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Verification of CCSL Specifications

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Objective

- Exhaustive Verification with CCSL
  - Observer-based (LCTES'09, SIES'10)
    - Verify that a property specified in CCSL holds for a given implementation
  - **ICECCS'11**
    - Verify that a property specified in LTL holds for a given CCSL specification => SPIN
    - Means: Transformation into Promela
      - Pro: Promela supports non-deterministic choice
      - Pro: Promela is used in TrustableMDA
      - Con: Promela is asynchronous, does not natively support simultaneity

CCSL -> Promela

- Get some inspiration from the operational semantics of CCSL
  - CCSL clocks: encoded as shared boolean variables
  - A *run* :
    - a sequence of coincident instants
    - valid evolution conforming to the specification
    - Promela must explore ALL the valid runs
  - A *coincident instant*
    - consists of several valid configurations
    - each configuration is a set of ticking decisions, {a,¬b}
    - which configuration is chosen is non-deterministic
  - A *step* :
    - Decide what clocks **MUST** or **CANNOT** fire (enabled)
    - Choose what clocks **ACTUALLY** fire (firing)
      - Non-deterministic choice
      - Conflicts

```
typedef Clock { bool must_tick, cannot_tick, actually_tick, dead };
```

CCSL -> Promela

- Global clock declaration

```
typedef Clock { bool must_tick, cannot_tick, actually_tick, dead };
```

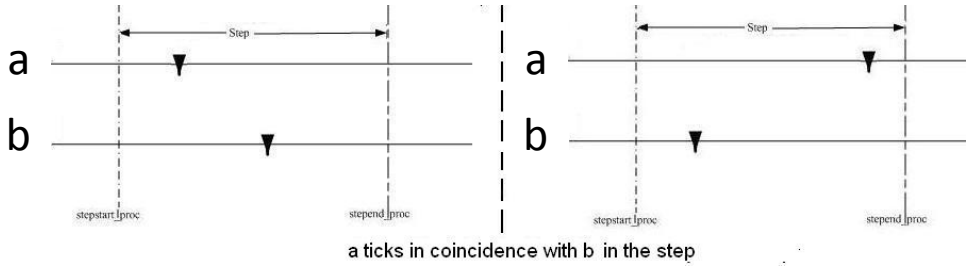
- Operator process instantiations + init process
- A *coincident instant*

Start: compute ticking decisions(must,cannot)

Firing: chose what clocks actually fire, non-determinsitic

End: update+reset

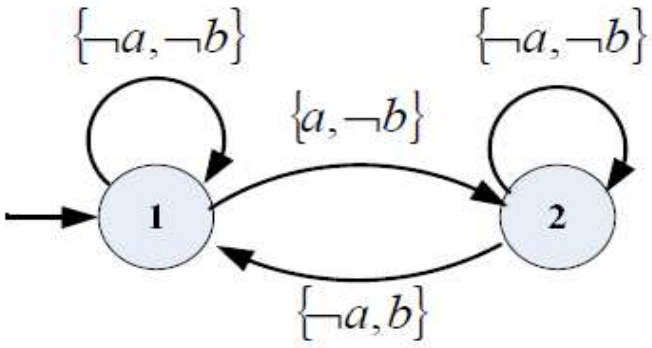
Order:

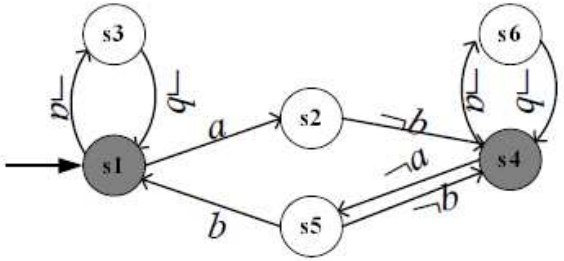


a ≃ b

Example

- T={S,A,->,I,clp}, each transition is labeled by a set of actions, representing clock decisions in the coincident instant;clp indicates checkpoints






```
proctype alternatesWith(int cLeft; cRight) {
    bool state = true;
    do
    :: start_proc?true;
       if
       :: state -> clocks[cRight].cannot_tick = true ;
       :: ! state -> clocks[cLeft]:cannot tick = true ;
       fi;
       end_proc?true;
```

Enabling

Global non-deterministic choice

```
       if
       :: state -> if :: clocks[cLeft].actually_tick -> state = false
                      :: else -> skip     fi
       :: !state -> if :: clocks[cRight].actually_tick -> state = true
                      :: else -> skip     fi
       fi
    od
}
```

