$$





Back to 1d to change paradigm

 $s_{i} := s_{i-1} + \Delta x S_{i-1/2}$ 

$$\frac{s_{i} - s_{i-1}}{\Delta x} = S_{i-1/2} \approx \partial_{x} s_{i-1/2} = S_{i-1/2}$$

$$\psi_{i+1/2} := \psi_{i-1/2} - \Delta x s_i$$



$$_{2} \approx \int_{x_{i-1}}^{x_{i}} \partial_{\mathbf{x}} s(\mathbf{x}) = \int_{\mathbf{x}_{i-1}}^{\mathbf{x}_{i}} \mathbf{S}$$

cell potential for the source flux  $\frac{\psi_{i+1/2} - 2\psi_{i-1/2} + \psi_{i-3/2}}{2} = S_{i-1/2} \approx -\partial_{xx}\psi_{i-1/2} = S_{i-1/2}$  $\Delta x^2$ 



Back to 1d to change paradigm

$$\Delta_{i} x \frac{u_{i}^{n+1} - u_{i}^{n}}{\Delta t} + \phi_{i}^{i-1/2} + \phi_{i}^{i+1/2} = 0$$

$$\phi_{i}^{i+1/2} + \phi_{i+1}^{i+1/2} = \phi^{i+1/2} = \int_{\Delta_{i+1/2} x} (\partial_{x}f + S)$$

used in practice







 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ 

Residual distribution and global fluxes : Cartesian grids

$$|C_{i,j}| \frac{du_{i,j}}{dt} + \sum_{C \ni i,j} \phi_{i,j}^{C} = 0$$
$$\sum_{i,j \in C} \phi_{i,j}^{C} = \phi^{C} = 0$$





$$\int_{C} (\nabla \cdot F + S)$$
  
For example  $\phi_{i,j}^{C} = \beta_{i,j} \phi^{C}$ 



#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = 0$

Residual distribution and global fluxes : Cartesian grids

Retrace the steps taken in 1D

- STEP 1: write equivalent consistent fluxes for RD in homogeneous case
- STEP 2: what is the source integral equal to in 2D?



#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) = 0$

Residual distribution and global fluxes : Cartesian grids

STEP 1: write equivalent consistent fluxes for RD in homogeneous case (R. Abgrall and MR, ECM 2017, Abgrall CMAM 2018)



and 
$$\sum_{ij} (\hat{F}_{n_{v_{ij}}} - F_{ij} \cdot \hat{n}_{v_{ij}})$$
  
its  
stem for  $\hat{F}_{n_{v_{ij}}}$   
 $|C_{i,j}| \frac{du_{i,j}}{dt} + \sum_{j=1}^{n_{v_{ij}}} dt$ 

C∋i,j v<sub>ij</sub>



C





Consistent fluxes : Cartesian grids







#### $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) = 0$

Residual distribution and global fluxes : Cartesian grids

STEP 1: write equivalent consistent fluxes for RD in homogeneous case (R. Abgrall and MR, ECM 2017, Abgrall CMAM 2018)

$$C_{i,j} \left| \frac{du_{i,j}}{dt} \right| = -\sum_{\substack{C \ni i,j}} \phi_{i,j} = -\sum_{\substack{C \ni i,j}} \phi_{i,j}$$







 $= F \cdot n_{v_{ii}}$  for u <u>constant over the cell (multiD</u>)

Notion of consistency wrt constants



 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ 

Residual distribution and global fluxes : Cartesian grids

STEP 2: what is the source integral equal to in 2D?

$$|C_{i,j}| \frac{du_{i,j}}{dt} + \sum_{C \ni i,j} \phi_{i,j}^{C} = 0$$
$$\sum_{i,j \in C} \phi_{i,j}^{C} = \phi^{C} = \int_{C} (\nabla \cdot F + S)$$



 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ 

Residual distribution and global fluxes : Cartesian grids

STEP 2: what is the source integral equal to in 2D?

$$\int_{C_{i+1/2, j+1/2}} \nabla \cdot \mathbf{F} = \Delta \mathbf{y}(\mathbf{f}_{i+1, j+1/2} \cdot \mathbf{F}_{i+1/2, j+1/2})$$

**J**C<sub>i+1/2, j+1/2</sub>





 $-f_{i,i+1/2}$ ) +  $\Delta x(h_{i+1/2,i+1} - h_{i+1/2,i})$ 





 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ 

Residual distribution and global fluxes : Cartesian grids STEP 2: what is the source integral equal to in 2D? Define for example the edge fluxes  $\sigma_{i+1,j+1/2}^{x} = \sigma_{i,j+1/2}^{x} + \frac{|C_{i+1/2,j+1/2}|}{2\Delta v} S_{i+1/2,j+1/2}$ lo get **J**C<sub>i+1/2, j+1/2</sub> Inia