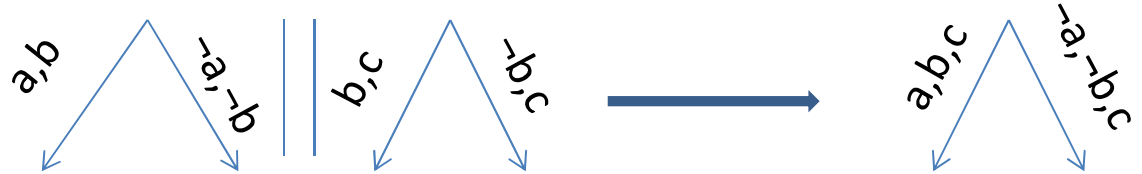
State Update

Composition

$$T_1 = \{S_1, \mathcal{A}_1, \Rightarrow_1, I_1, C_1\} \qquad T_2 = \{S_2, \mathcal{A}_2, \Rightarrow_2, I_2, C_2\}$$

$$T_1 || T_2 = \{S_1 \times S_2, \mathcal{A}_1 \cup \mathcal{A}_2, \Rightarrow, I_1 \times I_2\}$$

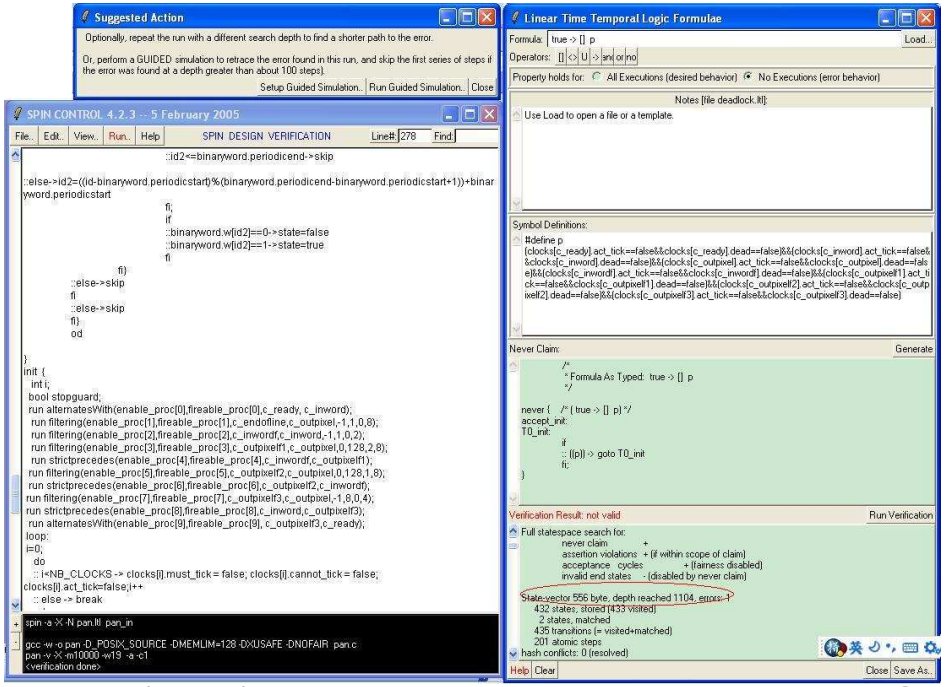
$$\frac{s_1 \overset{\mu_1}{\Longrightarrow} s_1' \in T_1, s_2 \overset{\mu_2}{\Longrightarrow} s_2' \in T_2, \ \forall a \in \mathcal{A}_1 \cup \mathcal{A}_2, \ a \in \mu_1 \wedge \neg a \notin \mu_2}{(s_1, s_2) \overset{\mu_1 \cup \mu_2}{\Longrightarrow} (s_1', s_2')}$$

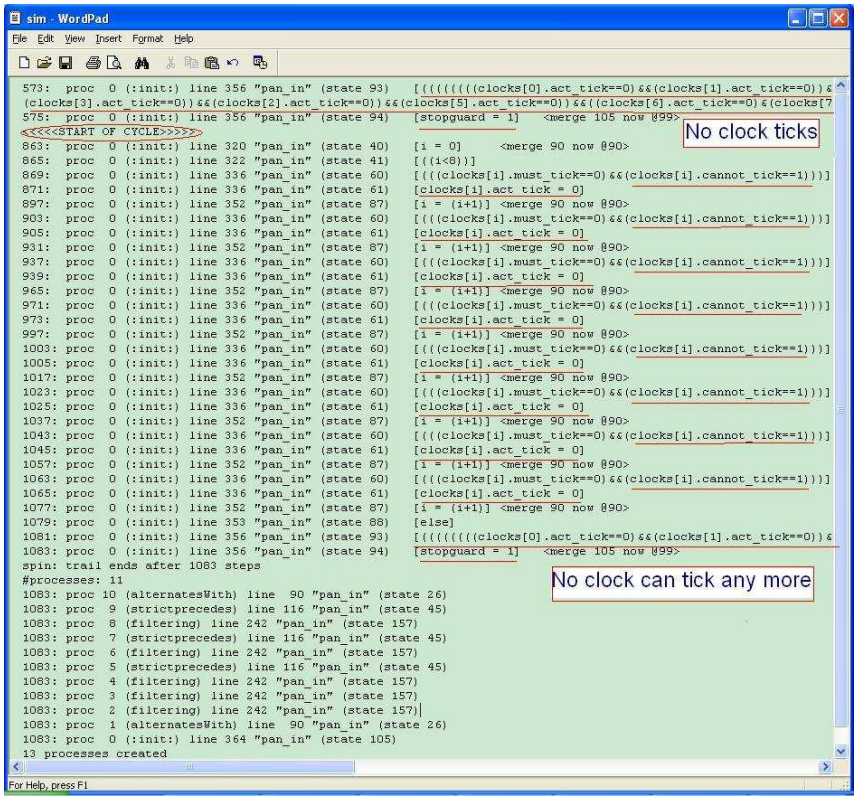


Verifying LTL properties on CCSL

$$\varphi ::= true | inst \wedge \psi | \mathbf{X}\varphi | \mathbf{F}\varphi | \mathbf{G}\varphi | \varphi_1 \mathbf{U} \varphi_2$$
$$\psi ::= c.act\_tick | \neg\psi | \psi_1 \wedge \psi_2$$

- Special variable `inst’ guaranteeing properties are checked each `coincident instant’