#### Closing(1). Going multiD i + 1, j + 1 i + 1, j + 1 i + 1/2, j + 1/2i, j <del>+</del> 1 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ i + 1, j **I**, **J** Residual distribution and global fluxes : Cartesian grids $\frac{1}{1} + \frac{1}{2}$

STEP 2: what is the source integral equal to in 2D? As before we can set

 $-\Delta x \,\sigma_{i,\,j+1/2}^{x} = \psi_{i+1/2,\,i+1/2} - \psi_{i-1/2,\,i+1/2}$ 

To show

Inia

 $\Delta x^2$ 

 $-\Delta y \,\sigma_{i+1/2,\,i}^{y} = \psi_{i+1/2,\,j+1/2} - \psi_{i+1/2,\,j-1/2}$ 

 $\psi_{i+3/2, j+1/2} - 2\psi_{i+1/2, j+1/2} + \psi_{i-1/2, j+1/2} = \psi_{i+1/2, j+3/2} - 2\psi_{i+1/2, j+1/2} + \psi_{i+1/2, j-1/2}$ = S $\Delta y^2$ 







#### Closing(1). Going multiD i, j + 1 i + 1, j + 1 $\partial_t \mathbf{u} + \nabla \cdot \mathbf{F}(\mathbf{u}) + \mathbf{S}(\mathbf{u};\mathbf{d}) = \mathbf{0}$ $\land \dots \rightarrow i + 1/2, i + 1/2$ + 1, j 1, ] Residual distribution and global fluxes : Cartesian grids ··•> + 1/2 i STEP 2: what is the source integral equal to in 2D?

There are many different possibilities

- Edge fluxes (using cell source values) cell potentials
- unstaggered with nodal fluxes and potentials
- etc

These can be all embedded in the residual distribution formalism



# • Cell flux values (using edge averaged source values) - edge potentials





**Residual Distribution** 

$$\phi^{i+1/2} = \int (\partial_{x}f + S) = \Delta f + \int S_{\Delta_{i+1/2}x}$$

$$f_{i} = f(u_{i}) = f(v(u_{i}; d_{i}))$$

$$f_{i+1} = f(u_{i+1}) = f(v(u_{i+1}))$$

$$i \quad i+1$$

$$\forall v = v(u; d)$$

Global Flux

 $g_i := f_i + \int S$  $\Delta_{i+1/2} x$ 

S(u; d), u and d linear

 $(1; d_{i+1}))$ 

S(v(u; d); d), v and d linear i + 1

there are  $N \gg 1$  possibilities















#### S(u; d), u and d linear





there are  $N \gg 1$  possibilities



Stab<sub>i+1/2</sub> = 
$$\alpha_{i+1/2} = \alpha_{i+1/2} \begin{pmatrix} \Delta_{i+1/2} u \\ (v_u)_{i+1/2}^{-1} \Delta_{i+1/2} v \\ (g_u)_{i+1/2}^{-1} \Delta_{i+1/2} g \\ etc \end{pmatrix}$$

 $\Delta_{i+1/2} \mathbf{x}$ 

$$g_i := f_i +$$

$$g_i := f_i + \Delta$$

S

#### Closing(2). Final boss: subgrid structure Perturbation of the constant slope eq.: $gh \nabla b = -c_f(h, ||\vec{u}||)\vec{u}$



Figure 5.12: Super-critical flow in slopping channel with friction at different times for a Manning ficient of 0, 5 with the IMEX RK RD scheme. coefficient of 0,02 with the IMEX RK RD scheme.



Figure 5.13: Flow in slopping channel with friction with a perturbation at different times for a Manning coefficient of 0, 2 with the Strang splitting RD scheme.



Perturbation of the classical subcritical case





Delestre et al, IJNMF 2013





Perturbation of the classical subcritical case







97

Perturbation of the classical subcritical case







98

#### Final summary

Error balance and residual distribution/fluctuation splitting

- o balance laws —> equivalence with FV and consistent global fluxes
- O unsteady: global flux and mass matrix, time stepping issues
- O variety of source terms and so far no a-priori knowledge on the ex. sol !
- O going multiD : global flux and solenoidal involutions —> more on potentials ?
- O sub-grid structure:
  - invariants
  - residual based/global flux for improved consistency (not always exactly WB) residual/global flux based stabilization to preserve consistency initial work by Castro and Pares to "guess" the sub-grid structure (inverse pb)

  - more to come for sure ...