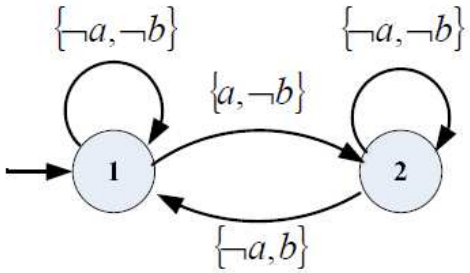


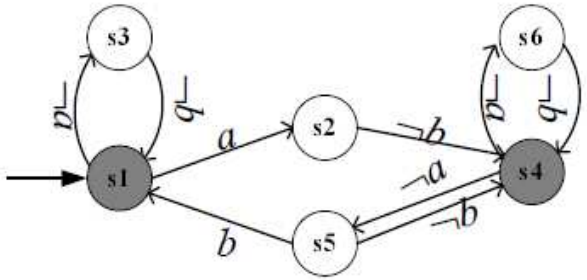


Encoding correctness

LTL property pattern

+ coincident encoding





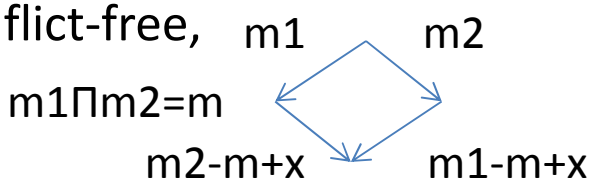
Checkpoint bisimulation equivalent

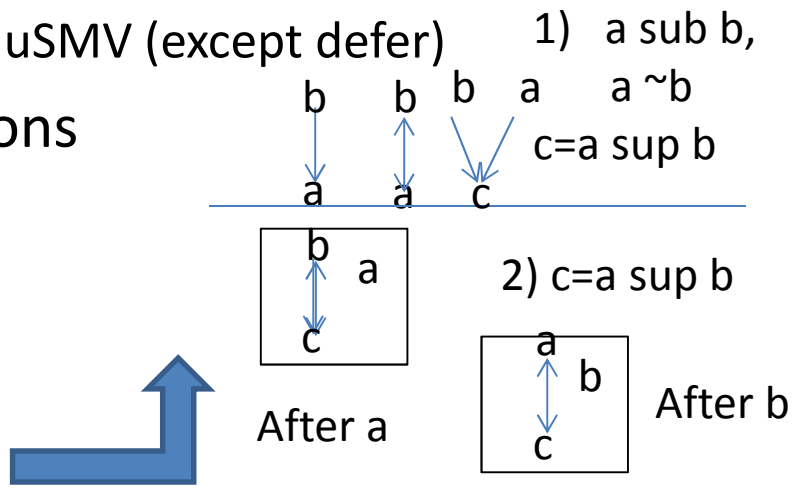
- Checkpoint bisimulation checks from checkpoint to checkpoint, requiring compared systems have executed the same set of visible actions. Orders of the actions are irrelevant
- It preserves logical truth under the pattern
- It is a congruence w.r.t parallel composition

Discussion

- Synchronous Transition System
  - easier with synchronous models, NuSMV (except defer)
- Choices among valid configurations

  Unpredictable random -> predictable
  - Conflict-free,





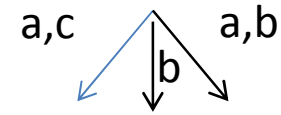
Condition: for all states, each pair of transitions, (m1-m,m2-m) independent

Independent: 1)Not connected, don't affect common clocks (too strong, e.g. prevent c=a sup b) → 2) build dependent relations for each state, only one instant (still strong, prevent c=a union b, may cause problem on strictSampling)

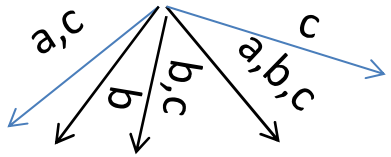
  - Otherwise,
    - Some clocks tick in some paths, while can not tick in others (deadlock or not)
    - If then else case

Non Conflict-free examples

c=a preemption b



- Single operator: sampling, preemption
- Conflict caused by non conflict-free operators no c anymore
  - a sub c, d=c filterby(01)^w, d=f preemption b



b blocks d->c->a

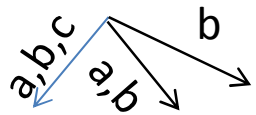
ac,b involved in disjoint operators.

(b in operator o3, while a and c involved in operator o1 and o2.
)

Non Conflict-free examples

- Composition of conflict-free operators:
  - 1) Choosing one path blocks unchosen clocks

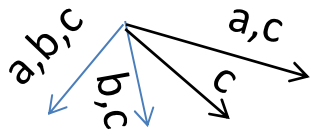
b= a wait 1, c sub b



no c anymore

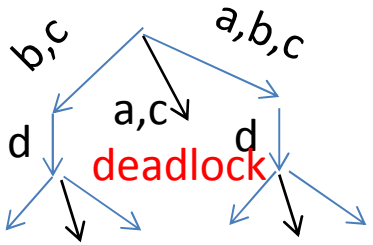
d=c filterby $(01)^w$,

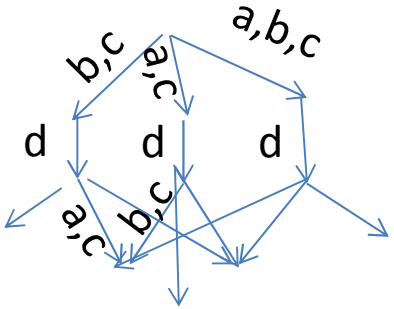
a sub c, b sub c, b<d



block d-> c->a,b

c=a union b, c ~ d, b <d



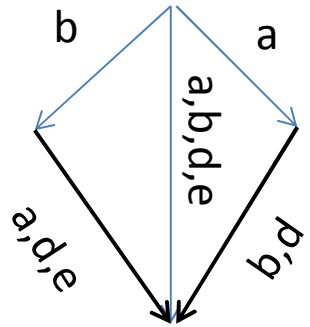


But removing d<d (lower one) yields conflict-free, even it does not satisfy the definition used above. Right now, ignore this case in the definition.

Non Conflict-free examples

- 2)Choosing one path doesn't block unchosen clocks, but forcing different new clocks

  d=a sup b, e=a intersection d



- If then else case:

  a sub m, b sub n

  c=a union b, b<d, a<d, c ~d, a#b

Looking for condition for conflict-free

- Not composition preserving
  - Composition of self conflict-free operators may introduce conflict
  - Restrict conflict operators may end as non conflict-free specification
    - c=a strictSampling b, a~b